REMARKS

A Substitute Specification and Abstract is submitted herewith to place the case in better English form. The Substitute Specification and Abstract contains no new matter. In order that the examiner can satisfy himself in this regard, also submitted herewith is a marked-up copy of the original Specification and Abstract from which the Substitute Specification and Abstract was typed.

Respectfully submitte

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DESCRIPTION

AUTOMATIC TRANSMISSION

(ROSS-REFENCE TO RELATED APPLICATION)

The present application has been filed under 35 USC 371 as a national phase of International Application No.

Application No.

Technical Field

The teachings of which are incorporated by reference in its entirety, inclusive of

The present invention relates to an automatic transmission incorporated in a vehicle, and more specifically, it relates to the placement construction of an automatic transmission that can shift multiple speeds by with the capability of input of reduced rotation to one of the rotation components of a planetary gear unit.

Background Art

Generally, there is known an automatic transmission

incorporated in a vehicle or the like which comprises a

planetary gear unit with two rows of linked planetary gears,

and planetary gear that can output the reduced rotation

wherein the rotation speed of the input shaft, is reduced

for example, see Japanese Unexamined Patent application

Publication No. 4-125345 and Japanese Unexamined Patent

application Publication No. 2000-274498. These achiever

for example, six forward speed levels and one reverse speed

level by being capable of input of reduced rotation from

the planetary gear via a clutch, to reduced rotation from

rotation-components.

The recent years, multi-staging of automatic transmissions has been desired from the perspective of improved fuel efficiency, due to environmental problems and so forth. However, in general, multi-staging results in a larger automatic transmission due to the increased number of patts, but from the perspective of ability to mount on a vehicle, a compact automatic transmission is desired.

The above-described automatic transmission comprises

two clutches for inputting the rotation of the input shaft

a rotary

into the rotation component of the planetary gear unit, and

in the speed of

rotation component of the planetary gear units however, in where the event that the two clutches or an oil pressure servo that controls the engaging of the clutches is configured between the planetary gear unit and the planetary gear, the unit for transmitting the reduced rotation of the planetary gear unit must be gear to the rotation component of the planetary gear unit must be axially becomes elongated in the axial direction.

means that the member transmitting a large torque is clongated, and providing an elongated member that can such large torque requires providing a relatively thick material that is elongated, which prevents providing a compact automatic transmission. Further, the weight of such a unit would be heavier, and not only would a lightweight

inertia) would increase, decreasing the controllability of is decreased the automatic transmission and the shock of speed change shocks would occur more easily.

Further, for example, in order to engage or disengage france.

The reduced rotation output to the planetary gear unit from the planetary gear, a clutch or brake must be provided. In the case that a clutch is provided, this clutch and the above described two clutches, in other words three clutches, are necessary. In general, a clutch has a drum-shaped member aclutch drum that transmits the input rotation to the friction plates, and therefore, with a problem such as relative rotation for example, supply of oil pressure to the oil chamber of the oil pressure servo of the clutch must be made from the mid-section of the automatic transmission.

The shape-mentioned located to the configured on one

side in the axial direction of the planetary gear unit for example, oil lines for supplying oil pressure to three oil must be provided pressure servos are constructed in triplicate in the midsection of the automatic transmission for example, and the configuration of the oil lines become complicated.

Accordingly, the object of the present invention is to provide an automatic transmission that achieves multistaging, and realizes reduction in size by placement configuration.

Further, another object of the present invention is to speed provide an automatic transmission wherein reduced rotation output means and a first clutch are configured on one side in the axial direction of the planetary gear unit, and the second clutch is configured on the other side in the axial direction of the planetary gear unit, so as to provide solutions to the above-mentioned problems.

Invention. provides Accordingly The present invention according to Glatm 1 is an automatic transmission comprising: an input shaft that output from rotates based on output rotation of a drive source; a planetary gear unit comprised of first, second, third, and fourth rotation components: reduced rotation output means for reducing the speed of the input rotation from the input shall and for a The reduced speed capable of outputting a reduced rotation to the first rotation component from the input shaft wherein selectively connects
-speed is reduced; a first clutch that links the input shaft and the second rotation component, in a manner capable of disengaging; a second clutch that links the input shaft and the third rotation component in a manner capable of disengaging; and an output unit that outputs the rotation of the fourth rotation component to a drive wheel transmission mechanisms wherein t he reduced rotation output means and the

first clutch are configured on one side on the axial

direction of the planetary gear unity and wherein the second

clutch is configured on the other side in the axial direction of the planetary gear unit.

Accordingly, the reduced rotation output means and planetary gear unit can be disposed closer to each other in comparison with a case wherein the first clutch and second clutch, for example, are configured between the reduced speed rotation output means and the planetary gear unit, while providing enabling realizing at least five speed levels forward and transmitting the reduced rotation can be made relatively short, thereby enabling forming the automatic transmission to be made the planetary gear unit, while providing the reduced rotation can be made relatively short, thereby enabling forming the automatic transmission to be made there in a compact manner.

Further, because the kinking member for transmitting the reduced rotation can be made relatively short, this can initerial be more lightweight, and further, because the inertia (force of inertia) can be smaller, the controllability of the automatic transmission can be improved, and the occurrence of speed change shock can be reduced.

rotation output means has a clutch, three clutches are nall are required configured, but compared to the case wherein the three clutches are enfigured on one side of the planetary gear unit, the construction of the oil lines supplying the pressure servos of those clutches is easier, and the manufacturing process can be simplified and the costs 13

reduced. zutomatic transmission of the

The present invention according to Claim 2 is

may

configured further comprising a linking member for linking

speed

the reduced rotation output means and the planetary gear

located radially inward

unit, wherein the first clutch is configured on the inner

transmilling

circumference side of the linking member.

configured with the reduced rotation output means further include rotation component for input singular rotation of the input shaft at all times, a fixed element

component for fixing rotations at all times, a speed speed y element reduction planetary gear that has a reduced rotation

component that rotates at the reduced rotation, and a third for controlling connection, through the clutch that can link the linking member between the reduced speed rotation component and the first rotation component in a speed manner capable of disongaging, wherein the reduced rotation consagement of is transmitted to the first rotation component by the third clutch engaging. Transmission of the may have

The present invention according to Claim 4 has the located radially inward first clutch configured on the inner circumference side of the third clutch.

relatively large torque to transmit the reduced rotation,

/ocated

can be configured on the outer circumference side, and this
third clutch and the oil pressure servo thereof can have a

A See 1

larger diameter. Particularly, the pressure area of the oil chamber of the oil pressure servo can be increased, and the capacity for torque transmission of this third clutch can be increased. However, by configuring the first clutch, which can have a small capacity for torque transmission compared to the third clutch, on the inner circumference side, the automatic transmission can be formed more compact.

The present invention according to Claim 5 is configured with the third clutch comprising a friction member, and a drum unit and a hub unit that link with the friction members wherein; the hub unit links with the reduced rotation component, the drum unit forms an oil pressure servo with a piston sealed in an oil-tight manner, and links with the first rotation components and the first located radially inward clutch is configured on the inner circumference side of the unit drum member.

configured with the friction member of the third clutch are present by radially outward located on the outer circumference side of the speed reduction planetary gears wherein an oil pressure servo of the third clutch is disposed adjoining the speed reduction planetary gear on the opposite side of the planetary gear unit in the axial direction.

The present invention according to Claim 7 is

The hydraulic

configured with an oil pressure servo of a first brake for

unit to which reduced rotation is input configured on the radially offward outer carsumference of the eil pressure servo of the third clutch.

configured with the reduced rotation output means further include comprising an input rotation component capable of inputting rotations of the input shaft, a fixing component for fixing rotations at all times, a speed reduction planetary gear unit that has a reduced rotation component that links to the first rotation component at all times, and rotates at the reduced rotation, and a third clutch that can link the linking member between the input shaft and the input rotation component in a manner capable of disengaging; wherein the reduced rotation is transmitted to the first retation component by the third clutch engaging

The present invention according to Claim 9 is

The intermediate element

configured with a fixing component of the speed reduction

planetary gear of fixed and configured on a first boss unit

extending from one edge of a side wall of a case; an ori

pressure servo of the third clutch is configured on the

Likewise, the hydraulic

outside of the first boss unit; an oil pressure servo of the

second clutch is configured on the outside of the second

boss unit that extends from another edge of a side wall of

located

the cases the first clutch is configured adjoined to the

repests

planetary gear and also comprises a friction member and an a hydraulic engaging cilipressure servo for pressurizing the friction member, and a drum unit and hub unit configured integrally with the cilipressure servo; and the drum unit is linked with the input shaft.

The present invention according to claim 10 is

In one embodiment, includes

configured with the reduced rotation output means further

comprising an input rotation component for inputting

rotations of the input shaft, a fixing component for fixing

rotations, a speed reduction planetary gear that has a

reduced rotation component that links to the first rotation

component at all times; and rotates at the reduced rotation,

for selectively connecting, through the transmitter

a third clutch that can link the linking member, between the

capable of disengaging, and a third brake capable of fixing the fixable element against the rotations of the fixing component, wherein the reduced speed rotation is transmitted to the first rotation component by engagement of the third clutch and the third brake, engaging.

input shaft and the input rotation component in a manner

The present invention according to Claim 11 is

configured further comprising: a linking member for linking

the reduced rotation output means and the planetary gear

may be radially inward

unit; wherein the third clutch is disposed on the inner

circumference side of the linking member.

With the present invention according to Claim 12, the may be located axially first clutch and the third clutch are configured adjacent in

the axial direction, on the inner circumference side of the transmiller linking member.

The present invention according to Claim 13 is

configured with the third clutch comprising a friction

member and an oil pressure servo for pressurizing the

hydraulic

friction member; wherein the oil pressure servo is

located

configured on the opposite side in the axial direction of

the speed reduction planetary gear as to the friction

unit axially opposite the first planetary gear

the speed reduction planetary gear as to the friction

un

forms the

member; and wherein a drum unit that configures a cylinder

of the oil pressure servo is linked with the input shaft.

With the present invention according to Claim 14, the hydraulic oil pressure servo of the third clutch is configured adjoining the oil pressure servo of the first clutch, between the oil pressure servo of the first clutch and the friction material of the third clutch.

The present invention according to Claim 15 is

configured further comprising: a linking member for linking

the reduced rotation output means and the planetary gear

unit; wherein the third brake is configured on the opposite

side in the axial direction of the planetary gear unit as to

the speed reduced planetary gear.

The present invention according to Claim 16 is

hydravlic

configured with the oil pressure servo of the third brake

may be formed the case.

The present invention according to Claim 17 is

configured with the third clutch comprising a friction member and an oil pressure servo for pressurizing the friction member; wherein the oil pressure serve is configured on the opposite side in the axial direction of the speed reduction planetary gear as to the friction member; and wherein a drum unit that configures a cylinder of the oil pressure servo, is linked

The present invention according to Glaim 18 is the reduced rotation output means forther en component for Vinput Lag_ ing an input rota₩ a Sixable element for being fixed of rotations of the input shaft, a fixing component for fixing speed reduction planetary a reduced rotation component that rotates at the reduced speed which

rotation and that is connected to the first rotating

component at all times, and a third brake capable of fixing the fixable element aszinst the rotation of the fixing component; wherein the reduced speed

rotation is transmitted to the first rotation component by emagen en of the third brake, engaging.

With the present invention according to Claim 197 the third brake is configured on the opposite side in the axhal direction of the planetary gear unit as to the speed reduction planetary gear;

wherein the oil pressure servo of the third brake is provided in a dase.

The present invention according to Claim 20 is

reverse speed level can be achieved, and in the case of the fourth forward speed level the first clutch and the second clutch are engaged

The aviamalic transmission of the foregoing embeliance Thievachieves six forward speeds and one reverse speed, and at fourth speed forward the first and second clutches the aviamalic transmission is are engaged together, that is to say directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be lowered, and thereby allowing engine revolutions can be lowered, and the avent reports.

The present invention according to Claim 21 is configured such that, in a speed line chart illustrating the revolutions of the first, second, third, and fourth rotation components with the vertical axis, and the gear ratio of the first, second, third, and fourth rotation components with the horizontal axis in a corresponding manner; the first rotation component to which the reduced rotation is input is positioned at the farthest edge in the horizontal direction, with the third rotation component, the fourth rotation component linked to the output member, and the second rotation component, corresponding in that order.

With the present invention according to Claim 22, the

the quietness of the vehicle while running at & high speed.

Of the Sirst

preterably

unit

vplanetary gear unit is a multiple type planetary gear, comprising a first sun gear, a long pinion which meshes with the first sun gear, a short pinion which meshes with the long pinion, a carrier for rotation ally supporting the long pinion and the short pinion, a second sun gear meshing with the short pinion, and a ring gear meshing with the long

In such an embodiment pinion wherein the first rotation component is the first which receives کیم sun gear eapable of inputring the reduced rotation of the reduced rotation output means, and which is capable of being against rotation engasement fixed by the retaining of the first brake, and wherein the which receives second rotation component is the second sun gear capable of input shaft by the engaging of the first clutch , and wherein the third rotation component is the carrier eapable of inputating the rotation of the input shaft by the engaging of the second clutch, and which zgzikst rotation is capable of boing fixed by the retaining of the second brake, and wherein the fourth rotation component is the ring gear linked to the output member.

The present invention according to Claim 23 comprises a pair of the planetary gear units each comprising a first sun gear, a second sun gear linked to the first sun gear, a first carrier meshing with the first sun gear, a second carrier meshing with the second sun gear, a first ring gear linked to the second carrier, and a second ring gear meshing with the second carrier, and a second ring gear meshing to the second carrier, and a second ring gear meshing to the second carrier, and a second ring gear meshing to the second carrier, wherein the first rotation.

which receives component is the second ring gear gapable of input//mg the reduced rotation of the reduced rotation output means, and against rotation which is capable of being fixed by the ret first brake and wherein the second rotation component is the first sun gear and the second sun rage capable of input the rotation of the input shaft by the engaging of the first clutch and wherein the third rotation component is the second carrier and the first ring gear which capable of input ping the rotations of the input shaft by engaging of the second clutch, and also capable of being engagement fixed by the retaining of the second brake, and wherein the fourth rotation component is a first carrier linked to the output member.

The present invention according to Claim 24 Is

In the Soregoing embodine of

configured wherein, in the first speed forward, the first

clutch is engaged and the second brake is retained; and

wherein, in the second speed forward, the first clutch is

engaged and the first brake is retained; and wherein in the

speed

third speed forward, reduced rotation is input to the first

rotation component from the reduced rotation output means,

and the first clutch is engaged; and wherein in the fourth

speed forward; the first clutch and the second clutch are

both engaged; and wherein in the fifth speed forward,

reduced rotation is input to the first rotation component

speed

from the reduced rotation output means, and the second

Coptionally olong with 15%

the second clutch is engaged and the first brake is engaged; and whereing in the first brake is engaged; and whereing in the first speed reverse, reduced speed rotation is input to the first rotation component from the reduced rotation output means, and the second brake is engaged. In this embadiment retained, whereby six forward speed levels and one reverse are provided speed levels and one reverse are provided.

No 97

With the present invention according to Claim 25, six and speed levels and one reverse speed level can be

the first clutch and the second clutch are engaged. To provide a

Accordingly, this achieves six forward speeds and one

second clutches are engaged together, that is to say

directly coupled at fifth speed forward. Therefore, between first speed forward and fourth speed forward, the width of the gear ratios can be specified in detail, and particularly

when mounted on a vehicle; in the event that the vehicle is speed running at a low to moderate speed, the engine can be consumption utilized with better revolutions, and fuel cost can be reduced,

improved with the vehicle running at a low to moderate speed.

The present invention according to Claim 26 is configured such that, in a speed line chart illustrating the revolutions of the first, second, third, and fourth rotation components with the vertical axis, and the gear ratio of the

first, second, third, and fourth rotation components with the horizontal axis in a corresponding manner; the first rotation component to which the reduced rotation is input is positioned at the farthest edge in the horizontal direction, with the fourth rotation component linked to the output member, the third rotation component, and the second

corresponding in that order. on component, Alternatively, in embodiments wherein present invention according to claim 27, planetary gear unit is a multiple type planetary gear comprising a first sun goar, a long pinion which meshes with the first sun gear, a short printon which meshes with the long pinion a carrier for rotationally supporting the long pinion and the short pinion, a second sun gear meshing with the short pinion and a king gear meshing with the long pinion; wherein the first rotation component is the second sun gear capable of inner of inputriog the reduced rotation of the reduced rotation output means; and wherein the rotation __component is the carrier capable of input/cage rotations of the input shaft by the engaging of the first clutch, and against roletion engagement which is capable of being fixed by the retain the vof the first brake; and wherein the third rotation component is the which receives first sun gear capable of input ming the rotations of the input shaft by the engaging of the second clutch, and which agains rotation by engagement is capable of being fixed by the retaining of the second brake; and wherein the fourth rotation component is the ring

gear linked to the output member:

In the foregoing alternative embodiment

The present invention according to Claim 28 is

-configured such that, in the first speed forward; reduced speed rotation is input to the first rotation component from the reduced rotation output means, and the first brake is engaged

retained; and wherein, in the second speed forward, reduced speed rotation is input to the first rotation component from the reduced rotation output means, and the second brake is cretained; and wherein, in the third speed forward, reduced speed rotation is input to the first rotation component from the reducedVrotation output means, and the second clutch is engaged; and whomin, in the fourth speed forward, reduced speed rotation is input to the first rotation component from the reduced rotation output means, and the first clutch is engaged; and whomein in the fifth speed forward, the first clutch and the second clutch are both engaged; and whorein in the sixth speed forward, the first clutch is augusted and the second brake is retained; and wherein in the first speed reverse, the second clutch is engaged and the first tre engaged Thus this embodiment also Provides
brake is retained whereby six forward speed levels and one

reverse speed level can be achieved

The present invention according to Claim 29 is

may be located on the configured with the first clutch configured on the opposite side in the axial direction of the planetary gear unit as to the speed reduction planetary gear.

The present invention according to Claim 29 is

may be located on the opposite side in the axial direction of the planetary gear unit as to the speed reduction planetary gear.

Carrier fixed to the case, optionally a boss on the interior of the case, and carrying pinions meshed will the input ratary element and the reduced speed rotary clement. Likewise, the sixable alement " May be a carrier which can be sixed against rotation by engagement of a brake and which corries pinions meshed with against rotation by engagement of a brake and which corries pinions meshed with the input notary element and the reduced speed rotary elements

is 17

With the present invention according to Claim 30, the first clutch is a clutch which engages at relatively low to medium speed level.

Accordingly, when this second clutch is disengaged at relatively high speed levels or at the reverse speed level, particularly the unit linking this second clutch and the third rotation component rotates at a relatively high speed or in the opposite direction. On the other hand, a case may transmittingmember, that transmits the reduced speed rotation from the reduced rotation output means rotates at reduced retailer or is engaged, and the difference in ltions may be great. However, because this second clutch is located on the opposite side of the reduced rotation output means via the planetary gear unit īn ay, the unit with a relatively high rota or vreverse rotation and the unit with reduced rotation of this reduced speed rotation output means (particularly the linking member) can be separated, and configured. For example, compared to the arranged in case wherein those units are confwith a multiple axis on and are in contact, decrease Pefficiency of the automatic transmission due to relative rotation # between these units can be prevented.

In the foregoing embodimen!

With the present invention according to Claim 31; the second clutch is a clutch that engaged at the reverse, level:

Accordingly, when this second clutch is engaged in

No #7

speed

reverse level, the reduced rotation unit (particularly the Speed transpeilling linking member) of the reduced vrotation output means rotates in reverse disections on the other hand, a case may occur wherein the unit linking this second clutch and the third rotation component becomes the rotation of the input shaft due to this second clutch being engaged, and the difference roTalional speeds in revolutions may be great. However, because this second opposite The clutch is located on the opposite side of the reduced rotation output means via the plan planetary gear unit, that is to say, the unit with reverse rotation (particularly the rotales with inking member) and the unit that ta on the rotation of A5 · 二個的學術 the input shaft can be configured separated. compared to the case wherein these units are configured a multiple axis construction and are in contact, decreased in efficiency of the automatic transmission due to relative rotation between these units can be prevented.

The present invention according to Claim 32 is

configured with the first clutch comprising a friction plate?

having their peripheries
of which the inner circumferential side is splined to a

member linked to the second rotation component, a first drum

member encompassing an oil pressure servo and which is
splined to the outer circumferential side of the friction

plate, a first piston member for presents the friction plate?

and a first oil pressure servo oil pressure chamber formed

livid-light

by sealing between the inner circumferential side of the

first piston member and the first drum member, so as to be liquid tight: wherein the second clutch comprises of friction the inner sirsum tial side is splined to a member linked to the third rotation component, a second drum member encompassing an oil pressure servo and which is splined to the outer eircumferential side of the friction plates and is disposed in the inner circumference side of a member linked to the second rotation component, a second piston member for present the friction plate, and a second hydraulic lydrasure chamber formed by sealing surface of the second piston between the inner circumferential member and the input shaft, and between the outer circumference eido and the second drum member, so as to be -liquid-tight.

The present invention according to Claim 33 is

eonfigured with the output member disposed between the Sirst

planetary gear unit and the reduced rotation output means, in

the axial direction.

Accordingly, the output unit can be configured in axial approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear the end receiving direction when the input side from the drive source is the front direction) can be prevented because the output member

is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of an FF vehicle,

the interference toward the front wheels is reduced, and the

mountability on a vehicle can be improved, such as the

steering angle being greatly increased, for example,

The present invention according to Claim 32 is nay be located axially configured with the output member disposed between the planetary gear unit and the second clutch, in the axial direction.

No F > rota

Accordingly, the planetary gear unit and the reduced pred rotation output means can be disposed even closer together, and the linking member can be shortened.

The present invention according to Claim 34 is

may be in the form of

configured with the reduced rotation output means comprising

Unit, more specifically,

a speed reduction planetary gear formed of a double pinion

planetary gear's wherein the speed reduction planetary gear,

for 5

the planetary gear unit, and the output member, are provided

coaxially with the input shaft.

The present invention according to Claim 35 is configured further comprising A differential unit for the outputting rotations to driving wheels, and a counter shaft unit for engaging the differential unit, wherein the output member is a counter gear meshing with the counter shaft unit.

Brief Description of the Drawings

view Fig. 1 is a schematic cross-sectional diagram an automatic transmission device of an according Mg to a first embodiment, Fig. 2 is ap operational table of an automatic transmission the first embodiment, 3 is a speed line torautomatic transmission relating Fig. 4 is a schematic cross-sectional diagramillustrating an automatic transmission device of an automatic transmission relating to a second embodiment 5 is a schematic cross-sectional diagram illustrating an -automatic transmission-device of an automatic transmission according Fig. 6 is an operation of relating to a third embodiment, table of an automatic transmission relating to the third Fig. 7 is a speed line diagram of an automatic to the third embodiment, Fig. 8 is a transmission rela VIEW schematic cross-sectional diagram illustrating an automatic _transmission device of an automatic transmission relatin a fourth embodiment, Fig. 9 is approperational table of automatic transmission relating to the fourth embodiment, For the Fig. 10 is a speed line diagram of an automatic transmission relating to the fourth embodiment. View Fig. 11 is a schematic cross-sectional diagraman automatic according automatic transmission relating to a fifth embodiment, view 12 is a schematic cross-sectional diagram illustrating an

ansmission device of an automatic transmission a sixth embodiment, Fig. 13 is a schematic View cross-sectional diagram illustrating an automatic transmission device of an automatic transmission relating to Fig. 14 is a schematic cross-sectional a seventh embodiment, illustrating an automatic transmission device of an automatic transmission relating to an eighth embodiment, Fig. 15 is a schematic cross-sectional diagram illustrating an automatic transmission device of an automatic transmission relating to a ninth embodiment, Fig. 16 is a schematic view cross-sectional diagram-illustrating an automatic according transmission devise of an automatic transmission relating to a tenth embodiment; Fig. 17 is a schematic cross-sectional view diagram illustrating an automatic transmission device of an automatic transmission relating to an eleventh embodiment, Fig. 18 is a schematic cross-sectional diagram illustrating View device of an automatic transmission relating to a twelfth embodiment, View schematic cross-sectional diagram illustrating an automatic transmission device of an automatic transmission relating to a thirteenth embodiment, and Fig. 20 is a schematic crosssectional diagram illustrating an automatic -device of an automatic transmission relating to a fourteenth embodiment.

View

Niew

Niew

Also, Fig. 21 is a schematic cross-sectional diagram

illustrating an automatic transmission device of an according automatic transmission relating to a fifteenth embodiment, table of an vautomatic transmission Fig. 22 is an operational the fifteenth embodiment, Fig. 23 is a speed Sor the line diagram of an automatic transmission relate $m ilde{V}_{
m Fig.}$ 24 is a schematic cross-sectional fifteenth embodiment illustrating an automatic transmission device of an according ing to a sixteenth embodiment, of and automatic transmission Fig. 25 is a operation to the sixteenth embodiment, Fig. 26 is a speed line diagram 😝 an automatic transmission relating to the sixteenth embodiment, Fig. 27 is a schematic cross-sectional diagram illustrating an automatic transmission automatic transmission selating to a seventeenth embodiment, of the 7 Fig. 28 is appropriational table of an automatic transmission to the seventeenth embodiment, and Fig. speed line diagram of automatic transmission see the seventeenth embodiment, Also, Fig. 30 is a schematic cross-sectional diagram-illustrating an automatic tran automatic transmission relating to an eighteenth embodiment, Fig. 31 is appropriational table of an automatic transmission the eighteenth embodiment, Fig. 32 is a speed line diagram of an automatic transmission relating to the eighteenth embodiment, Fig. 33 is a schematic cross-

view sectional diagram illustrating an automatic -device of an automatic transmission relating to a nineteenth embodiment, Fig. 34 is appropriation table of an automatic to the nineteenth embodiment, $V_{\text{Fig.}}$ 35 transmission relating is a speed line diagram automatic transmission -to the nineteenth embodiment, $^{oldsymbol{\prime}}$ Fig. 36 is a schematic cross-sectional diagram illustrating an automatic according to transmission device of an automatic transmission rela Fig. 37 is appoperation a twentieth embodiment, ar automatic transmission relating to the twentieth and Fig. 38 is a speed line diagram of automatic transmission relating to the twentieth embodiment, Also, Fig. 39 is a schematic cross-sectional di Thustrating an automatic transmission device of an automatic transmission relating to a twenty-first embodiment, View Fig. 40 is a schematic cross-sectional diagram-illustrating transmission device of an automatic transmission relating to a twenty-second embodiment, Fig. 41 is a schematic cross-sectional diagram illustrating an automatic transmission device of an automatic transmission according to a twenty-third embodiment, view schematic cross-sectional diagram illustrating transmission device of an automatic transmission relation a twenty-fourth embodiment, and Fig. 43 is a schematic Vícω
cross-sectional diagram illustrating an automatic

-transmission device of an automatic transmission relating to a twenty-fifth embodiment.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

Best Mode for Carrying Out the Invention

☆First Embodiment

The first embodiment relating to the present invention will be described, with reference to Fig. 1 through Fig. 3 below. Fig. 1 is a schematic cross sectional diagram filtustrating the automatic transmission device of an automatic transmission relating to the first embodiment, Fig. 2 is an operational table of an automatic transmission relating to the first embodiment, Fig. 3 is a speed line diagram of an automatic transmission relating to the first embodiment.

embodiment.

Fig. 1 Shows

1, according

Van automatic transmission relating to the first

embodiment according to the present invention has an

automatic transmission device 1, as illustrated in Fig. 1.

That is particularly favorable for an FF (front engine,
front wheel drive) vehicle, and has A case comprising a

housing case (not illustrated) and a transmission case 3, which
and within this housing case is configured a torque

converter, not illustrated, within this transmission case 3 houses the is configured an automatic transmission device l_1 , a counter shaft unit (drive wheel transmission device) (not illustrated) and a differential unit (drive wheel

transmission device).

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20

the axis that is centered on Van input shaft 2 of the automatic transmission device 1, which is on the same axis as the output shaft of the engine (not illustrated), and this automatic transmission device 1; is configured on the output shaft of this engine, in other words, the axis that is contered on an input shaft 2. Further, the abovementioned counter shaft unit is configured on a counter aligned shaft (not illustrated) on an axis that is parallel to the input shaft 2, and the above-mentioned differential unit is configured so as to have a lateral axle not illustrated, on the counter shaft.

next, an automatic transmission device 1, of an automatic transmission relating to the first embodiment will be described, with reference to Fig. 1. As illustrated in arranged along.

Fig. 1, whe input shaft 2, has a planetary gear unit PU and a second planetary gear (reduced rotation output means) PR. This The first planetary gear unit PU is a multiple type planetary gear includes which has a sun gear (the second rotation component) S2, a carrier (the third rotation component) CR2, a ring gear (the fourth rotation component) R3, and a sun gear (the first rotation component) S3, as the four rotation components wherein The carrier CR2 has a long pinion PL that meshes with sun gear S3 and a ring gear R3, and a short pinion PS

pinions 2/50 that meshes with a sun gear S2, which are meshed to one another. Further, the above mentioned planetary gear PR is a so-called double planetary gear that has a carrier CR1, which rotatably whorein a pinion Pb meshes with a ring gear R1 and a pinion pinions are also Pa meshes with a sun gear S1, which mesh one with another. on the above mentioned input shaft 2 is configured a multi-disc clutch (first clutch) C1, which comprises an oil -pressure servo 11, / friction plate 71, a drum shaped member 21 that forms a clutch drum, and a hub unit 22 like sun gear S2 on the inner circumference side; and a multiincludes a hydraulic disc clutch (third clutch) C3, which has servo 13, friction plate 73, a drum-shaped member 25 that forms a clutch drum on the outer circumference side. on the outer circumference side of the drumysperset -member 25 is configured a multi-disc brake B1 (first brake) hydraulic ofl pressure servo 14 and \not friction plate 74. Hudravic servo 11 is constructed from a piston unit b for pressurizing the friction plate 71, a drumpshaped member 21 that has a cylinder unit e, an oil pressure servo oil chamber (hereafter, simply "oil chamber") "a" which is . interposed formed by sealing between this piston unit b and this cylinder unit e with seal rings f and g, a return spring c piston unit b toward this oil chamber "a", bears the Sarce of this return and a return plate d that absorbs the

10

spring c.

Now, for the following descriptions, each oil pressure

servo shall be considered as being constructed similarly, to end the sharing from an oil chamber "a", a piston unit b, a return spring c,

a return plate d, a cylinder unit e, and seal rings f and g,

Thereos repeated

and, as such, these descriptions will not be given.

The oil chamber "a" of this oil pressure servo 11 is connected to an oil line 2a which is formed on the above mentioned input shaft 2, and this oil line 2a is provided along one edge of the case 3, and is connected to the oil in The form of a sleeve surrounding line 91 of the boss unit 3a which is provided on the input shaft 2, in a sleeve form. Further, this oil line 91 is connected to an oil pressure control unit, not illustrated. In other words, due to the above-mentioned oil pressure servo 11 being enfigured on the input shaft 2, an oil line from the oil pressure control unit, not illustrated, to the connected oil chamber "a" of the oil pressure servo 11 is configured, simply by providing one set of seal rings 81 to seal between the boss unit 3a of the case 3 and the input shaft 2.

Further, the oil chamber "a" of the above-mentioned oil hydraulic directly pressure servo 13 is connected to an oil line 92 of the above-mentioned boss unit 3a, and this oil line 92 is connected to an oil pressure control unit, not illustrated.

Thus, the hydraulic In other words, for the above mentioned oil pressure servo has it in oil line from the oil pressure control unit, not connected to the oil pressure illustrated, to the oil chamber "a" of the oil pressure

control unit serve 13 is configured, simply by providing one set of seal rings 80 km stal between the boss and 3a of the case and the drum that predimender 25.

The above-mentioned input shaft 2 is connected to the above-mentioned drum/shaped member 21, and ear the inner fiel surface circumference side of this drum/shaped member 21 is configured in a splined manner the friction plate 71 of the operated by the hydraulic clutch C1 which is eapable of engaging due to the oil pressure servo 11 for the clutch C1, and is connected wherein the inner effective side of the friction plates are intermeshed with friction plates 71 of this clutch C1 is splined to the hub unit 22. Further, which this hub unit 22 is connected to the above mentioned sun gear S2.

supported by the above mentioned boss unit 3a so as to rotate, and so the outer circumference side of the front partian edge of this drum shaped member 25 is splined the friction plate 74 of the brake Bl which can be rotated by the sill pressure servo 14 for the above mentioned brake Bl. On the inner circumference side of the front edge of this drum splined to splined to shaped member 25 is configured the friction plate 73 of the clutch C3 which is capable of engaging by the cill pressure servo 13 for the clutch C3, splined, and on the inner circumference side of the friction plate 73 of the clutch C3 which is capable of engaging by the cill pressure servo 13 for the clutch C3, splined, and on the inner circumference side of the friction plate 73 of this clutch

with Sriction Plates splined to

the ring gear Rl, is splined.

Further, The carrier CR1 has a pinion Pa and a pinion Pb, and this pinion Pb meshes with the above-mentioned ring gear R1, and this pinion Pa meshes with the sun gear S1 which As connected to the input shaft 2. This carrier CR1 is secured to the boss wait 3a of the case of via a side plate, and this ring gear R1 is supported by a supporting plate, which, in Turn, is rotate by supported by unit 26 to the boss wit 3a so as to rotate.

Further, to the above-mentioned drum Ashaped member 25 receives, wiz is sonnected a linking member (hereafter, also referred to as "transmitting member") 30, that transmits the rotation of the ring gear R1 when the clutch C3 is engaged, and further, -side of this transmitting member 30 is connected the sun gear S3 of the above mentioned planetary gear unit PU.

-On the other hand, on the other side of the input shaft 2 (left in diagram) is configured a multi-disc clutch (second clutch) C2 that has an oil pressure servo 12, friction plate 72, a drum/shaped months a that forms a clutch drum, and a hub unit 24 linked to a carrier CR2.

The Gil chamber "a" of this oil pressure servo 12 is connected to an oil line 2b which is formed on the abovementioned input shaft 2, and this oil line 2b is provided along the edge of the case 3 that is the opposite side of

-that of the above mentioned boss unit 3a, and is connected to the oil line 93 of the boss which is provided on zround

the input shaft 2, in a sleeve form. Further, this oil line

93 is connected to an oil pressure control unit, not

Thus,

illustrated. In other words, an oil line from the oil

ressure control unit, not illustrated, to the oil chamber

"a" of the oil pressure servo 12 is configured, simply by

providing one set of seal rings 82 to seal between the input

shaft 2 and the drum shaped member 23.

the left side of the dragram, a drum-shaped member 23 is connected, and on the inner circumference side of the front edge of this drum-shaped member 23 is splined the friction plate 72 of the clutch C2 which is capable of engaging by the out pressure servo 12 for the clutch C2. The inner circumference side of the friction plate 72 of this clutch are intermeshed wilk briction plate 72 of this clutch are intermeshed wilk briction plates.

C2 is splined to the hub unit 24, and this hub unit 24 is connected to the side plate of the above montioned carrier CR2.

On the other hand, on the outer circumference side of the planetary gear unit PU is configured a multi-disc brake (second brake) B2 that has an oil pressure servo 15, friction plate 75, and a hub unit 28. The side plate of the carrier CR2 of this planetary gear unit PU is connected to a hub unit 28 to which is splined the friction plate 75 of the above-mentioned brake B2, and further, this hub unit 28 is connected to the inner race of a one-way clutch F1.

Further, The above mentioned ring gear R3 meshes with the has one end connected to long pinion PL of this carrier CR2, a linking member 27 is connected to one edge of this ring goar R3, and this ring gear R3 is linked to the counter gear 5 via this linking member 27.

As described above, the planetary gear PR and the located at clutch C3 are configured on one side in the axial direction of the planetary gear unit PU, and also the clutch C1 is located the opposite exial direction, and the

direction, and the counter gear 5 is configured in between second unit 5:-5!

the planetary gear PR and the planetary gear unit PU.

Further, the clutch C1 is disposed on the inner

-sircumferential side of the clutch C3, and particularly of section of the transmitting member 30 that transmits the output thereof.

Further, the brake B1 is configured on the outer

Second Un: T

circumference side of the planetary gear PR, and the brake

B2 is configured on the outer circumference side of the first

planetary gear unit PU.

the operations of a automatic transmission device 1, will now be described, with reference to Fig. 1, Fig. 2, and Fig. 3 below. Now, the vertical axis of the speed line diagram illustrated in Fig. 3 indicate the revolutions of each rotation component, and the horizontal axis indicates the

corresponding gear ratio of these rotation components. regarding the planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 3) corresponds to sun gear S3, and horeafter moving to the left direction within the diagram, the vertical axis corresponds to the carrier CR2, the ring gear R3, and the sun gear S2. Further, regarding the planetary gear PR section of this speed line diagram, the vertical axis to the farthest horizontal edge-(the right side of Fig. 3) corresponds to sun gear S1, and thereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R1 and the carrier CR1. Further, the width between these vertical axes are proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the inverse of number of teeth of each of the ring gears R1, R3. -Also, the dotted line in the horizontal direction within the diagram represents that the rotation is transmitted from the transmitting member 30.

As illustrated in Fig. 1, the rotation of input shaft 2 is input to the above mentioned sun gear S2, by engaging the clutch C1. The rotation of input shaft 2 is input to the above-mentioned carrier CR2, by engaging the clutch C2, and this carrier CR2 can fix the rotation by the retaining of in limited to brake B2, and further, the rotation in one direction is

regulated by the one-way clutch Fl. Further, the sun gear be against engagement
S3 can fix the rotation by the rotation of the brake B1.

On the other hand, the above-mentioned sun gear S1 is

SO 25 To receive 25 input thereof.

connected to the input shaft 2 and the rotation of this

input shaft 2 is input, and further, the carrier CR1 is fixed

connected to the case 3 and its rotation is fixed, and

therefore the ring gear R1 rotates at reduced rotations.

Further, by engaging the clutch C3, the reduced rotation of

this ring gear R1 is input to the sun gear S3.

Also, the rotation of the above mentioned ring gear R3 is output to the above mentioned counter gear 5, and is output to the drive wheels via this counter gear 5, a counter shaft unit not illustrated, and a differential unit.

illustrated in Fig. 2, the clutch C1 and the one-way clutch F1 are engaged. Then, as illustrated in Fig. 3, the rotation of input shaft 2 is input to the sun gear S2 via the clutch C1, and the rotation of the carrier CR2 is limited to regulated in one direction (the forward rotation direction). In other words, the carrier CR2 is prevent from rotating in the opposite direction and becomes fixed. Further, the rotation of input shaft 2 that is input to the sun gear S2 is output to the ring gear R3 via the fixed carrier CR2, and the forward rotation for first speed forward is output from the counter gear 5. Now, When downshifting (when coasting),

the brake B2 is retained and carrier CR2 is fixed, and the above-mentioned state of first speed forward is maintained while preventing the forward rotation of this carrier CR2.

Further, at this first speed forward, the one-way clutch F1 prevents the carrier CR2 from rotation in the opposite direction and allows forward rotation, and therefore, switching from a non-driving range to a driving range and achieving the first speed forward can be accomplished more smoothly by the automatic engaging of the one-way clutch.

illustrated in Fig. 2, the clutch C1 is engaged and the brake B1 is retained. Then, as illustrated in Fig. 3, the rotation of input shaft 2 is input to the sun gear S2 via the clutch C1, and the sun gear S3 is fixed by retaining the brake B1. By doing so, the carrier CR2 slightly reduced rotation speed, and the rotation of input shaft 2 that was input in the sun gear S2 is output to the ring gear R3 via the carrier CR2 at this reduced rotation, and the forward rotation for second speed forward is output from the counter gear 5.

At third speed forward within the D (drive) range, as illustrated in Fig. 2, the clutch C1 and the clutch C3 are engaged. Then, as illustrated in Fig. 3, the rotation of input shaft 2 is input to the sun gear S2 via the clutch C1.

state of

sun gear S1 and the fixed carrier CR1, the ring gear R1 is rotated at 2 reduced retation speed, and the speed reduction speed rotation of their ring gear R1 is output to the sun gear S3 via the clutch C3 and the transmitting member 30. Then, the carrier CR2 has a slightly greater reduced rotation compared rotation of this sun gear S3 because of the rotation of the input shaft 2 input to the sun gear S2 and the reduced rotation of the sun gear S3. Further, the rotation of input shaft 2 that was input in the sun gear S2 is output to the ring gear R3 via the carrier CR2 at this reduced rotation, and the forward rotation for third speed forward is output from the counter gear 5. In this case, because the sun gear S3 and the ring gear R1 are vat a speed ion, the above-mentioned transmitting member 30 Transmile orms a relatively large torque transmission.

In fourth speed forward within the D (drive) range, as illustrated in Fig. 2, the clutch C1 and the clutch C2 are engaged. Then, as illustrated in Fig. 3, the rotation of input shaft 2 is input to the sun gear S2 via the clutch C1, and into the carrier CR2 via the clutch C2. Therefore, by input S the rotation of the input shaft 2 input to the sun gear S2 and the rotation of input shaft 2 input to the carrier CR2,

in other words, in the state of directly coupled rotation is established wherein the rotation of the input shaft 2 is output as is into the ring gear R3, and the forward rotation for fourth speed

forward is output from the counter gear 5.

At fifth speed forward within the D (drive) range, as illustrated in Fig. 2, the clutch C2 and the clutch C3 are engaged. Then, as illustrated in Fig. 3, the rotation of input shaft 2 is input to the carrier CR2 via the clutch C2. Further, by the rotation of the input shaft 2 input to the sun gear S1 and the fixed carrier CR1, the ring gear R1 role of a reduces retation speed, and the speed reduction speed rotation of this ring gear R1 is output to the sun gear S3 via the clutch C3 and the above-mentioned transmitting member 30. Then the Gverdrive rotation is output to the ring gear R3 from the reduced rotation of the sun gear S3 and the carrier CR2 wherein the rotation of the input shaft 2 io-imput, and the forward rotation for fifth speed forward is output from the counter gear 5. In this case, similar to the case of the above-mentioned third speed forward, due to rotation of the sun gear S3 and the ring gear R1 being at a reduced on, the above-mentioned transmitting member 30 performs a relatively large torque transmission.

At sixth speed forward within the D (drive) range, as illustrated in Fig. 2, the clutch C2 is engaged and the brake B1 is retained. Then, as illustrated in Fig. 3, the rotation of the input shaft 2 is input to the carrier CR2 via the clutch C2, and the sun gear S3 is fixed by retaining the brake B2. This causes an overdrive rotation (even

forward), from the rotation of the input shaft 2 input to state of which overdrive rotation the carrier CR2 and the fixed sun gear S3, and is output to the ring gear R3, and the forward rotation for sixth speed forward is output from the counter gear 5.

To the first speed reverse within an R (reverse) range, as illustrated in Fig. 2, the clutch C3 is ongaged and the are engaged Then, as illustrated in Fig. 3, the ring gear R1 rotates at reduced rotations from the rotation of input shaft 2 input to the sun gear S1 and the fixed state of carrier CR1, and the reduced rotation of this ring gear R1 this reduced rotation is output to the sun gear S3 via the clutch C3 and the above-mentioned transmitting member 30. Further, the carrier CR2 is fixed by retaining the brake B2. Then, the reduced rotation of the sun gear S3, and the carrier CR2 is output to the ring gear R3 as an opposite and is output as direction rotation, and the opposite direction rotation for first speed reverse is output from the counter gear 5. this case, similar to the case of the above-mentioned third speed forward or fifth speed forward, since the sun gear S3 rotating and the ring gear R1 are at a reduced setation, the abovetransmils a relatively large mentioned transmitting member 30 perfor

the P (parking) range and the N (neutral) range,

particularly clutch C1, clutch C2, and clutch C3 are

torque transmission.

released, the transmission movement between the input shaft 2 and the counter gear 5 is disconnected, and the automatic transmission device 1_1 as a whole is in an idle state (neutral state).

As described above, according to the automatic ٠f transmission device 11 relating to the present invention, due to the planetary gear PR and the clutch C1 being configured on one side in the axial direction of the Firs! planetary gear unit PU, and the clutch C2 being eon the axial direction of the planetary on the other side se cond uniT gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, compared to the case wherein for example two clutches C1 and C2 are located configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for transmitting reduced vrotation can be relatively shortened. La This manner doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia inertia can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. compared to the case wherein three clutches C1, C2, C3 are gured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 92, 93), that supply the hydrzulic mir pressure servos 11, 12, and 13 of these clutches C1, C2, C3, can be constructed easily, and the manufacturing process can be simplified and the costs brought down.

Further, due to the oil pressure servos 11 and 12 being provided on the input shaft 2, one set of seal rings 81 and serves to somm a connection with 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be hydraulic supplied to the oil chamber "a" of the oil pressure servos 11 and 12 without providing seal rings between, for example, hydraulic nressure servos 11 and 12. the input shaft 2 and the or receive 2 of Further, the orl pressure servo 13 can supply oil from the 1. €. boss unit 3a provided from the case 3, without passing through other units, for example, Therefore, the hydraulic serves eil by providing one set of seal rings 80.

connected to the oil supply can be supplied simply by providing one set of seal rings 81 and 82, 80 each for the oil pressure servos 11, 12, and 13, -and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved. located radially inward

Further, since the clutch C1 is configured on the inner circumference side of the clutch C3, the clutch C3, which must transmit a relatively large torque in order to transmit the reduced rotation, can be configured on the outer therefore circumference side, and this clutch C3 and the oil pressure operator servo 13 thereof can have an increased diameter.

Thus, Particularly the pressure area of the oil chamber "a" of the

capable of torque transmission of this clutch C3 can be increased. By confiduring the clutch C1 which can have a smaller capacity for torque transmission compared to the clutch C3, the automatic transmission can be made more compact.

Further, because the counter gear 5 is configured in the axial direction between the planetary gear unit PU and the planetary gear PR, the counter gear 5 can be conf in approximately the center in the axial direction of the automatic transmission. V for example, when the automatic transmission is mounted on the vehicle, enlarge towards the axis (particularly in the rear direction when the input side from the drive source is the is not necessary can be prevented because the counter gear 5 mate with is mounted to match the drive wheel transmission device. Because of this, particularly in the case of a FF vehicle, wilk the interference teward the front wheels is reduced, and the a vehicle can be improved, such as the steering $angle^{V}$ be a greatly increased, for example.

Further, the automatic transmission device 1, according to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when

event that the vehicle is running at a high speed, the engine revolutions can be relatively which allows lower , and this contributes to the quietness of the vehicle while running at a high speed.

Second Embodiment?

A second embodiment, which is a partial modification of the first embodiment, will be described, with reference to which shows Fig. 4 Fig. 4 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the second embodiment.

Now, Components of the second embodiment that are the same those of are as the first embodiment will be denoted with the same reference numerals, and description thereof omitted, except

those components for partial modifie

As Fig. 4 illustrates, the automatic transmission as having its -device 12 of the automatic transmission relating to the -second embodiment has the input side and output side 5 reversed backwards from that of the automatic transmission device 1_1

of the automatic transmission of the first embodiment.

operations of the warm through the Further, the actions of the first speed of Is of the second

sixth speed forward and the first speed reverse is similar embodiment are similar to those of the automatic transmission I, of the first (see Fig. 2 and Fig. 3).

As with in this second embodiment to the first embodiment, according

automatic transmission device-12 relating to the present invention, due to the planetary gear PR and the clutch C1

being configured on one side in the axial direction of the planetary gear unit PU, and the clutch C2 being configure on the other side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, compared to the case wherein, for example, two clutches C1 and C2 are located second unit the Siri the first second localed configured in between the planetary gear PR and planetary gear unit PU, so the transmitting member 30 for transmitting reduced rotation can be relatively shortened. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia (force) inertia) can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case where three clutches C1, C2, C3 are configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 92, 93) that supply the oil pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be MOTE (constructed easily, and the manufacturing process can be simplified and the costs brought down.

Further, since the off pressure servos 11 and 12 are

mounted
provided on the input shaft 2, one set of seal rings 81 and
serves to
82 seal the case 3 and supply oil to the oil lines 2a and 2b

provided within input shaft 2, and therefore oil can be
supplied to the oil chamber "a" of the oil pressure servos

11 and 12 without providing seal rings between, for example, hydraulic the input shaft 2 and the off pressure servos 11 and 12. pressure servo 13 can supply oil from the boss hydraulic unit 3a provided from the case of without passing through other units for example, in other words, can supply oil by providing one set of seal rings 80. Therefore, oil can be simply by providing one set of seal rings 81 and 82, 80 each for the oil prossure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and accordingly, the efficiency of the automatic transmission can be improved. because 13 loca to the clutch C1 being circumference side of the clutch C3, the clutch C3, which must transmit a relatively large torque in order to transmit the reduced rotation, can be configured on the Therefore, outer circumference side and this clutch C3 and the cil pressure servo 13 the can have an increased diameter, Particularly, the pressure area of oil chamber of the servo 13 can be enlarged, and the eapable of torque transmission o clutch 63 can be By configuring the clutch C1 whi smaller capacity for torque transmission compared to the clutch C3, the automatic transmission can be made more compact.

Further, because the counter gear 5 is seen

the axial direction between the planetary gear unit PU and seemed unit the planetary gear PR, the counter gear 5 can be configured axial in approximately the center in the axial direction of the will this second embodiment also automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards

one direction of the axis (particularly in the rear end which receives direction when the input side from the drive source is the front direction) can be prevented because the counter gear 5 mate will is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of and FF vehicle,

the interference toward the front wheels is reduced, and the

mountability on a vehicle can be improved, such as the

steering angle being greatly increased, for example.

according to the present embodiment is a transmission device

that is directly coupled at fourth speed forward. Therefore,

at fifth speed forward and sixth speed forward, the gear

ratio can be specified to a high ratio, and particularly

when mounted on a vehicle, in the event that the vehicle is

running at a high speed, the engine revolutions can be relatively less

lowered, and this contributes to the quietness of the

more quietly

vehicle while running at a high speed.

A third embodiment partially modified from the first embodiment will be described with reference to Fig. 5

diagram illustrating the automatic transmission device of an automatic transmission relating to the third embodiment, Fig. 6 is an operational table of an automatic transmission relating to the third embodiment, and Fig. 7 is a speed line diagram of an automatic transmission relating to the third embodiment, and Fig. 7 is a speed line diagram of an automatic transmission relating to the third embodiment. Now, components of the third embodiment that are the same as the first embodiment will be denoted with the same reference numerals, and description thereof omitted, thus components descriptions.

As Fig. 5 illustrates, the automatic transmission

device 1₃ of the automatic transmission relating to the

third embodiment is a modification of the configuration of

the planetary gear PR and the clutch C3 from that of the

automatic transmission device 1₁ of the automatic

transmission of the first embodiment (see Fig. 1).

The clutch C3 is configured on the planetary gear unit second unit.

PU side (left side of diagram) of the planetary gear PR.

within this automatic transmission device 13. The inner circumference side of the front edge of the drumffshaped.

member 25 of this clutch C3 is splined to the friction plates which are intermested will 73, and the inner sireumforence side of this friction plates splined to the hub unit 26. Further, the drum shaped member 25 is connected to the input shaft 2, and the hub unit 26 is connected to the sun gear S1.

3 d'Empod

Further, the side plate of the carrier CR1 is fixed and supported by the case 3. Also, the ring gear R1 is connected to the transmitting member 30, and the outer circumference side of this transmitting member 30 is splined to the friction plate 74 of the brake B1, and this transmitting member 30 is connected to the sun gear S3.

The oil chamber of this oil pressure servo 13 for the clutch C3 is connected to an oil line 2c which is formed in parallel with a double structure with oil line 2a on the Above mentioned input shaft 2, and this oil line 2c is connected to the oil line 92 of the boss unit 3a of the case 3.

Which, in Turn, Further, this oil line 92 is connected to an oil pressure control unit, not illustrated. In other words, due to the because the helps line of the because the helps line servo 11 and the oil pressure are mounted servo 13 being configured on input shaft 2, an oil line from the oil pressure control unit, not illustrated, to the oil chamber of the oil pressure servo 11 and the oil pressure servo 13 is configured, simply by providing seal ring 81 followed between the boss limit 3a of the case and the input shaft 2.

the Operations of the automatic transmission device 13 will

Now be described below, with reference to Fig. 5, Fig. 6, and

Fig. 7. Now, Similar to the above first embodiment, the

vertical axis of the speed line diagram illustrated in Fig.

utions of each rotation component, and 7 indicate the re the horizontal axis indicates the corresponding gear ratio of there rotation components. Further, regarding the planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 7 corresponds to the sun gear S3, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the carrier CR2, the ring gear R3, and the sun gear S2. Further, planetary gear PR section of this speed line diagram, the vertical axis to the farthest herizontal adjustine right side of Fig. 7 corresponds to the sun gear S1, and -horoafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R1 and the carrier CR1. Further, the width between these vertical axes are proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the inverse of the number of teeth of each of the ring gears R1, R3. Also, the (dotted line in the horizontal direction in the diagram illustrate that the rotation is transmitted from the transmitting member 30.

As Fig. 5 illustrates, the rotation of input shaft 2 is input to the above mentioned sun gear S1 by engaging the clutch C3. Further, the rotation of the above mentioned carrier CR1 is fixed of to the case 3, and the above

montioned ring gear R1 rotates at reduced rotations based on the rotation of input shaft 2 which is input to the sun gear S1. In other words, by engaging the clutch C3 the reduced rotation of the ring gear R1 is input to the sun gear S3 via the transmitting member 30.

In this wanter : llustrated in
By doing so, as Fig. 6 and Fig. 7 Ithustrate, regarding the planetary gear PR, at third speed forward, fifth speed forward, and first speed reverse, the rotation of the input shaft 2 is input to the sun gear S1 by engaging the clutch C3, and the reduced rotation is output to the ring gear R3 by the fixed carrier CR1, and the reduced retation is input to the sun gear S3 via the transmitting member 30. case, the ring gear R1 and the sun gear S3 are rotating at 2 reduced speed, therefore the above mentioned transmitting transmils member 30 performs a relatively large torque transmission. On the other hand, it first speed forward, second speed forward, fourth speed forward, and sixth speed forward, the rotation of the sun gear S3 is input to the ring gear R1 via the transmitting member 30, and further, because the clutch C3 is released, as Fig. 7 illustrates, the sun gear S1 rotates based on each the rotation within the speed level of

this ring gear R1 and the fixed carrier CR1. The operations described above for Now, the actions other than those of the above

mentioned planetary gear PR are similar to those of the previously about described first embodiment (see Fig. 2 and Fig. 3),

and accordingly description thereof will be omitted.

As described above, according to the automatic of this third embodimen transmission device 13 relating to the present invention, unit due to the ${}^{\mathbf{v}}$ planetary gear ${}^{\mathbf{w}}$ PR and the clutch C1 being axial bested -configured on one side in the axial direction of the First planetary gear unit PU, and the clutch C2 being config on the other side in the axial direction of the pla planetary second UNIT gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, compared to the case wherein for example two clutches C1 and C2 are located unit the S: located in between the planetary gear PR and planetary theresore gear unit PU, and the transmitting member 30 for -transmitting reduced rotation can be relatively shortened. In this manner By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia can be reduced, the controllability of the automatic transmission can-be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case wherein three clutches C1, C2, C3 are configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 92, 93) that supply the hydraulic pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, the manufacturing process can be reduced can be simplified and the costs brought down.

Further, due to the oil pressure servos 11, 12, and 13

seal the sace 3 and 3b to the input shaft 2, the seal rings 81 and 82 Can be seal the sace 3 and supply oil to the oil lines 2a and 2b, 2c provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11, 12, and 13 without providing the seal rings between, for example, the input shaft 2 and the oil pressure servos 11, 12, and 13.

Therefore, voil can be supplied simply by providing the seal rings 81 and 82 each for the oil pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, because the counter gear 5 is configured in SirsT the axial direction between the planetary gear unit PU and located second the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one-direction of the axis (particularly in the rear direction when the input side from the drive source is the front direction) can be prevented because the counter gear 5 is mounted to match the drive wheel transmission device. Because of this, particularly in the case of an FF vehicle, the interference toward the front wheels is reduced, and the mountability on a vehicle can be improved, such as steering angle being greatly increased, for example.

In transmissions where Further, in the event that the clutch C3 is placed

between the ring gear R1 and the sun gear S3 for example, the clotch C3

Thigh Torque, speed

the reduced rotation must be engaged and disengaged, and therefore must be

However, in the present invention,

becomes relatively large, but by placing between the input

shaft 2 and the sun gear S1, the engaging and disengaging of the Joth C3

transfer of

controls V the rotation of the input shaft 2 from this clutch C3 causes

output of speed

controls V the reduced rotation output from the ring gear R1. of the

planetary goar PR is to be engaged and disengaged, and the clutch C3 can be made more compact, and therefore the automatic transmission can be made more compact.

Further, the automatic transmission device 13 according this third to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be thus allowing lowerful, and this contributes to the quietness of the vehicle while running at a high speed.

ZFourth Embodiment

Below, the fourth embodiment, which is a partial now modification of the first embodiment, will be described with reference to Fig. 8 through Fig. 10. Fig. 8 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to

the fourth embodiment, Eig. 9 is an operational table of an automatic transmission relating to the fourth embodiment, and Eig. 10 is a speed line diagram of an automatic transmission relating to the fourth embodiment. Now,

those of the first embodiment which are the same as those of the first embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 8 illustrates, the automatic transmission

device 14 of the automatic transmission relating to the

fourth embodiment comprises a brake (third brake) B3 instead

of the clutch C3, and the carrier CR1 of the planetary gear

PR is can be fixed by the brake B3, in comparison with that

of the automatic transmission device 1, of the automatic

transmission of the first embodiment (see Fig. 1).

10

The brake B3 is configured on the opposite side of the apposite vplanetary gear unit po (right side of diagram) of the sint pu.

Y planetary gear PR within this automatic transmission device a hydraulic.

This brake B3 has an off pressure servo 16, A friction plate 76, and a hub unit 33.

The hub unit 33 of this brake B3 is connected on one side plate of the carrier CR1, and this carrier CR1 is rotatably supported by the boss and 3a or the input shaft 2, so as to be capable of rotation. Further, the sun gear S1 is connected to the input shaft 2 A Porther, the friction plate 5

74 of the brake Bl is splined to the outer circumference surface side of the ring gear R1. This ring gear R1 is connected to the transmitting member 30, and the sun gear S3 is connected via this transmitting member 30.

Continuing, based on the above mentioned construction, of the South embediment the Operations of an automatic transmission device 14 will hard be described, with reference to Fig. 8, Fig. 9, and Fig. 10, below. Now, as with the above-mentioned first embodiment, the vertical axis of the speed line diagram illustrated in the Various Fig. 10 indicate the revolutions of each rotation component, and the horizontal axis indicates the corresponding gear ratio of these rotation components. Further, regarding the first planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 10% corresponds to sun gear S3, and hereafter moving to the left direction within the diagram, the vertical axis correspond to the carrier CR2, the ring gear R2, and the sun gear S2. Further, regarding the planetary gear YPR section of this speed line diagram, the vertical axis to the farthest horizontal edge time right side of Fig. 10% corresponds to sun gear S1, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R1 and the carrier CR1. Further, the width between these vertical axes are inversely proportional to the inverse of the number of teeth of each

of the sun gears S1, S2, S3, and to the inverse of the number of teeth of each of the ring gears R1, R3. Also, the dotted line in the horizontal direction in the diagram in the diagram in the transmitting member 30.

As Fig. 8 illustrates, the above mentioned carrier CR1 is fixed to the case 3 by retaining with the brake B3, whereby Further, the rotation of the input shaft 2 is input to the sun gear S1, and the above mentioned ring gear R1 rotates at reduced retations based on the rotation of input shaft 2 and the braking of which is input to the sun gear S1, because the carrier CR1, is fixed. In other words, by engaging the brake B3, the reduced rotation of the ring gear R1 is input to the sun gear S3 via the transmitting member 30.

By doing so, as Fig. 9 and Fig. 10 illustrate, regarding the planetary gear PR, at third speed forward, fifth speed forward, and first speed reverse, the rotation of the input shaft 2 is input to the sun gear S1 by engagement of rotation with the brake B3, the carrier CR1 is fixed, and the reduced rotation is output to the ring gear R3 by the input of the sun gear S1 wherein the rotation of the input shaft 2 is input, and the reduced rotation is input to the sun gear S3 via the transmitting member 30. In this case, the ring gear R1 and the sun gear S3 are rotating at reduced speed, and therefore the above mentioned

transmitting member 30 performs a a relatively large torque. transmission. On the other hand, at first speed forward, second speed forward, fourth speed forward, and sixth speed forward, the rotation of the sun gear S3 is input to the ring gear R1 via the transmitting member 30, and further, because the brake B3 is released, as Fig. 10 illustrates, al a speed the carrier CR1 rotates based on each the rotation the speed level of this ring gear R1 and the sun gear S1 of operations of the Third embodiment, ow, the actions other than those of the above mentioned planetary gear PR are similar to those of the above-described first embodiment (see Fig. 2 and Fig. 3), and accordingly description thereof will be omitted. to the automatic third embodiment to the present invention, transmission device 13 relating due to the planetary gear PR and the clutch C1 being located on one side in the axial direction of the first planetary gear unit PU, and the clutch C2 being configured on the other side in the axial direction unit second PU, the planetary gear PR and the planetary gear unit PU can be configured closely together compared to the

case wherein for example two clutches C1 and C2 are configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 which transmitting reduced rotation can be relatively shortened.

By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertial force inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced.

Further, since the off pressure servos 11 and 12 are form provided on the input shaft 2, the seal rings 81 and 82 seals of the case 3 and supply of the the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12 without providing seal rings between, for example, the input shaft 2 and the off pressure servos 11 and 12. Therefore, the supplied simply by providing the seal rings 81 and 82 each for the oil pressure servos 11 and 12, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

the axial direction between the planetary gear unit PU and located the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear which receives input direction when the input side from the drive source is the

front direction) can be prevented because the counter gear 5

male with

is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of and FF vehicle,

the interference toward the front wheels is reduced, and the

mountability on a vehicle can be improved, such as the

steering angle being greatly increased, for example.

Further, because the reduced rotation output to the Sirst scored unit controlled by selective planetary gear unit PU from the planetary gear PR is engaged and of parts (for example, drum-shaped members and so forth) can be reduced as compared to the case wherein, for example, a clutch C3 is provided. Further, the brake B3 can configure an oil lime directly from the case 3, and therefore the configuration of the oil line can be simplified as compared to the case wherein, for example, a clutch C3 is provided.

Turther, the automatic transmission device 14 according to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be lowered, and this contributes to the quietness of the vehicle while runping at a high speed.

#Fifth Embodiment#

modification of the first embodiment, which is a partial modification of the first embodiment, will be described, below with reference to Fig. 11. Fig. 11 is a schematic cross pactional dragram illustrating the automatic transmission device of an automatic transmission relating to the fifth embodiment. Now, the fifth embodiment will be described in an abbreviated manner, using the same reference numerals for component that are the same as the first embodiment. Except for partial modifications.

As Fig. 11 illustrates, the automatic transmission device 15 of the automatic transmission relating to the ha5 modification of the configuration of hird embodiment is modified relative to the planetary gear PR and the clutch C3 from that of the automatic transmission device 11 of the automatic the first embodiment (see Fig. 1), and provided to tix the further, a brake B3 is gured, and the carrier CR1 of uni T Second. the planetary gear PR can be fixed by the In this sisth embediment located The clutch C3 is conf igured on the Vplanetary gear unit seand PU side (left side of diagram) of the planetary gear PR automatic transmission device 15, and the brake other, side of the second B3 is configured on the planetary gear PR on the opposite -from the Vplanetary gear unit PU. The inner circumference side of the front edge of the drumpshaped member 25 of this clutch C3 is splined to the friction plates 73, and the inner execuminance side ence side of this friction plates

splined to the hub unit 26. Further, the drum shaped member 25 is connected to the input shaft 2, and the hub unit 26 is connected to the sun gear S1.

The brake B3 is configured on the epposite side of the second opposite

planetary gear unit by (right side of diagram) of the Siral

unit Pu

planetary gear way. This brake B3 comprises an oil pressure

servo 16, a friction plate 76, and a hub unit 33. The

friction plate 76 is splined on the outer circumference side

of the hub unit 33 of this brake B3, and the hub unit 33 is

connected to one side plate of the carrier CR1, and this

carrier CR1 is supported by the input shaft 2 or the boss

unit 3a, so as to rotate. Also the friction plate 74 of the

brake B1 is splined on the outer circumference side of the

ring gear R1, and this ring gear R1 is connected to the

transmitting member 30, and the sun gear S3 is connected via

this transmitting member 30.

The oil chamber of this oil pressure servo 13 for the clutch C3 is connected to an oil line 2c which is formed to in parallel a doubled construction with oil line 2a on the abovementioned input shaft 2, and this oil line 2c is connected to the oil line 92 of the boss many 3a of the case 3.

Further, this oil line 92 is connected to an oil pressure control unit, not illustrated. In other words, because the above mentioned oil pressure servo 11 and the oil pressure servo 13 are configured on input shaft 2, an oil line from

the oil pressure control unit, not illustrated, to the oil chamber of the oil pressure servo 11 and the oil pressure servo 12 is configured, simply by providing seal ring 81 to seal between the boss unit 3a of the case 3 and the input shaft 2.

the operations of the automatic transmission device 15 will now below. Now, the present fifth embodiment is similar to the first embodiment, and therefore will be described based on the engagement chart and the speed line diagram described in the first embodiment (see Fig. 2 and Fig. 3).

As Fig. 11 illustrates, the rotation of input shaft 2 is input to the above mentioned sun gear S1 by engaging the clutch C3. Further, the rotation of the above mentioned engagement of carrier CR1 is fixed to the case 3 by the brake B3.

Tetaining. Therefore, upon the clutch C3 engaging and the brake B3 rotaining, the above mentioned ring gear R1 rotates at reduced rotations based on the rotation of input shaft 2 which is input to this sun gear S1. In other words, by engaging the clutch C3 and retaining the brake B3, the reduced rotation of the ring gear R1 is input to the sun gear S3 via the transmitting member 30.

By doing so, as Fig. 2 and Fig. 3 illustrate, regarding the planetary gear PR, at third speed forward, fifth speed

forward, and first speed reverse, the rotation of the input shaft 2 is input to the sun gear S1 by engaging the clutch ensegement of C3, and further, the carrier CR1 is fixed by brake B3, and therefore the reduced rotation is output to the ring gear R3 by the fixed carrier CR1, and the reduced ring gear R3 rotation is input to the sun gear S3 via the transmitting member 30. In this case, the ring gear R1 and the sun gear S3 are rotating at reduced speed, therefore the abovetransmits s a relatively large mentioned transmitting member 30 at first speed torque transmission. forward, second speed forward, fourth speed forward, and sixth speed forward, the rotation of the sun gear S3 is input to the ring gear R1 via the transmitting member 30, but because the clutch C3 and the brake B3 are released, the carrier CR1 and the sun gear S1 are freely rotating. Operations of the Sisth embodiments

Now, the actions other than those of the above second unit mentioned planetary gear PR, are similar to those of the above described first embodiment (see Fig. 2 and Fig. 3), and accordingly description thereof will be omitted.

As described above, according to the automatic

of the

transmission device 15 relating to the present invention,
location of the planetary gear PR and the clutch C1 being

configured on one side in the axial direction of the first

planetary gear unit PU, and the clutch C2 being configured

on the other side in the axial direction of the planetary

gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, compared to the -ease wherein for example two clutches C1 and C2 are second located configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for transmitting reduced rotation can be relatively shortened. oing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. a transmission compared to the case wherein three clutches C1, C2, C3 are located configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 92, 93) that supply the hydraulic pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, and the manufacturing process can be reduced can be simplified and the costs brought down. Further, since the oll pressure servos 11, 12, and 13 are provided on the input shaft 2, the seal rings 81 and 82 serve to connect

2c provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11, 12, and 13 without providing the seal rings between, for example, the input shaft 2 and the oil pressure servos 11, 12, and 13. Therefore, oil can be supplied simply by providing the seal

rings 81 and 82 each for the oil pressure serves 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, due to the counter gear 5 being configured in -direction between the Vplanetary gear unit PU and the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear em the drive source is the direction when the input side 4 is not necessary front direction) can be prevented because the counter gear 5 mete with is mounted to match the drive wheel transmission device. Because of this, particularly in the case of a FF vehicle, The interference toward the front wheels is reduced, and the mountability on a vehicle can be improved, such as the steering angle being greatly increased, for example. Further, in the event that the clutch C3 is placed

between the ring gear R1 and the sun gear S3 for example, it must be sufficiently large to transmit the high torque.

the reduced rotation must be engaged and disengaged, and the dutch C3

becomes relatively large, but by placing between the input shaft 2 and the sun gear S1, the engaging and disengaging of the rotation of the input shaft 2 from this clutch C3 causes

the reduced rotation output from the ring gear R1 of the second

planetary gear PR to be engaged and disengaged, and the fellow likewise clutches can be made more compact, and therefore the automatic transmission can be made more compact.

Further, the automatic transmission device 15 according Siff to the present embodiment is a transmission device that to directly coupled at fourth speed forward. Therefore, at in fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be thereby allowing the Torum lowered, and this contributes to the quietness of the more quietly vehicle while running at a high speed.

Sixth Embodiment

Below, the sixth embodiment, which is a partial now modification of the first embodiment, will be described; with reference to Fig. 12. Fig. 12 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the sixth embodiment. Now, components of the sixth embodiment which are the same as those of the first embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 12 illustrates, the automatic transmission

device 16 of the automatic transmission relating to the

has beared

sixth embodiment configures the clutch C2 on one side in the

No P

axial direction wherein the planetary gear PR of the planetary gear unit PU is configured, and the clutch of is localed in the axial direction; in sixth embodine of has other words, the configuration is such that the positions where the clutch C1 and the clutch C2 are disposed are switched as compared to that of the automatic transmission device 1, of the automatic transmission of the first embodiment (see Fig. 1).

This automatic transmission dealer 16 comprises a multia hydraulic
disc clutch C2 comprising an off pressure servo 12, a
friction plate 72, a drum product member 23 that forms a

2 clutch drum, a hub unit 24 linked to a sun gear S2 on the
radially inward
inner chroumference side of the above-mentioned input shaft
2, and a multi-disc clutch C3 comprising an oil pressure
servo 13, a friction plate 73, a drum shaped member 25 that
forms a clutch drum, a hub unit 24 linked to a sun gear S2
on the outer circumference side. Further, a multi-disc
brake B1 comprising an oil pressure servo 14 and a friction
plate 74.

The above drum-shaped member 23 is connected to the flavoristic above input shaft 2, and and the inner circumference side of portion is the front edge of this drum shaped member 23 is configured by splining to the friction plate 72 of the clutch C2 which can be engaged by the oil pressure servo 12 of the clutch C2, intermeshed and the inner circumference side of the friction plate 72 of

with Sriction plates splined this clutch C2 is connected to the hub unit 24 by oplining.

Further, this hub unit 24 is connected to the above-mentioned carrier CR2.

On the other hand, on the other edge of the input shaft

2 (left of the diagram) is configured a multi-disc clutch C1

comprising an origination servo 11, friction plate 71, a

dram-shaped member 21 that forms a clutch drum, a hub unit

22 linked to a sun gear S2.

the left side of the diagram, the drum shaped member 21 is connected, on the inner circumference side of the front odge of this drum shaped member 21 is configured by means of splining the friction plate 71 of the clutch C1 that can be engage by the oil pressure servo 11, for the clutch C1. On are intermed the friction plate 71 of the friction plate 71 of the clutch C1. On are intermed to the inner erroumference side of the friction plate 71 of this clutch C1 the hub unit 22 is splined, and this hub unit 22 is splined, and this hub unit 22 is connected to the above mentioned sun gear S2.

The operations of the automatic transmission device 167 hased on the above construction, are similar to those of the above mentioned first embodiment (see Fig. 2 and Fig. 3), and accordingly description thereof will be omitted.

transmission device 16 relating to the present invention,

due to the planetary gear PR and the clutch C2 being

configured on one side in the axial direction of the

planetary gear unit PU, and the clutch C1 being configured on the other side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, compared to the

-case wherein for example two clutches C1 and C2 are configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for transmitting reduced rotation can be relatively shortened. In this manner By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia (force of inertia) can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, 4 transmission compared to the case wherein three clutches C1, C2, C3 are bested configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 92, 93) that supply the hydraulic oil pressure servos 11, 12, and 13 of these clutches C1, C2, MOTE C3 can be constructed easily, and the manufacturing process can be reduced can be simplified and the costs brought down.

Further, since the oil pressure servos 11 and 12 are mounted provided on the input shaft 2, one set of seal rings 81 and 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12 without providing the seal rings between, for example, the

input shaft 2 and the off pressure servos 11 and 12.

Further, the oil pressure servo 13 can supply oil from the boss unit 3a extended from the case 3, without passing through other parts for example, and therefore can supply can be connected oil by providing one set of seal rings 80. Therefore, oil can be supplied simply by providing one set of seal rings 81 and 82 each for the oil pressure servos 11 and 12, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, since the clutch C2 is configured on the inner circumference side of the clutch C3, the clutch C3, which must transmit a relatively large torque in order to transmit the reduced rotation, can be configured on the outer circumference side, and this clutch C3 and the oil pressure servo 13 thereof can have an increased diameter, a larger pressure area of the oil chamber of the oil pressure of torque transmission of this clutch C3 can be increased.

By configuring the clutch C2 which can have a smaller capacity for torque transmission compared to the clutch C3,

the automatic transmission can be made more compact.

As with the previously described embodiments

Purther, because the counter gear 5 is configured in

the axial direction between the planetary gear unit PU and

second unit

the planetary gear PR, the counter gear 5 can be configured

in approximately the tenter in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear direction when the input side from the drive source is the front direction) can be prevented because the counter gear 5 is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of a FF vehicle, the interference toward the front wheels is reduced, and the mountability on a vehicle can be improved, such as the steering angle being greatly increased, for example.

Further, the clutch Cl is a clutch which engages at the relatively slow to medium speed levels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is released at the relatively high speed levels of fifth speed forward, sixth speed forward, or first speed reverse, particularly the hub unit 22 that connects this clutch C1 and the sun gear S2 rotates at a relatively high revolution or nevolver in reverse (see Fig. 7). On the other hand, at the fifth speed forward of first speed reverse the rotates at a reduced transmitting member 30 reduces rotation speed, and at the sixth speed forward the transmitting member 30 may be fixed in some cases, and difference in reve between the hub unit 22 and the transmitting member 30 can occur.

because this clutch C1 is located on the opposite side of the planetary gear PR via the planetary gear unit PO, the hub unit 22 and the transmitting member 30 can be configured apart from one another. Compared with a sase wherein these units are in contact due to a multi-axial configuration for example, decreased efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

Further, the automatic transmission device 16 according to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at in fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be lowered, and this contributes to the quietness of the vehicle while running at a high speed.

Now, the linking member (in particular the transmitting second vait for linking the planetary gear VPR and the planetary gear unit PU requires rigidity, to withstand the reduced speed torque that is input. For example, in the case of configuring a clutch that engages at a slow to medium speed for transmission of or a clutch that engages and disengages reduced rotations on the inner circumference side of the linking member, the clutches must have a large capacity, therefore also

appropriate diameter to correspond with this capacity thing becomes necessary. Therefore, in the event that the linking member is the type that passes on the outer circumforence side of this type of clutch, even a larger diameter than the necessary diameter measurement of those clutches becomes necessary, and the diameter measurement of the linking radial dimension of the member is enlarged more than necessary, and the vautomatic transmission as a whole becomes greater in the radial direction. Accordingly, it is an object of this embodiment to reduce the enlargement of the diameter measurement, and thereby more provide a compact automatic transmission.

According to the present embodiment, all clutches can arranged so as to avoid need for be configured without enlarging the diameter measurement of specifically by arranging the linking member, by configuring a clutch C2 with a small radial invariant capacity on the linking member, particularly on the inner circumference side of the transmitting member 30.

Seventh Embodiments

The seventh embodiment partial modified from the and sixth embodiment will be described received with reference to Fig. 13. Fig. 13 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the seventh embodiment.

New, Components of the seventh embodiment which are the same as those of the sixth embodiment will be denoted with the same reference numerals, and description thereof omitted,

except for partial modifications.

As Fig. 13 illustrates, the automatic transmission device 17 of the automatic transmission relating to the seventh embodiment is a modification of the configuration of the planetary gear PR and the clutch C2 and the clutch C3, as compared to that of the automatic transmission device 16 of the automatic transmission of the sixth embodiment (see Fig. 12).

are located The clutch C2 and the clutch C3 is configured on the opposite side of the planetary gear unit PU (right side of opposite 5:737 unit PU the diagram) of the planetary gear PR within this automatic transmission device 17. The inner circumference side of partion front edge of the drum shaped member 25 of this clutch C3 is splined to the friction plate 573, and the inner effcumference side of this friction plate who splined to the hub unit 26. The drum shaped member 25 is connected to the input shaft 2, and the hub unit 26 is connected to the sun gear S1 of the planetary gear PR. Further, the clutch Lydraulic C2 comprising a oil pressure servo 12, a friction plate 72, a drum shaped member 23, and a hub unit 24 is configured on radially inward the inner circumference side of the above-mentioned clutch dutch C2 C3, that is to say, is enclosed within the hub unit 26.

On the other hand, on the outer circumference side of second with the planetary gear PR is configured a multi-disc brake B1 that comprises an off pressure servo 14 and a friction plate?

seconcl

74. The side plate of the carrier CR1 of this planetary gear PR is fixed and supported by the case 3. Further, the the sun gear S3 by ring gear R1 is connected to the transmitting member 30, and the friction plate 74 of the brake B1 is splined to the outer circumference side of this transmitting member 30, and this transmitting member 30 is connected to the sun gear S3.

The operations of the automatic transmission devices 17, of this seventh embodiment based on the above construction, are similar to those of the third embodiment (see Fig. 6 and Fig. 7), and accordingly description thereof will be omitted.

As described above, according to the automatic,

of the seventh embatiment

transmission device 1, relating to the present invention,

second unit

due to the planetary gear PR and the clutch C2 being

configured on one side in the axial direction of the first

planetary gear unit PU, and the clutch C1 being configured

on the other side in the axial direction of the planetary

gear unit PU, the planetary gear PR and the planetary gear

unit PU can be configured closely together, compared to the

gear unit PU, and the transmitting member 30 for which transmitting reduced rotation can be relatively shortened.

In this manner By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertial force inertial can be reduced, the controllability of

the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case wherein three clutches C1, C2, C3 are sonfigured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 92, 93) that supply the oil pressure servos 11, 12, and 13 of these clutches C1, C2, wore

C3 can be constructed easily, and the manufacturing process can be simplified and the costs prought down.

hydraulic Hipressure servos 11 and 12 are Further, since the off mounted provided on the input shaft 2, one set of seal rings 81 and 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12 without providing the seal rings between, for example, the hydraulic pressure servos 11 and 12. input shaft 2 and the Further, the oil pressure servo 13 can supply oil from the boss with 3a extended from the case 3, without passing components through other parts for example, and therefore can supply can be sonnected oil by providing one set of seal rings 80. Therefore, oil Can be supplied simply by providing one set of seal rings 81, -82, and 80 each for the oil pressure servos 11 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, since the counter gear 5 is configured in the

planetary gear VPR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear facing when the input side from the drive source is the front direction) can be provented because the counter gear 5 is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of aff FF vehicle, the interference toward the front wheels is reduced, and the mountability on a vehicle can be improved, such as the steering angle being greatly increased, for example.

relatively slow to medium speed bevels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is released at the relatively high speed levels of fifth speed forward, sixth speed forward, or first speed reverse, particularly the hub unit 22 that connects this clutch C1 and the sun gear S2 rotates at a relatively high revolution

or **evolves* in reverse (see Fig. 7). On the other hand, **

fifth speed forward of first speed reverse the transmitting member 30 reduces rotation speed, and at a sixth speed forward the transmitting member 30 can engage,

The Embos

whereby There can be a large speed 35 and difference in revolutions between the hub unit 22 and the transmitting member 30, can occur. However, because this clutch C1 is located on the opposite side of the planetary gear PR via the planetary gear unit PD, the hub unit 22 and second the transmitting member 30 can be configured apart from one another. In comparison with the case wherein, for example, these members are in contact due to a multi-axial configuration, decreased efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

-Further, in the event that the clutch C3 is placed

the reduced rotation must be engaged and disengaged, and therefore Must be becomes relatively large, but by placing between the input

shaft 2 and the sun gear S1, the engaging and disengaging of

the rotation of the input shaft 2 from this clutch C3 eauses

controls autput of

v the reduced rotation output from the ring gear R1 of the second

unit

planetary gear VPR to be engaged and disengaged, and the

clutch C3 can be made more compact, and therefore the

as a whole

automatic transmission can be made more compact.

Further, the automatic transmission device 1, according to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when

the event that the vehicle is mounted on a vehicle, running at a high speed, the engine revolutions can be lowered, and this contributes to the quietness of the vehicle while running at a high speed. were to be localed is configured in between the second a clutch is planetary gear PR and the planetary gear unit PU for example, the length of the linking member (particularly the second transmitting member) that links the planetary gear PR and in the axially elongated the planetary gear unit PU becomes jone transmitting direction, and because this nking member is for transmit $\frac{1}{1}$ the reduced $\frac{1}{1}$ rotation, the thickness of the unit must be increased so as to withstand this, and therefore the weight also increases. Therefore an object of the present wherein invention is to provide an automatic transmission that shorten the distance between the speed reduction planetary gear and the planetary gear unit, and reduce the increase in the weight is Thereby reduced In this seventh present embodiment, in particular, the clutch posed on the opposite side in the axial PR axially opposit of the planetary gear unit posterom the planetary gear of the sirst and second and therefore, providing a clutch between the planetary gear Units PR and the planetary gear unit PU is not necessary, and the length of the linking member particularly the transmitting member 30 can be made that much shorter. Therefore, The ncrease in weight of the automatic transmission as a whole

can be prevented.

/Eighth Embodiment/

Now, the eighth embodiment which is a partial modification of the sixth embodiment will be described with reference to Fig. 14. Fig. 14 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the eighth embodiment. Now, components of the eighth embodiment which are the same as those of the sixth embodiment will be denoted with the same reference numerals, and description there of omitted, except for partial modifications.

As Fig. 14 illustrates, the automatic transmission

device 18 of the automatic transmission relating to the

has

eighth embodiment is a modification of the configuration of

modified

has

the clutch C2, and further configures a brake B3 instead of

a clutch C3, and enables the carrier CR1 of planetary gear

which features differ from those

PR to be fixed by the brake B3, as compared with that of the

automatic transmission device 16 of the automatic

Within the automatic transmission device 18, the brake

| Ocated side of the second Unit axially

B3 is configured on the planetary gear PR con the opposite

(right side on the diagram) from the planetary gear unit PU.

This brake B3 comprises an oil pressure servo 16, a friction plate 76, and a hub unit 33. Further, the clutch C2, comprising an oil pressure servo 12, a friction plate 72, a

drum shaped momber 23, and a hub unit 24, vis configured on inward of the the inner circumference side of above mentioned brake B3, i.e. that is to say, is enclosed within the hub unit 33. The hub unit 33 of this brake B3 is connected to the side plate of one side of the carrier CR1, and the vide plate of the other side of this carrier CR1 is supported by the input shaft 2.

so as to be capable of rotating. Further, the sun gear S1 is connected to the input shaft 2 via the drum shaped member 24 of the clutch C2. Also, the friction plate 74 of the brake B1 is splined with the outer circumference side of the ring gear R1, and this ring gear R1 is connected to the sun gear S3, wis this transmitting member 30, and is connected to the sun gear S3, wis this transmitting member 39.

The operations of the automatic transmission device 18 of of eighth embodiment based on the above construction, are similar to those of the fourth embodiment (see Fig. 9 and Fig. 10), and accordingly not repeated here description thereof will be emitted.

As-described above, according to the automatic transmission device 18 relating to the present invention, Unit second due to the Vplanetary gear PR and the clutch C2 being lac ested configured on one side in the axial direction of the firs located planetary gear unit PU, and the clutch C1 being configured on the vother side in first the axial direction of the planetary unit second SINST gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, Vcompared to the

case wherein for example two clutches C1 and C2 are for and second white configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for transmitting reduced rotation can be relatively shorteased.

By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertial force inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced.

Further, since the expressure servos 11 and 12 are mounted provided on the input shaft 2, the seal rings 81 and 82 sear to connect the ease 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12 without providing the seal rings between, for example, the input shaft 2 and the oil pressure servos 11 and 12.

Therefore, oil can be supplied simply by providing the seal rings 81 and 82 each for the oil pressure servos 11 and 12, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, since the counter gear 5 is configured in the axial direction between the planetary gear unit PU and the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the

automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear direction when the input side from the drive source is the front direction) can be prevented because the counter gear 5 mate with is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of and FF vehicle, the interference toward the front wheels is reduced, and the mountability on a vehicle can be improved, such as the steering angle being greatly increased, for example.

Further, the clutch C1 is a clutch which engages at the relatively slow to medium speed levels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is released at the relatively high speed levels of fifth speed forward, sixth speed forward, or first speed reverse, particularly the hub unit 22 that connects this clutch C1 and the sun gear S2 rotates at a relatively high or revelves in reverse (see Fig. 10). On the other hand, at the fifth speed forward or first speed reverse the transmitting member 30 reduces retation speed, and at a sixth speed forward the transmitting member 30 may be fixed in some cases, and difference in reve utions between the hub unit 22 and the transmitting member 30 can occur. because this clutch C1 is located on the epposite side of

unit prexielly opposite the planetary gear via the planetary gear unit hub unit 22 and the transmitting member 30 can be $\stackrel{ extbf{eq}}{=}$ 2 toansmission apart from one another. In comparison with the case wherein, for example, these members are in contact due to a multiaxial configuration, decreased efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

Further, because the reduced rotation output to the first planetary gear unit PU from the planetary gear PR is made engaged and disengaged by the brake B3, the number of parts (for example drum-shaped members and so forth) can be an embodiment employing a reduced as compared to the case wherein, for clutch C3 is provided. Further, the brake B3 can configure oil line directly from the case 3, and therefore the configuration of the oil line can be simplified as compared an embodiment employing to the case wherein for example, a clutch C3, is provided.

Further, the automatic transmission device 18 according to the present embodiment is a transmission device directly coupled at fourth speed forward. Therefore, at 1 fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolution lowered, and this cont tributes to the quietness of the vehicle while runging at a high speed.

Jocated in between the Sirst and second -planetary gear PR and the planetary gear unit PU for example, the length of the linking member (particularly gear PR and second transmitting member that links the planetary the planetary gear unit PU becomes longer in the axially elongated direction, and since this linking member is for transmitting JPEC. the reduced rotation, the thickness of the member must be increased so as to withstand this, and therefore the weight 15 also increased. Therefore an object of the present invention is to provide an automatic transmission that shorten the distance between the speed reducgear and the planetary gear unit, and reduce the increas weight's Thereby reduced. In this eighth has the clutch the clutch

c2 is disposed on the opposite side in the axial direction second proposite size of the planetary gear unit po from the planetary gear unit po from the planetary gear providing a clutch between the planetary gear unit pu is not necessary, and the length of the linking member, particularly the transmitting member 30 can be made that much shorter. Therefore, and increase in weight of the automatic transmission as a whole can be prevented.

Winth Embodiment

Below, the ninth embodiment, which is a partial now modification of the first embodiment, will be described

with reference to Fig. 15. Fig. 15 is a schematic crosssectional diagram illustrating the automatic transmission device of an automatic transmission relating to the ninth embodiment Now Components of the ninth embodiment which are the same as those of the first embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 15 illustrates, the automatic transmission ور ما devlee 19 of the automatic transmission relative ocaTed located a clutch C2 on one si ninth embodiment configures between the planetary gear PR of the planetary gear unit PU is configured, and configures the clutch Cl and the counter gear 5 on the ather side of the first planetary gear on Thus, axialy diffection, that is to say, interchanges the locations

of the clutch C1 and the clutch C2, and further, the positions of the unit V planetary gear VPR, the clutch C3, and the brake B1 are and are neversed the position the counter gear 5 of planetary gear unit PU, as compared to that of the automatic transmission device 11 of the automatic transmission of the first embodiment (see Fig. 1). mounted

Within the automatic transmission device 1, on the above mentioned input shaft 2 is configured a multi-disc clutch C1, which comprises an expressure servo 11, friction plate 71, a drum shaped member 21 that forms a clutch drum, and a hub unit 22 liked to a sun gear S2 on the

MITPU

Vinner circumference side.

The oil chamber of this of pressure servo 11 is connected to soil line 2a which is formed on the above mentioned input shaft 2, and this oil line 2a is provided along one edge of the case 3, and is connected to the oil in the firm of 3 sleeve surrounding one ends in the firm of 3 sleeve surrounding one ends line 91 of the boss unit 3a which is provided on the input shaft 2 in a sleeve form. Further, this oil line 91 is connected to an oil pressure control unit, not illustrated. In other words, since the above-mentioned oil pressure servo 11 is configured on input shaft 2, an oil line from the oil pressure control unit, not illustrated to the oil chamber of the oil pressure servo 11 is configured; simply by providing one set of seal rings 81 to seal between the boss unit 3a of the case 3 and the input shaft 2.

The above mentioned input shaft 2 is connected to the having an above mentioned drum-shaped member 21, and on the inner circumference side of this drum shaped member 21 is suffice To which configured the friction plate 71 of the clutch C1 which is capable of engaging by the oil pressure serve 11 for the clutch C1, splined, and is connected wherein the inner circumference side of the friction plate 71 of this clutch in turn, C1 as splined to the hub unit 22 present this hub unit 22 present this hub unit 22 is connected to the above memberoned sun gear S2.

On the other hand, On the other side of the input shaft side

2 (left in diagram) is configured a multi-disc clutch C2

that has an oil pressure servo 12, a friction plate 72, a drum shaped member 23 that forms a clutch drum, a hub unit 24 linked to a carrier CR2. On the outer circumference side is configured a multi-disc clutch C3 that comprises an oil pressure servo 13, a friction plate 73, and a drum unit 25, that forms a clutch drum. Further, on the outer circumference side of the drum phaped member 25 is configured a multi-disc brake B1 that comprises on oil pressure servo 14 and a friction plate 74.

The oil chamber of this oil pressure servo 12 is connected to an oil line 2b which is formed on the above mentioned input shaft 2, and this oil line 2b is provided along the edge of the case 3 that is the opposite side of

to the oil line 93 of the boss which is provided on communication the input shaft 2 in a sleeve form. Therefore, an oil line

oil chamber of the eil pressure servo 12 is constructed on the above mentioned eil pressure servo 12, simply by providing one set of seal rings 82 to seal between the boss and the input shaft 2.

Further, the oil chamber of the above mentioned of hydraulic pressure servo 13 is connected to an oil line 94 of the above mentioned boss unit 3b, and this oil line 94 is connected to are oil pressure control unit, the illustrated.

The Embodiment

In other words, for the above-mentioned oil pressure servo an oil line from the oil pressure control unit, to the oil, chamber providing Gorm a is constructed, by one set of seal rings 84 to seal between the boss and the drum shaped member 25. above-mentioned input shaft 2 is connected to the above mentioned drum bhaped member 23 or the left side of the diagram, and A the inner circumferen clutch
splined to
this drum shapped member 23 is configured the friction plate. 72 of the clutch C2, which as capable of engaging by the oil pressure servo 12 for the clutch C2, splined, and is connected wherein the inner circumference side of the is clutch 62 is splined to the hub which unit 24 Further, this hab unit 24 is connected to the above-montioned carrier CR2. clutch Further, The above-mentioned drumpshaped member 25 is rotatably supported by the above mentioned boss unit 3b se as to a stort portion as tate, and and the outer circumference clotch splined -edge of this drum shaped member 25 is configured friction plate 74 of the brake Bl, which is capacity operation of hydraulic retaining by the cil pressure servo 14 for the abovementioned brake Bl, splined, on the inner circumference Sace portion clutch' side of the front edge of this drum shaped member 25 is configured the friction plate 73 of the clutch C3 which is engaged disengaged hydraulic. engaging by the oil pressure vservo 13 for the

the friction plate 73 of this clutch C3 the ring gear R1 is splined.

Further, carrier CR1 has a pinion Pa and a pinion Pb, and this pinion Pb meshes with the above mentioned ring gear R1, and this pinion Pa meshes with to the sun gear S1 which IS connected to the input shaft 2. This carrier CR1 is secured to the boss muit 3b of the case 3 via a side plate, and this ring gear R1 is supported by a supporting unit 26 executing to the boss unit 3b so as to rotate.

Further, to the above mentioned drum shaped member 25 is connected a linking member 30 that transmits the rotation of the ring gear R1, when the clutch C3 is engaged, and further, to the other side of this transmitting member 30 is connected the sun gear S3 of the above-mentioned planetary gear unit PU.

The operations of the automatic transmission dowice 19 7 nink embodiment based on the above construction, are similar to those of the first embodiment (see Fig. 2 and Fig. 3), and accordingly description thereof will be emitted.

As described above, according to the automatic,

of the ninth embodiment, because
transmission device 1, relating to the present invention,

second unit

due to the planetary gear PR and the clutch C2 being
configured on one side in the axial direction of the
is located
V planetary gear unit PU, and the clutch C1 being configured

= xially opposite on the other side in the axial direction of the planetary Unit second gear unit PU, the planetary gear PR and the planetary gear located more unit PU can be configured closely together, as compared to an automatic Transmission the case wherein, for example, two clutches C1 and C2 are configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for transmitting reduced rotation can be relatively shortened. In this manner

By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia force inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case wherein three clutches C1, C2, C3 are 10cz Ted configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 93, 94) that supply the hydraulic il pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, and the manufacturing process can be reduced can be simplified and the costs brought down. 4xdraulic

Further, since the oil pressure servos 11 and 12 are

/ocatel

provided on the input shaft 2, one set of seal rings 81 and

Sorm and Silvery connection by providing a

82 seal the case 3 and supply oil to the oil lines 2a and 2b

provided within input shaft 2, and therefore oil can be

supplied to the oil chamber of oil pressure servos 11 and 12

without providing the seal rings between, for example, the

input shaft 2 and the oil pressure servos 11 and 12.

Further, the extrement servo 13 can supply oil from the which some and supply oil from the boss unit 3a extended from the case 3, without passing through other parts for example, and therefore can supply oil by providing one set of seal rings 80. Therefore, oil supply can be supplied simply by providing one set of seal rings 81 and 82, 84 each for the oil pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, because the clutch C2 is configured on the inner circumforence side of the clutch C3, the clutch C3, bear which must transmit a relatively large torque in order to transmit the reduced rotation, can be configured on the outer circumference side, and this clutch C3 and the oil pressure servo 13 thereof can have an increased diameter. In pressure servo 13 can be enlarged, and the capacity capable of torque transmission of this clutch C3 can be increased.

By configuring the clutch C2 which can have a smaller capacity for torque transmission can be made more compact.

Further, the clutch C1 is a clutch which engages at the relatively slow to medium speed levels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is

released at the relatively high speed levels of fifth speed forward, sixth speed forward, or first speed reverse, sartfollarly the hub unit 22 that connects this clutch C1 and the sun gear S2 rotates at a relatively high revolution or revolves in reverse (see Fig. 3). On the other hand, the fifth speed forward or first speed reverse the rotates at transmitting member 30 reduces rotation speed, and at a sixth speed forward the transmitting member 30 may be fixed in some cases, and difference in revolu lutions between the hub may differ from that of unit 22 and the transmitting member 30, can occur. However, because this clutch C1 is located on the opposite side of first unit PU axially opposite PR the planetary gear unit PU, the second hub unit 22 and the transmitting member 30 can be conf to a Transmission apart from one another. In comparison with the case wherein, for example, these members are in contact due to a multiaxial configuration, decrease efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

Further, the automatic transmission device 1, according nint to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at n fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be

lowered, and this contributes to the quietness of the more quietly vehicle while running at a high speed.

New, the linking member (in particular the transmitting which canneds second unit first which canneds second unit first which canneds second unit for linking the planetary gear PR and the planetary gear unit PU requires rigidity to withstand the reduced speed torque that is input. For example, in the case of configuring a clutch that engages at a slow to medium speed and or a clutch that engages and disengages reduced rotations on the inner circumference side of the linking member the clutches must have a large capacity therefore an must have a large capacity therefore an must have appropriate diameter to correspond the vent that the finking member is the type that passes on the outer circumference side of this type of clutch, even a larger diameter than the aforement of those clutches becomes necessary and the diameter measurement of the linking

necessary diameter measurement of those clutches becomes necessary, and the diameter measurement of the linking member is enlarged more than necessary, and the automatic transmission as a whole becomes greater in the direction of the diameter. Therefore an object of the present embodiment is to reduce the enlargement of the diameter measurement and provide a compact automatic transmission.

According to the present embodiment, all clutches can enlargement of be configured without enlarging the diameter measurement of the linking member, by configuring a clutch C2 with a small capacity on the linking member, particularly on the inner.

circumference side of the transmitting member 30.

Now, the tenth embodiment which is a partial Row modification of the ninth embodiment will be described with reference to Fig. 16. Fig. 16 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the tenth embodiment. Now, Components of the tenth embodiment which are the same as those of the ninth embodiment will be denoted with the same reference numerals, and description will be here the for partial modifications.

As Fig. 16 illustrates, the automatic transmission

device 1₁₀ of the automatic transmission relating to the

tenth embodiment is a modification of the configuration of

second viil that of

the planetary gear VPR and the clutch C3 compared to that of

the automatic transmission device 1₉ of the automatic

transmission of the first embodiment (see Fig. 15).

The clutch C3 is configured on the opposite side of the proving planetary gear unit po (left side of diagram) of the first planetary gear PR within this automatic transmission device the first surface that the front edge of the drum shaped member 25 of this clutch C3 is splined to the friction plate 73 and the inner error meteric side of this friction plate 73 and the inner error meteric side of this friction plate 73 and the inner error meteric side of this friction plate 73 and the inner error meteric side of this friction plate 73 and the inner error which are shaped member 25 is connected to the input shaft 2, and the

hub unit 26 is connected to the sun gear S1. Further, the clutch C2 comprising a off pressure servo 12, of friction plate 72, a drum shaped member 23, and a hub unit 24, is configured on the inner circumference side of the above mentioned clutch C3, that is to say, is enclosed within the hub unit 26.

the other hand. On the outer circumference side of the planetary gear unit PU is configured a multi-disc brake B1 that comprises an oil pressure servo 14 and friction plate 74. The side plate of the carrier CR1 of this second planetary gear VPR is fixed and supported by the case 3. Further, the ring gear R1 is connected to the transmitting member 30, and the friction plate 74 of the brake B1 is splined with the outer circumference and of this which transmitting member 30, and this transmitting member 30 is connected to the sun gear S3.

The operations of the automatic transmission device 1₁₀, based on the above construction, are similar to those of the third embodiment (see Fig. 6 and Fig. 7) and accordingly not repeated here description thereof will be omitted.

As described above, according to the automatic

of the teath embodiment

transmission device 110 relating to the present invention,

yeard unit

due to the planetary gear PR and the clutch C2 being

configured on one side in the axial direction of the

located on the exial planetary gear unit PU, and the clutch C1 being configured

axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear -unit PU can be configured closely together, compared to the case wherein for example two clutches C1 and C2 are eonfigured between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for reduced rotation can be relatively shortened. In this manner By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia (force inertia) can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. compared to the case wherein three clutches C1, C2, C3 are located configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 93, 94) that supply the oil pressure servos 11, 12, and 13 of these clutches C1, C2, and the manufacturing process C3 can be/constructed easily, can be simplified and the costs brought down.

Further, since the off pressure servos 11 and 12 are located provided on the input shaft 2, one set of seal rings 81 and 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of the hydraulic servos 11 and 12 without providing the seal rings between, for example, the input shaft 2 and the oil pressure servos 11 and 12.

Further, the off pressure servo 13 can supply oil from the which boss unit 3b extended from the case 3, without passing through other parts for example, and therefore can supply can be connected oil by providing one set of seal rings 84. Therefore, oil can be supplied simply by providing one set of seal rings 81 and 82, 84 each for the off pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, the clutch Cl is a clutch which engages it the relatively slow to medium speed levels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is released at the relatively high speed levels of fifth speed forward, sixth speed forward, or first speed reverse, particular the hub unit 22 that connects this clutch C1, and the sun gear S2 rotates at a relatively high # or revolves in reverse (see Fig. 7). On the other hand, at the fifth speed forward or first speed reverse the transmitting member 30 reduces retation speed, and at a sixth speed forward the transmitting member 30 may be fixed in some cases, and difference in revolutions between the hub unit 22 and the transmitting member 30 can occur. However, because this clutch C1 is located on the epposite side of the planetary gear PR via the planetary gear unit Po, the second

hub unit 22 and the transmitting member 30 can be configured apart from one another. In comparison with the case wherein, for example, these members are in contact due to a multi-axial configuration, decreased efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

between the ring gear R1 and the sun gear S3, for example,

speed

the reduced rotation must be engaged and disengaged, and consequently

clutch C3 must be
becomes relatively large, but by placing between the input

shaft 2 and the sun gear S1, the engaging and disengaging of
the rotation of the input shaft 2 from this clutch C3 causes

the reduced rotation output from the ring gear R1 of the
planetary gear PR to be engaged and disengaged, and the
clutch C3 can be made more compact, and therefore the
automatic transmission can be made more compact.

Further, the automatic transmission device 110 according to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be appecified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be lowered, and this contributes to the quietness of the while running at a high speed.

:hat a clutch is conf between the planetary gear VPR and the planetary gear unit PU for example, the length of the linking member (particularly The transmitting members that links the planetary gear PR the axially elongated and the planetary gear unit PU becomes longer in direction, and since this linking member is for transmitting the reduced rotation, the thickness of the member must be increased so as to withstand this, and therefore the weight is Therefore an object of the present also increases. invention is to provide an automatic transmission that can shorten the distance between the speed reduction planetary gear and the planetary gear unit, and reduce the -weight.

tenth With the present embodiment, in particular, the clutch C2 is disposed on the opposite side in the axial direction of the planetary gear unit po from the planetary gear VPR, and therefore, providing a clutch between the planetary gear PR and the planetary gear unit PU is not necessary, and the length of the linking member, particularly the transmitting member 30 can be made that much shorter. Therefore, an increase in weight of the automatic transmission as a whole reduced can be prevented.

/ Eleventh Embodiment

New, the eleventh embodiment partial the changed from the ninth embodiment will be described with reference to Fig.

17. Fig. 17 is a schematic-cross-sectional diagram

illustrating the automatic transmission device of an

automatic transmission relating to the eleventh embodiment.

Now, Components of the eleventh embodiment which are the

same as those of the ninth embodiment will be denoted with

the same reference numerals, and description thereof omitted,

except for partial modifications.

As Fig. 17 illustrates, the automatic transmission

device 1₁₁ of the automatic transmission relating to the

lass ed

eleventh embodiment is a modification of the configuration

of the clutch C2, and further, configures a brake B3 instead

thereby

of a clutch C3, and enables the carrier CR1 of the planetary

gear PR to be fixed by the brake B3, compared to that of the

automatic transmission device 1₉ of the automatic

transmission of the ninth embodiment (see Fig. 15).

Within the automatic transmission device 111, the brake located meside second whit

B3 is configured on the planetary gear PR consider opposite (left side of the diagram) from the planetary gear unit PU.

This brake B3 comprises an oil pressure servo 16, of friction plate 76, and a hub unit 33. Further, the clutch C2, comprising an oil pressure servo 12, of friction plate 72, of drum shaped member 23, and a hub unit 24, is configured on the inner circumference side of above mentioned brake B3, that is to say, is enclosed within the hub unit 33. The hub unit 33 of this brake B3 is connected to the side plate of aneces.

Ache side of the carrier CR1, and the side plate of the other rotatably side of this carrier CR1 is supported by the input shaft 2 so as to be capable of rotating. Further, the sun gear S1 is connected to the input shaft 2 via the drum rotate member 23 of the clutch C2. Also, the friction plate 74 of the brake B1 is splined with the outer circumference aids of the ring gear R1, and this ring gear R1 is connected to the transmitting member 30, and is connected to the sun gear S3 via this transmitting member 30.

The operations of the automatic transmission device 1_{11} , of this eleventh embodiment based on the above construction, are similar to those of the fourth embodiment (see Fig. 9 and Fig. 10), and accordingly description thereof will be omitted.

As described above, according to the automatic transmission device 111 relating to the present invention, due to the planetary gear PR and the clutch C2 being configured on one side in the axial direction of the planetary gear unit PU, and the clutch C1 being configured on the other side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, vcompared to the case wherein, for example, two clutches C1 and C2 are configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for speed made transmitting reduced rotation can be relatively shortened.

By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertial force of inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced.

Further, since the oil pressure servos 11 and 12 are provided on the input shaft 2, the seal rings 81 and 82 seal the case 3 and supply of to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12 without providing the seal rings between, for example, the input shaft 2 and the oil pressure servos 11 and 12.

Therefore, oil can be supplied simply by providing the seal rings 81 and 82 each for the oil pressure servos 11 and 12, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, the clutch C1 is a clutch which engages at the relatively slow to medium speed levels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is released at the relatively high speed levels of fifth speed forward, sixth speed forward, or first speed reverse, particularly the hub unit 22 that connects this clutch C1 and the sun gear S2 rotates at a relatively high revolution

or retained in reverse (see Fig. 10). On the other hand, at the fifth speed forward or first speed reverse the transmitting member 30 reduced rotation speed, and at a sixth speed forward the transmitting member 30 may be fixed therefore therewill be a sixth speed forward the transmitting member 30 may be fixed in some cases, and difference in revelutions between the hub unit 22 and the transmitting member 30 can be ween. However, because this clutch C1 is located on the opposite side of the planetary gear PR via the planetary gear unit PU, the hub unit 22 and the transmitting member 30 can be configured apart from one another. In comparison with the case wherein, for example, these members are in contact due to a multi-axial configuration, decreased efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

planetary gear unit PU from the planetary gear PR is made to controlled be engaged and disengaged by the brake B3, the number of parts (for example drum-shaped members and so forth) can be reduced as compared to the case wherein, for example, a clutch C3 is provided. Further, the brake B3 can configure an oil line directly from the case 3, and therefore the configuration of the oil line can be simplified as compared to the case wherein, for example, a clutch C3 is provided.

Further, the automatic transmission device 1_{11} according this elevent to the present embodiment is a transmission device that is

directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be lowered, and this contributes to the quietness of the more quietly vehicle while running at a high speed.

between the event that a clutch is configured in second with the planetary gear VPR and the planetary gear unit PU for example, the length of the linking member (particularly with transmitting member) that links the planetary gear VPR and the planetary gear unit PU becomes longer in the axially claration, and since this linking member is for transmitting member the reduced rotation, the thickness of the member must be increased so as to withstand this, and therefore the weight also increased. Therefore an object of the present invention is to provide an automatic transmission that can shorten the distance between the speed reduction planetary gear and the planetary gear unit, and reduce the increase in weight.

With the present embodiment, in particular, the clutch

C2 is disposed on the opposite side in the axial direction relative to second

The planetary gear unit PU from the planetary gear PR,

and therefore, providing a clutch between the planetary gear unit. The planetary gear unit PU is not necessary, and the

length of the linking member, particularly the transmitting member 30 can be made that much shorter. Therefore, and increase in weight of the automatic transmission as a whole can be prevented.

ATwelfth Embodiment

Below, the twelfth embodiment, which is a partial modification of the first embodiment, will be described with reference to Fig. 18. Fig. 18 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the twelfth embodiment. Now, components of the twelfth embodiment which are the same as those of the first embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 18 illustrates, the automatic transmission device 1₁₂ of the automatic transmission relating to the has second unit twelfth embodiment configures the planetary gear PR, the clutch C3, and the brake B1 are configured by the opposite relative to

(left side in the drawing), sempared to that of the and in This respect

I Sters from the

V automatic transmission device 1, of the automatic

-transmission of the first embodiment (see Fig. 1).

Within the automatic transmission device 1₁₂, on the mounted above-mentioned input shaft 2 is configured a multi-disc clutch C2, which comprises an opt pressure servo 12,

clutch

friction plate 72, a drumashaped member 23 that forms a linked to a sun gear S2 on the radially inner circumference side.

The oil chamber of this oil pressure servo 12 is connected to an oil line 2a which is formed on the abovementioned input shaft 2, and this oil line 2a is provided along one edge of the case 3, and is connected to the oil line 91 of the boss unit 3a, which is provided on the input shaft 2 in a sleeve form. Further, this oil line 91 is connected to an oil pressure control unit, not illustrated.

In other words, because the above-mentioned oil pressure
servo 12 is configured on input shaft 2, an oil line from
the oil pressure control unit not illustrated, to the oil
chamber of the oil pressure servo 12 is configured, simply
by providing one set of seal rings 81 to seal between the
boss unit 3a of the case 3 and the input shaft 2.

The above mentioned input shaft 2 is connected to the clutch which has its above mentioned drum shafted member 23 and on the inner circumference side of this drum-shaped member 23 is configured the friction plate 72 of the clutch C2 which is capable of engaging by the oil pressure servo 12 for the clutch G2 splined, and is connected wherein the inner circumference side of the friction plate 72 of this clutch are intermeshed with friction plate 72 of this clutch which is splined to the hub unit 24 Further, this hub unit 24 which is connected to the above mentioned carrier CR2.

hand, on the other side of the input shaft 2 (left in diagram) is configured a multi-disc clutch C1 operated by a hydraulic and including has an oil pressure servo 11, of friction plate 571, a that forms a clutch drum, a hub unit Adjacent 22 linked to a sun gear S2. Of the outer circumference side is configured a multi-disc clutch C3 that comprises an oil and including dutch pressure servo 13, / friction plate 73, and a drum unit 25 radially outward that forms a clutch drum. Further, on the outer clutch side of the drum-shaped member 25 is _configured a multi-disc brake B1 that comprises _pressure servo 14 and a friction plate 74.

hydraulic

The oil chamber of this oil pressure connected to an oil line 2b which is formed in the abovementioned input shaft 2, and this oil line 2b is provided along the edge of the case 3 that is the opposite side of -that-of the above-mentioned boss unit 3a, and is connected formed 23 2 steeve around to the oil line 93 of the boss unit 3b which is provided Therefore, an oil line the input shaft 2 in a sleeve form. from the oil pressure control unit, not illustrated, to the oil chamber of the cil pressure servo 11 is constructed on the above mentioned oil pressure serve 11, simply by which form & providing one set of seal rings 82 to seal between the boss

unit 3b of the case 3 and the input shaft 2.

Lydraulic

Further, the oil chamber of the above mentioned oil

pressure servo 13 is connected to an oil line 94 of the

above mentioned boss unit 3b and connected to an oil pressure control unit, not illustrated. other words, for the above mentioned oil pressure servo communication between 13, and oil line from the oil pressure control unitariot and illustrated to the oil chamber of the oil pressure servo 13

which provide 2 is eonstructed, by one set of seal rings 84 to seal between clutch the boss anit 3b of the case 3 and the drum shaped member 25.

Further, the above-mentioned input shaft 2 is connected to the above-mentioned drum-shapped member 21 on the left, located radially outward side of the diagram, and on the inner sircumference side of Clutch this drum/shaped member 21 is configured the friction plate 71 of the clutch C1 which is capable of engaging by the sil pressure servo 11, for the clutch S1, splined, and is and are intermeshed with connected wherein the inner circumference side of the friction plate 71 of this clutch el is splined to the hub

which unit 22 Rurther, this hub unit 22 is connected to the

-above mentioned sun gear S2. supported by the above mentioned boss unit. 3b so as to retator and on the outer circumference side of the front portion therest is solined to the

is splined to The

edge of this drum-shaped-member 25 is configured the friction plate 74 of the brake Bl which is capable

Tetaining by the oil pressure servo 14 for the above

mentioned brake Bl. splined on the inner circumference portion cotch side of the front edge of this drum/shaped members 25 is

capable of engaging by the off pressure servo 13 for the clutch C3 which is capable of engaging by the off pressure servo 13 for the clutch C3, splined, and on the inner sircumference side of the friction plate 73 of this clutch C3 the ring gear R1 is splined.

Further, carrier CR1 has a pinion Pa and a pinion Pb, which and this pinion Pb meshes with the above mentioned ring gear R1, and this pinion Pa meshes with the sun gear S1 which is connected to the input shaft 2. This carrier CR1 is secured to the boss unit 3b of the case 3 via a side plate, and this rotately ring gear R1 is supported by a supporting unit 26 to the boss unit 3b, so as to rotate:

Further, to the above-mentioned drum shaped member 25 to one end of transmitting member 30 that transmits the rotation of the ring gear R1 when the clutch C3 is engaged, and further, to the other side of this transmitting member 30 is connected the sun gear S3 of the above-mentioned planetary gear unit PU.

The operations of the automatic transmission device 1_{12} , and 1_{12} , and 1_{12} , based on the above construction, are similar to those of the first embodiment (see Fig. 2 and Fig. 3), and accordingly that repeated here.

As described above, according to the automatic for the fixelf ambodiment, transmission device 1₁₂ relating to the present invention, because due to the planetary gear PR and the clutch C1 being

configured on one side in the axial planetary gear unit PU, and the clutch C2 being configured on the other side in the axial direction of the planetary units gear unit PU, the planetary gear VPR and the planetary gear -unit PU can be configured closely together, v compared to the case wherein for example, two clutches C1 and C2 are configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 30 for transmitting reduced rotation can be relatively shortened: By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia (force pinertia) can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case wherein three clutches C1, C2, C3 are configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 93, 94) that supply the hydraulic servos 11, 12, and 13 of these clutches C1, C2, can be constructed easily, and the manufacturing process can be reduced can be simplified and the costs brought down. Further, since the oil prossure servos 11 and 12 are

Further, since the oil pressure servos 11 and 12 are mounted provided on the input shaft 2, one set of seal rings 81 and provide a between 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12

without providing the seal rings between, for example, the input shaft 2 and the ca pressure servos 11 and 12. Further, the oil pressure servo 13 can supply oil from the boss which savextended from the case 3, V without passing through other parts for example, and therefore can supply can be supply simply by providing one set of seal rings 81 and 82, 84 each for the oil pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission Further, due to the clutch of being enfigured on the can be improved. inner circumference side of the clutch C3, the clutch C3, which must transmit a relatively large torque in order to specd transmit the reduced rotation can be configured on the outer circumferance side, and this clutch 63 and the oil 2nd its hydrzulie <u>pressure</u> servo 13 thereof can have an increased diameter, -Particularly the pressure area of the oil chamber of the oil pressure servo 13 can be enlarged, and the capacity capable of torque transmission of this clutch C3 can be increased.

Further, by providing

By configuring the clutch C1 which can have a smaller capacity for torque transmission compared to the clutch C3, the automatic transmission can be made more compact. because Further, the automatic transmission device 1_{12} according

to the present embodiment is a transmission device that is

directly coupled at fourth speed forward, Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle in the event that the vehicle is running at a high speed, the engine revolutions can be lowered, and this contributes to the quietness of the vehicle while runfing at a high speed.

MThirteenth Embodiment 4

modification of the twelfth embodiment, which is a partial modification of the twelfth embodiment, will be described with reference to Fig. 19. Fig. 19 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the thirteenth embodiment. Now, components of the thirteenth embodiment which are the same as those of the twelfth embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 19 illustrates, the automatic transmission

device 1₁₃ of the automatic transmission relating to the

thirteenth embodiment is a modification of the configuration

of the planetary gear PR, the clutch C1, and the clutch e1 modified

compared to that of the automatic transmission device 1₁₂ of

relative to the

the automatic transmission of the twelfth embodiment (see

Fig. 18).

In this thirthealth embodiment - 114 -

The clutch C1 and the clutch C3 is configured on the side of the second PR opposision Vplanetary gear unit Poside (left side of diagram) of the this automatic transmission device planetary gear PR within The inner circumference side of the front edge of the drum to haped member 25 of this clutch C3 is splined to the friction plate 73, and the inner excumference side of The drum# friction plate 70 is splined to the hub unit 26. shaped member 25 is connected to the input shaft 2, and the hub unit 26 is connected to the sun gear S1. Further, the hydraulic clutch C1 comprising a oil pressure servo 12, of friction plate 71, a drum / straped member, 21, and a hub unit 22 is located tadially inward circumference side of the above - mentioned clutch C3, that is to say, is enclosed within the hub unit 26.

On the other hand, on the outer circumference side of second unit the planetary gear PR is configured a multi-disc brake B1 that comprises an oil pressure servo 14 and a friction plate?

74. The side plate of the carrier CR1 of this planetary unit gear PR is fixed and supported by the case 3. Further, the ring gear R1 is connected to the transmitting member 30, and the friction plate 74 of the brake B1 is splined with the outer circumference side of this transmitting member 30, and which, in the outer circumference side of this transmitting member 30, and

this transmitting member 30 is connected to the sun gear \$3,

The operations of the automatic transmission device 1,3, based on the above construction, are similar to those of the

third embodiment (see Fig. 6 and Fig. 7) and accordingly not repeated here. description thereof will be omitted:

As described above, according to the automatic of the Thirth leenth embodiment transmission device 113 relating to the present invention, because second due to the planetary gear PR and the clutch Cl being 2/6 loca Ted -configured on one side in the axial direction of the JiFS is wested on the axially planetary gear unit PU, and the clutch C2 being apposite side Sirst direction of the planetary on the other UHÍTS gear unit PU, the planetary gear PR and the planetary 2 Transmission located more unit PU can be configured closely together, compared to the case wherein for example two clutches C1 and C2 are located configured in between the planetary gear PR and planetary -gear unit PU, and the transmitting member 30 for transmitting reduced rotation can be relatively shortered. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia (force inertial) can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case wherein three clutches C1, C2, C3 are SirsT locate& configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 93, 94) that supply the hydraulic in pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, and the manufacturing process can be reduced can be simplified and the costs brought down.

- 116 -

e servos 11 and 12 are Further, since the mounted -provided on the input shaft 2, one set of seal rings 81 and serve to input shaft 2 of 82 seal the case 3 and supply foil to the oil lines 2a and 2b provided within input shaft 2a and ther supplied to the oil chamber of oil pressure servos 11 and 12 without providing the seal rings between, for example, the input shaft 2 and the oil pressure servos 11 and 12. Further, the oil pressure servo 13 can supply oil from the boss unit 3b extended from the case 3, without passing components through other parts for example, and therefore can supply by providing one set of seal rings 84. can be supplied simply by providing one set of seal rings 81 and 82, 84 each for the off pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, because the clutch C1 is configured on the immer circumference side of the clutch C3, the clutch C3, which must transmit a relatively large torque in order to transmit the reduced rotation, can be configured on the outer circumference side, and this clutch C3 and the oil pressure servo 13 thereof can have an increased diameter.

In particular the pressure area of the oil chamber of the oil pressure servo 13 can be enlarged, and the capacity capable capacity.

If torque transmission of these clutch C3 can be increased.

Further, by designing

By configuring the clutch C1 which can have a smaller

capacity for torque transmission compared to the clutch C3,

the automatic transmission can be made more compact.

the automatic transmission can be made more compact.

In contrast

the ring gear R1 and the sun gear S3, the reduced rotation

for would must be engaged and disengaged, and becomes relatively large,

the engaging and disengaging of the rotation of the input shaft 2 and the sun gear S1, speed shaft 2 from this clutch C3 causes the reduced rotation output from the ring gear R1 of the planetary gear PR to be engaged and disengaged, and the clutch C3 can be made more as a whole compact, and therefore the automatic transmission can be

made more compact.

Further, the automatic transmission device 1₁₃ according to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be lowered, and this contemporate to the quietness of the vehicle while running at a high speed.

Now, in the event that a clutch is configured in Units

between the planetary gear PR and the planetary gear unit PU

for example, the length of the linking member (particularly

and the planetary gear unit PU becomes longer in the axially classified

the reduced rotation, the thickness of the member must be the high target increased so as to withstand this, and therefore the weight is also increased. Therefore an object of the present invention is to provide an automatic transmission that can shorten the distance between the open reduction planetary gear and the planetary gear unit, and reduce the increase in weight.

With the present embodiment, in particular, the clutch

C1 is disposed on the opposite side in the axial direction of the planetary gear unit portron the planetary geary providing a clutch between the planetary gear unit.

PR and the planetary gear unit PU is not necessary, and the length of the linking member, particularly the transmitting member 30 can be made that much shorter. Therefore, an increase in weight of the automatic transmission as a whole avoided can be prevented.

Below, the fourteenth embodiment, which is a partial now modification of the twelfth embodiment will be described with reference to Fig. 20. Fig. 20 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the

embodiment which are the same as those of the twelfth embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 20 illustrates, the automatic transmission of the 1₁₄ of the automatic transmission relating to the differs from that the two fit embodiment in fourteenth embodiment is a modification of the configuration of the clutch C2, and further, configures a brake B3 instead of a clutch C3, and enables the carrier CR1 of the planetary gear PR to be fixed by the brake B3, compared to that of the automatic transmission device 1₁₂ of the automatic

transmission of the twelfth embodiment (see Fig. 18).

Within the automatic transmission derice 114, the brake 10c2Ted 3ide of the 114 professore on the planetary gear PR, on the opposite (left side on the diagram) from the planetary gear unit PU.

This brake B3 comprises an oil pressure servo 16, a friction plate 76, and a hub unit 33. Further, the clutch Classociated comprising an oil pressure servo 11, a friction plate 71, a serve drum shaped member 21, and a hub unit 22, vis configured on the inner circumference side of above mentioned brake B3, that is to say, is enclosed within the hub unit 33. The hub unit 33 of this brake B3 is connected to the side plate of one side of the carrier CR1, and the side plate of the other side of this carrier CR1 is supported by the input shaft 2.

is connected to the input shaft 2 via the drum shaped member 21 of the clutch C1. Also, the friction plate 74 of the brake B1 is splined with the outer circumference side of the ring gear R1, and this ring gear R1 is connected to the transmitting member 30, and is connected to the sun gear S3 via this transmitting member 30.

The operations of the automatic transmission plents 114 for the state of the based on the above construction, are similar to those of the fourth embodiment (see Fig. 9 and Fig. 10), and accordingly not repeated here description thereof will be omitted.

As described above, according to the automatic transmission device 114 relating to the present invention, due to the planetary gear PR and the clutch C1 being configured on one side in the axial direction of the planetary gear unit PU, and the clutch C2 being configured on the other side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together compared to the configured closely together compared to the configured in between the planetary gear PR and planetary gear units PU, and the transmitting member 30 for made transmitting reduced rotation can be relatively shortened.

In this manner By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia

the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, a transmission compared to the ease wherein three clutches C1, C2, C3 are located configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 93) that supply the oil to the hydraulic prosesure servos 11 and 12, of these clutches C1V C2, can be more constructed easily, and the manufacturing process can be simplified and the costs brought down.

Further, since the off pressure servos 11 and 12 are provided on the input shaft 2, the seal rings 81 and 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12 without providing the seal rings between, for example, the input shaft 2 and the oil pressure servos 11 and 12.

Therefore, voil can be supplied simply by providing the seal rings 81 and 82 each for the off pressure servos 11 and 12, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, since the reduced rotation output to the first planetary gear unit PU from the planetary gear PR is made to be engaged and disengaged by the brake B3, the number of parts (for example drum for the planetary gear) can be

reduced as compared to the case wherein, for example, a clutch C3 is provided. Further, the brake B3 can configure an oil line directly from the case 3, and therefore the configuration of the oil line can be simplified as compared to the case wherein, for example, a clutch C3 is provided.

Further, the automatic transmission applies 114 according to the present embodiment is a bransmission device that is directly coupled at fourth speed forward. Therefore, at in fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be the rest of the more quietly vehicle while running value in the quietness of the vehicle while running value in the speed.

Now, in the event that a clutch is configured in units between the planetary gear PR and the planetary gear unit PU for example, the length of the linking member (particularly units) the transmitting member that links the planetary gear PR and the planetary gear unit PU becomes longer in the axially clanated because direction, and since this linking member to for transmitting the reduced rotation, the thickness of the member must be increased so as to withstand this, and therefore the weight must be also increased. Therefore an object of the present invention is to provide an automatic transmission that can reduce shorten the distance between the speed reduction planetary units PV and PR,

gear and the planetary gear unit, and reduce the increase in weight of the Transmitting member

With the present embodiment, in particular, the clutch

C1 is disposed on the epposite side in the axial direction second PR apposite first unit PU of the planetary gear unit PU from the planetary gear PR, and therefore, providing a clutch between the planetary gear units

PR and the planetary gear unit PU is not necessary, and the length of the linking member, particularly the transmitting member 30 can be made that much shorter. Therefore, are increase in weight of the automatic transmission as a whole reduced can be prevented.

Fifteenth Embodiment

modification of the first through fourteenth embodiments

now
will be described, with reference to Fig. 21 through Fig. 23.

Fig. 21 is a schematic cross-sectional diagram illustrating
the automatic transmission device of an automatic
transmission relating to the fifteenth embodiment, Fig. 22

is an operational table of an automatic transmission
relating to the fifteenth embodiment, and Fig. 23 is a speed
line diagram of an automatic transmission relating to the
fifteenth embodiment. Now, components of the fifteenth
embodiment which are the same as those of the first
embodiment will be denoted with the same reference numerals,

will not be repeated here
and description thereof omitted, except for partial

modifications.

He

As illustrated in Fig. 21, and automatic transmission device 115 of an automatic transmission relating to the fifteenth embodiment comprises a planetary gear unit PU and a planetary gear PR on the input shaft 2, similar to that ar automatic transmission device 11 of an automatic transmission relating to the first embodiment. planetary gear unit PU comprises a first simple planetary gear VSP2 and a second simple planetary SP3, and is a Simpson-type planetary gear comprising a sun gear S2 and a sun gear S3 that are linked together, a carrier CR3 and a ring gear R2 that are linked together, a ring gear R3, and a carrier CR2, as the four rotation components. Further, the second unit mentioned planetary gear PR is a double pinion planetary gear comprising a carrier CR1, wherein a pinion ${\tt P1b}^{\sf V}$ is meshed with a ring gear R1 and a pinion ${\tt P1a}^{\sf V}$ is meshed wherein the pinions with a sun gear S1, which are meshed with one another. 2/50

on the above mentioned input shaft 2 is configured a multi-disc clutch C1, which comprises an oil pressure servo clutch

11, of friction plate 71, a drum shaped member 121 that forms

a clutch drum, and a hub unit 122. The oil chamber of this hadraulic
oil pressure servo 11 is connected to an oil line 91 of the forms a sleeve around one end of boss unit 3a which is provided on the input shaft 2 in a sleeve form and is provided along one edge of the case 3, and this oil line 91 is connected to an oil pressure control

unit, not illustrated. In other words, an oil line from the oil pressure control unit, not illustrated, to the oil connected chamber of the oil pressure servo 11 is configured, simply which form a by providing one set of seal rings 81 pp seal between the boss wast 3a of the ease 3 and the drum phaped member 121.

The above mentioned input shaft 2 is connected to the clutch above mentioned drum shaped member 121, and of the inner surface circumference side of this drum shaped member 121 is splined configured the friction plate 71 of the clutch C1 which is intermested capable of engaging by the oil pressure servo 11 for the clutch C1, splined, and is connected wherein the inner circumference side of the friction plate 11 of this clutch which is for the splined to the hub unit 122 per this shub unit is connected to the above mentioned sun gear S2.

on the other hand, on the other side (the left of the diagram) of the input shaft 2 is configured a multi-disc clutch C2 which comprises an oil pressure servo 12, description plate 72, a drum-shaped members 123 that forms a clutch drum, and a hub unit 124 liked to a carrier CR3. On the outer circumference side, a multi-disc clutch C3 decentification plate 73, a drum-shaped member 125 that forms a clutch drum. Further, on the outer circumference side of clutch drum. Further, on the outer circumference side of the drum-shaped member 125 is configured a multi-disc brake a hydraulic.

B1 which comprises an oil pressure servo 14 and for iction

plate 574.

The oil chamber of this oil pressure servo 12 is connected to an oil line 2b which is formed on the above mentioned input shaft 2, and this oil line 2b is provided along the edge of the case 3 that is the opposite side of that of the above-mentioned boss unit 3a, and is connected to the oil line 93 of the boss unit 3b which is provided on the input shaft 2 in a sleeve form. Therefore, an oil line from the oil pressure control unit, not illustrated, to the oil chamber of the oil pressure servo 12, is constructed on the above mentioned oil pressure servo 12, simply by providing one set of seal rings 82 to seal between the input shaft 2 and the drum/shaped member 23.

Further, the oil chamber of the above mentioned oil

pressure servo 13 is connected to an oil line 94 of the
above mentioned boss unit 3b, and this oil line 94 is
connected to an oil pressure control unit, not illustrated
In other words, for the above-mentioned oil pressure servo

13, an oil line from the oil pressure control unit, not
iffustrated, to the oil chamber of the oil pressure servo 13
is constructed by one set of seal rings 84 to seat between
the boss unit 3b of the case 3 and the drum shaped member

Further, the above mentioned input shaft 2 is connected to the above mentioned drum-shaped member 123 on the left

side of the diagram, and of the inner erroumference side of

splined to
this drum-shaped member 123 is configured the friction plate 5

72 of the clutch C2 which is capable of engaging by the oil
hutraulic
pressure servo 12 for the clutch C2 optimed, and is

re intermeshed will friction plates

The friction plates 72 of this clutch C2 is splined to the hub

unit 124, Further, this hub unit 124 is connected to the

above mentioned carrier CR3.

The clutch

Further, the above mentioned drum shaped member 125 is

v supported by the above mentioned boss unit 3b so as to

rotate, and in the outer circumforence side of the front clutch splined to edge of this drum; shaped member 125 is configured the friction plates 74 of the brake Bl which is capable of

retaining by the oil pressure servo 14 for the above—

mentioned brake B1, splined. On the inner sircumference partian

side of the front edge of the drumpshaped member 125 is splined to configured the friction plate 73 of the clutch C3 which is aperated capable of engaging by the oil pressure servo 13 for the

clutch C3, splined, and on the inner circumference side of to are intermested with friction plates splined to the friction plates 73 of this clutch C3 the ring gear R1, is

Further, the carrier CR1 comprises a pinion Pla and a pinion Plb, and this pinion Plb meshes with the above mentioned ring gear R1, and this pinion Pa meshes with the sun gear S1 which is connected to the input shaft 2.

Carrier CR1 is secured to the boss unit 3b of the case 3 via rotatebly a side plate, and this ring gear R1 is supported by a supporting unit 126 to the boss unit 3b, so as to rotate.

is connected a linking member 130 that transmitts the rotation of the ring gear R1 when the clutch C3 is engaged, and further, the other eide of this transmitting member 130 is connected the ring gear R3 of the second simple planetary gear SP3 of the above mentioned planetary gear unit PU.

On the other hand, on the outer circumference side of the first simple planetary gear SP2 is configured a one-way clutch F1, and the inner race of this one-way clutch F1 is connected to the hub unit 128 which is connected to the ring gear R2 of the first simple planetary gear SP1. Further, on the outer circumference side of this ring gear R2 is configured a brake B2 comprising an cit prossure servo 15, and friction plate 75. The inner circumference side of this friction plate 75 is splined to the ring gear R2 and the hub unit 128, and also the outer circumference side of surface side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined to the inner circumference side of surface friction plate 75 is splined friction plate 75

Further, the carrier CR3 which has a pinion P3

supported by the side plate is meshed with the inner

SUPSACE umforence side of the above mentioned ring gear R3 🕶 this pinion P3, and this carrier CR3 is meshed with the The carrier CR3 is above mentioned sun gear S3 via this pinion P3, and also the linked to the ring gear R2. Further, the carrier CR2 which SUPPONTS which -has a pinion P2 supported by the side plate is meshed with the inner eircumference side of the above mentioned ring gear R2 via this pinion P2, and this carrier CR2 moshes with and with tioned sun gear S2 via this pinion P2. Also, this carrier CR2 is linked to the counter gear 5 via this As described above, the planetary gear PR and the side plate 127. clutch C3 are configured on one side in the axial direction of the planetary gear unit PU, and also the clutch C2 is -configured on one side in the axial direction, and the clutch C1 is configured on the other direction, and the counter gear 5 is configured in the axially Side opposite direction (right side of the diagram) of the first planetary gear unit PU of the planetary gear PR. Further, the clutch C2 is disposed on the inner, circum of the clutch C3, and particularly of igularly of the transmitting member 130 that transmits the output thereof. Further, the brake B1 is configured on the outer circumference side of the planetary gear PR, and the brake B2 is configured or radially outward first outer circumference side of the planetary gear unit PU.

Continuing, based on the above mentioned construction,

of this fifteenth embodiment

The operations of an automatic transmission device 1,5 will now be described with reference to Fig. 21, Fig. 22, and Fig. 23 below. Now, the vertical axis of the speed line diagram illustrated in Fig. 23 indicate the revolutions of each rotation component, and the horizontal axis indicates the corresponding gear ratio of the rotation components. First regarding the planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 23) corresponds to ring gear R3, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R2 and the carrier CR3, the carrier CR2, and the sun gear S2 and the sun gear S3. planetary gear YPR section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 23) corresponds to sun gear S1, and hereafter moving to the left direction within the diagram, the vertical axis correspond to the ring gear R1 and the carrier CR1. Further, the width between these vertical axes are proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the inverse number of teeth of each of the ring gears R1, R3. Also, tin the horizonta Λ direction in the diagram illustrate that the rotation is transmitted from the transmitting member 130.

As illustrated in Fig. 21, the rotation of input shaft

2 is input to the above mentioned sun gear S2 and sun gear

S3, by engaging the clutch C1. The rotation of input shaft

also

2 is input to the above mentioned carrier CR3 and ring gear

R2, by engaging the clutch C2, and this carrier CR3 and ring

gear R2 can fix the rotation by the retaining of brake B2

and further, the rotation in one direction is regulated by

the one-way clutch F1.

on the other hand, the rotation of the input shaft 2 is input to the above mentioned sun gear S1, and the rotation of the above mentioned carrier CR1 is fixed to the case 3, and the above mentioned ring gear R1 rotates with reduced peccle rotations based on the rotation of the input shaft 2 which is input to this sun gear S1 via this carrier CR1. The reduced rotation of the ring gear R1 is input to the above mentioned ring gear R3 via the transmitting member 1301 by engaging the clutch C3. Further, the retation of the sagainst rotation of the sagainst rotation with the brake B1.

Also, The rotation of the above mentioned carrier CR2 is output to the above mentioned counter gear 5, and is output to the drive wheel via this counter gear 5, a counter shaft unit (not illustrated), and a differential unit.

rotation of input shaft 2 is input to the sun gear S2 and the sun gear S3 via the clutch C1, and the rotation of the carrier CR3 and the ring gear R2 is regulated in one direction (the forward rotation direction), in other words, the ring gear R2 is prevent from rotating in the opposite direction and is fixed. Further, the rotation of the input shaft 2 that is input to the sun gear S2 and the reduced precontation is output to the carrier CR2 via the fixed ring gear R2, and the forward rotation for first speed forward is output from the counter gear 5.

reduced rotation is output to the ring gear R3 via the sun which receives
gear S1 wherein the rotation of the input shaft 2 is input,
and the fixed carrier CR1, however, the transmitting member
130 in particular does not transmit torque; because the
clutch C3 is released. Further, when downshifting (when
coasting), the brake B2 is retained and the ring gear R2 is
fixed and the above mentioned state of first speed forward
is maintained while preventing the forward rotation of this
ring gear R2.

Further, in this first speed forward, the one-way clutch F1 prevents the ring gear R2 from rotation in the opposite direction and allows forward rotation, and therefore, switching from a non-driving range to a driving range and achieving the first speed forward can be

accomplished more smoothly by the automatic engaging of the one-way clutch.

illustrated in Fig. 22, the clutch C1 brake B1 are engaged.

Then, as illustrated in Fig. 23, the rotation of input shaft 2 is input to the sun gear S2 and the arm gear S3 via the clutch C1, and the rotations of the ring gear R3 are fixed.

Also, reduced rotation is output to the carrier CR3 and the ring gear R2 via the rotation of the input shaft 2 that is input to the sun gear S3 and the fixed ring gear R3.

The reduced rotation greater than that of the above-mentioned first speed forward is input to the carrier CR2, via the rotation of the input shaft 2 input to the sun gear S2 and the reduced rotation input to the sun gear S2 and the reduced rotation input to the sun gear R2, and the forward rotation for second speed forward is output from the counter gear 5.

Now, At this time, within the planetary gear PR, the reduced rotation is output to the ring gear R3 via the sun which receives gear S1 wherein the rotation of the input shaft 2 is input, and the fixed carrier CR1 however, the transmitting member 130 imparticular does not transmit torques because the clutch C3 is released.

At third speed forward within the D (drive) range, as illustrated in Fig. 22, the clutch C1 and the elutch C3 are engaged. Then, as illustrated in Fig. 23, the rotation of

input shaft 2 is input to the sun gear Sl and the ring gear speed from the fixed carrier CR1. The ring gear RI, now rotating as a outputs its reduced speech en speed reta speed reduct ut to the ring gear R3 via the transmitting member 130, from the clutch C3 engaging. a | 90 The rotation of the input shaft 2 is input to the sun gear speed S2, and a slightly greater reduced rotation is output to the carrier CR3 and the ring gear R2 from the rotation of the input shaft 2 input to this sun gear S3 and the reduced speed rotation of the ring gear R3. A reduced rotation greater than that of the above-mentioned second speed forward is output to the carrier CR2 from the rotation of the input shaft 2 input to the sun gear S2 and the slightly greater ω reduced rotation input to this ring gear R2, and the forward rotation for third speed forward is output from the counter In this case, because the ring gear R1 and the ring gear R3 are at a reduced retation, the above mentioned CBFFIES transmitting member 130 performs a relatively large torque. transmission.

It fourth speed forward within D (drive) range, as illustrated in Fig. 22, the clutch C1 and the clutch C2 are engaged. Then, as illustrated in Fig. 23, the rotation of input shaft 2 is input to the sun gear S2 and the sun gear S3 via the clutch C1, and pato the carrier CR3 and the ring gear R2 via the clutch C2 Therefore, by the rotation of

of input shaft 2 input to the sun gear S2 and the rotation of input shaft 2 input to the ring gear R2, in other words, in the state of directly coupled rotation, the rotation of the input shaft 2 is output as is into the carrier CR2, and the forward rotation for fourth speed forward is output from the counter gear 5. New, At this time, within the planetary unit speed gear PR, the reduced rotation is output to the ring gear R3 via the sun gear S1 which receives via the sun gear S1 wherein the rotation of the input shaft 2 is input, and the fixed carrier dR1, nowever, the transmitting member 130 imparticular does not transmit torque; because the clutch C3 is released.

the fifth speed forward within the D (drive) range, as illustrated in Fig. 22, the clutch C1 and the clutch C3 are engaged. Then, as illustrated in Fig. 23, the rotation of input shaft 2 is input to the sun gear S1, and the ring of rotation received through the gear R1 reduces rotation speed from the fixed carrier CR1. Further, the speed reduction speed rotation of this ring gear R1 is output to the ring gear R3 via the transmitting member 130, from the clutch C3 engagen The rotation of the input shaft 2 is \forall input to the carrier CR3 and the ring gear R2, and for overdrive rotation is output to the sun gear So and the sun gear S3 from the rotation of the input shaft 2 input to this reduced rotations of the ring gear R3. ${\mathscr B}$ verdrive rotation is ${}^{oldsymbol{\mathsf{v}}}$ output to the carrier CR2 from the

rotation of the input shaft 2 input to the ring gear R2 and the overdrive rotation input to this sun gear S2, and the forward rotation for fifth speed forward is output from the counter gear 5. In this case, because the ring gear R1 and rotation, the above the ring gear R3 are at a reduced rotation, the above mentioned transmitting member 130 performs a relatively large torque transmission.

At sixth speed forward within the D (drive) range, as illustrated in Fig. 22, the clutch C2 is engaged and the brake Bl is retained. Then, as illustrated in Fig. 23, the rotation of the input shaft 2 is input to the carrier CR3 and $^{\prime}$ the ring gear R2 via the clutch C2, and $^{\prime}$ the ring gear R3 is fixed by retaining the brake B1. This causes an overdrive rotation (even greater than that of the abovementioned fifth speed forward), from the rotation of the input shaft 2 input to the Carrier CR3 and the fixed ring which gear R3, and is output to the sun gear S3 and the sun year From the rotation of the input shaft 2 input to the ring gear R2 and the increased rotation speed input to this sun gear S2, a greater speed rotation than that of the raised above-mentioned fifth speed forward, is output, and the Forward rotation for sixth speed forward instituted from the counter gear 5. Nows At this time, within the planetary opeed gear ^{V}PR , the reduced ^{V}V rotation is output to the ring gear R3 (which receives via the sun gear S1 wherein the rotation of the input shaft

2) in improf and the fixed carrier CR1, however, the transmitting member 130 in particular does not transmit torque, because the clutch C3 is released.

At first speed reverse within an R (reverse) range, as illustrated in Fig. 22, the clutch C3 is engaged and the brake B2 is retained. Then, as illustrated in Fig. 23, the rotation of the input shaft 2 is input to the sun gear S1, and the ring gear R1 rotates at reduced rotations fixed carrier CR1. Further, because the clutch C3 is engaged, the reduced rotation of the ring gear R1 is input to the ring gear R2 via the above mentioned transmitting hand, because the brake B2 is member 130. engaged retained, the retation of the carrier CR3 and the ring gear are against rotation.

R2 is fixed, and a reverse rotation is output to the sun gear S3 and the sun gear S3 because of the fixed carrier CR3 and the reduced rotation of the ring gear R3. everse rotation is output to the carrier CR2 from ring gear R2 and the reverse rotation input to this sun gear S2, and the forward rotation for first speed reverse is output from the counter gear 5. Now, In this case, similar of the above-mentioned third speed forward of fifth speed forward, the ring gear R1 and the ring gear R3 are rotating with reduced speed rotations and accordingly, the -above-mentioned transmitting member 130 performs a relatively large torque transmission.

At the P (parking) range and The N (neutral) range, the clutch C1, clutch C2; and clutch C3 are released in particular, the transmission movement between the input shaft 2 and the counter gear 5 is disconnected, and the automatic transmission device 1₁₅ as a whole is in an idle state (neutral state).

As described above, according to the automatic 05 this fifthteenth embodiment transmission device 115 relating to the planetary gear PR and the clutch C2 being located -configured on one side in the axial direction of the firs? planetary gear unit PU, and the clutch C1 being axially opposite Wher side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear located more unit PU can be configured closely together, compared to the transmission ease wherein for example two clutches C1 and C2 are located units configuration between the planetary gear PR and planetary gear unit PU, and the transmitting member 130 for transmitting reduced rotation can be relatively shorte ed. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia force inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. compared to the case wherein three clutches C1, C2, C3 are JocaTed configured on one side of the planetary gear unit PU, the

oil lines (for example, 2a, 2b, 91, 93, 94) that supply the hydraulic oil pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, and the manufacturing process can be simplified and the costs brought down.

Because the oil pressure servos 11 and 12 are provided on the input shaft 2, one set of seal rings 81 and form a connection to 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be hydraulic supplied to the oil chamber of re servos 11 and 12 without providing seal rings between, for example, the input shaft 2 and the oil sure servos 11 and 12. Further, off receive of directly hydravic pressure servo 13 can supply oil from the boss and 3b provided from the case 3, without passing through for example other units, in other words, can supply oil by providing one set of seal rings 84. Therefore, oil can be supplied simply by providing one set of seal rings 81 and 82, hydraulic Dressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, because the clutch C2 is configured on the inverse side of the clutch C3, the clutch C3, which must transmit a relatively large torque in order to speed and its transmit the reduced rotation, can be configured on the outer sireumference side, and this clutch C3 and the oil

Avoltavic

proscure servo 13 thereof can have an increased diameter.

In particularity the pressure area of the oil chamber of the oil

hydravic

pressure servo 13 can be enlarged, and the separaty sepable

capacity

of torque transmission of this clutch C3 can be increased.

By configuring the clutch C2 on the inner circumference side,

which can have a smaller capacity for torque transmission

and therefore

compared to the clutch C3, the automatic transmission can be

made more compact.

Further, the clutch Cl is a clutch which engages at the relatively slow to medium speed levels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is released at the relatively high speed deve s~o£ fifth speed forward, sixth speed forward, or first speed reverse, particularly the hub unit 122 that connects this clutch C1 and the sun gear S2 rotates at a relatively high re or revelves in reverse (see Fig. 3). On fifth speed forward of first speed reverse the roTates at a transmitting member 130 reduced solution speed, and sixth speed forward the transmitting member 130 may be fixed in some cases, and diffe unit 122 and the transmitting member 130 can because this clutch C1 is located on the expecite side of Unit PU exially opposite the second the planetary gear PR via the planetary gear unit Po, the hub unit 122 and the transmitting member 130 can be

configured apart from one another. In comparison with the case wherein, for example, these members are in contact due to a multi-axial configuration, decreased efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

Further, the automatic transmission device 115 according this Sistificant to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is speed running at a high speed, the engine revolutions can be reduced thereby allowing lowered, and this contributes to the quietness of the vehicle white running at a high speed.

Now, the linking member (in particular the transmitting woils member) for linking the planetary gear PR and the planetary gear unit PU requires rigidity to withstand the reduced speed torque that is input. For example, in the case of configuring A clutch that engages at a slow to medium speed or a clutch that engages and disengages reduced rotation on the inner circumference side of the linking member the clutches must have a large capacity, therefore an appropriate diameter to correspond with this capacity becomes necessary. Therefore, in the event that the linking member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and member is the type that passes on the outer circumference and members are the type that passes on the outer circumference and the type that the type

side of this type of clutch, even plarger diameter than the necessary diameter measurement of those clutches becomes necessary, and the diameter measurement of the linking member is enlarged more than necessary, and the automatic transmission as a whole becomes greater in the direction of the diameter. Therefore an object of the present embodiment is to reduce the enlargement of the diameter measurement, mare and provide a compact automatic transmission.

According to the present embodiment, all clutches can be configured without enlarging the diameter measurement of localing the linking member, by configuring a clutch C2 with a small capacity on the linking member, particularly on the inner circumference side of the transmitting member 130.

Wasixteenth Embodiment#

modification of the fifteenth embodiment, which is a partial modification of the fifteenth embodiment, will be described with reference to Fig. 24 through 126. Fig. 24 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the sixteenth embodiment, Fig. 25 is an operational table of an automatic transmission relating to the sixteenth embodiment, and Fig. 26 is a speed line diagram of an automatic transmission relating to the sixteenth embodiment. Now, components of the sixteenth embodiment which are the same as those of the fifteenth embodiment will be denoted

with the same reference numerals, and description thereof will not be repeated modifications.

As illustrated in Fig. 24, an automatic transmission device 116 of an automatic transmission relating to the differs with regard to sixteenth embodiment is a modification of the configuration of the planetary gear VPR and the clutch C3, Compared to that of a automatic transmission device 1_{15} of an automatic relating to the fifteenth embodiment (see Fig. 21) In this sixTeenth embodiatent the clutch C3 is configured on the planetary gear unit PU side (left side of diagram) of the planetary gear PR • transmission device 116 ence side of the front edge of the drum/shaped member 125 of this clutch C3 is splined to the friction plate 73, which are intermeshed with plate 73, and the inner sircumference side of this friction plate splined to the hub unit 126. The drum spaced Vincember 125 is connected to the input shaft 2, and the hub unit 126 is connected to the sun gear S1. Further, the includes hydravice clutch C2 comprising a cit pressure servo 12, of friction plate 72, a drum Ashaped member 123, and a hub unit 124 located radially inward rence side of the abovementioned clutch C3 that is to say, is enclosed within the hub unit 126. on the other hand, On the vouter circumference side of

On the other hand, On the Vouter circumference side of the planetary gear PR is configured a multi-disc brake B1 second unit

are intermeshed with Striction plates

that comprises an off pressure servo 14 and a friction plates

74. The side plate of the carrier CR1 of this planetary

paint

gear PR is fixed and supported by the case 3. Further, the

ring gear R1 is connected to the transmitting member 130,

and the friction plate 74 of the brake B1 is splined with

the outer circumference side of this transmitting member 130 which

and this transmitting member 130 is connected to the ring

gear R3.

Continuing, based on the above mentioned construction, The operations of an automatic transmission devices 116 will now be described with reference to Fig. 24, Fig. 25, and Fig. 26 below. New As with the above-mentioned first embodiment, the vertical axis of the speed line diagram illustrated in rotary

Fig. 26 indicates the revolutions of each rotation component, and the horizontal axis indicates the corresponding gear ratio of these rotation components. Further, regarding the planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 26) corresponds to ring gear R3, and hereafter moving to the left direction within the diagram, the vertical axis correspond to the ring gear R2 and the carrier CR3, the carrier CR2, and the sun gear S2 and the sun gear S3. Further, regarding the planetary gear PR section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 26)

corresponds to sun gear S1, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R1 and the carrier CR1. Further, the width inversely between these vertical axes are proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the inverse of the number of teeth of each of the ring gears R1, R3. Also, the dotted line in the horizontal direction in the diagram illustrate that the rotation is transmitted from the transmitting member 130.

As illustrated in Fig. 24, by engaging the clutch C3, the rotation of the input shaft 2 is input to the sun gear S1. Further, the rotation of the above mentioned carrier CR1 is fixed to the case 3, and the above mentioned ring gear R1 rotates at reduced rotations based on the rotation of the input shaft 2 input to this sun gear S1. In other words, by engaging the clutch C3, the reduced rotation of the ring gear R1 is input to the ring gear R3 via the transmitting member 130.

planetary gear PR, at third speed forward, fifth speed
forward, and first speed reverse, the rotation of the input
shaft 2 is input to the sun gear S1 by engaging the clutch
C3, the reduced rotation is output to the ring gear R3 from
the fixed carrier CR1, and the reduced rotation is input to
the ring gear R3 via the transmitting member 130. At this

transmitting member 130 performs a relatively large torque.

transmitting member 130 performs a relatively large torque.

transmission. On the other hand, at first speed forward,
second speed forward, fourth speed forward, and sixth speed
forward, the rotation of the ring gear R3 is input to the
ring gear R1 via the transmitting member 130, and further,
because clutch C3 is released, as illustrated in Fig. 7, the
in accordance with the
sun gear S1 rotates based on each different speed lessed of

New the actions of the planetary gear are similar to those of the above mentioned fifteenth embodiment (see Fig. 22 and Fig. 23), and accordingly description thereof will be omitted.

gear unit PU, and the transmitting member 130

to the automatic of this sixteenth embodiment transmission device 116 relating because second to the planetary gear PR and the clutch C2 being located configured on one side finthe axial direction of the is located planetary gear unit PU, and the clutch C1 being opposite side SirsT irrection of the planetary the axial/d units gear unit PU, the planetary gear VPR and the planetary transmission located more unit PU can be configured closely together, compared to the -case wherein for example, two clutches C1 and C2 are ocaled on 13 configured in between the planetary gear PR and planetary

transmitting reduced rotation can be relatively shortened.

By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia force of inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the ease wherein three clutches C1, C2, C3 are located sonfigured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 93, 94) that supply the hydraulic off pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, and the manufacturing process can be simplified and the costs brought down.

Further, since the ordersure servos 11 and 12 are mounted provided on the input shaft 2, one set of seal rings 81 and to the input shaft 2 for 82 seal the case 3 $^{\prime}$ supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be hydraulic supplied to the oil chamber of oil pressure servos 11 and 12 without providing be seal rings between, for example, the input shaft 2 and the oir pressure serves 11 and 12. receive of hydraulic receive of directly in pressure servo 13 can supply oil from the Further, the oid boss unit 3a extended from the case 3, without passing through other parts for example, Therefore, oil oil by providing one set of seal rings 84. can be supplied simply by providing one set of seal rings 81 hydraulic and 82, 84 each for the pressure servos 11, 12, and 13,

and therefore the efficiency of the automatic transmission can be improved.

Further, the clutch Cl is a clutch which engages at the relatively slow to medium speed levels of first speed forward, second speed forward, third speed forward, and fourth speed forward, and therefore when this clutch C1 is released at the relatively high speed levels of fifth speed and forward, sixth speed forward, or first speed reverse, particularly the hub unit 122 that connects this clutch C1 and the sun gear S2 rotates at a relatively high revolution or revolves in reverse (see Fig. 3). On the other hand, at the fifth speed forward of first speed reverse the transmitting member 130 reduces rotation speed, and at a sixth speed forward the transmitting member 130 may be fixed in some cases, and difference in revoluti unit 122 and the transmitting member 130 can occur. because this clutch C1 is located on the specific side of first unit pu opposite second PR the planetary gear unit 20, the hub unit 122 and the transmitting member 130 can be The comparison with the gured apart from one another. -ansmission Trace wherein, for example, these members are in contact due to a multi-axial configuration, decreased efficiency of the automatic transmission resulting from friction and so forth avoided

from the relative rotation of those units can be prevented.

-that the clutch C3 is placed Further, in the event between the ring gear R1 and the sun gear S3, for example, the reduced rotation must be engaged and disengaged, and the clutch 3 must be becomes relatively large, but by placing between the input

shaft 2 and the sun gear S1, the engaging and disengaging of

the rotation of the input shaft 2 from this clutch C3 causes on of speed HEANSMISSION OF V the reduced rotation output from the ring gear R1 of the

planetary gear PR to be engaged and disengaged, and the clutch C3 can be made more compact, and therefore the automatic transmission can be made more compact.

Further, the automatic transmission device 1_{16} according of this sixteent to the present embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at 1/1 fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when cmounted on a vehicle, in event that the vehicle is running at a high speed, the engine revolutions can be the lowered, and this contributes to the quietness of the vehicle while running at a high speed.

13 that a clutch is configur between the planetary gear PR and the planetary gear unit PU for example, the length of the linking member (particularly URITS the transmitting member that links the planetary gear PR and the planetary gear unit PU becomes longer in the axially ebusated ion, and since this linking member is for transmitting member transmits

transmilling $oldsymbol{\mathsf{V}}$ the reduced $oldsymbol{\mathsf{V}}$ rotation, the thickness of the increased so as to withstand this; and therefore the weight also increases. Therefore an object of the present invention is to provide an automatic transmission that can shorten the distance between the speed reduction planetary gear and the planetary gear unit and reduce the increa weight.

-With the present embodiment, in particular, the clutch C2 is disposed on the opposite side in the axial direction of the planetary gear unit PU from the planetary gear PR, and therefore providing a clutch between the planetary gear units PR and the planetary gear unit PU is not necessary, and the length of the linking member, particularly the transmitting member 130 can be made that much shorter. Therefore, and the increase in weight of the automatic transmission as a whole reduced can be provented.

the seventeenth embodiment, which is a partial modification of the fifteenth embodiment will be described with reference to Fig. 27 through Fig. 29. the automatic schematic cross-sectional diagram illustrating transmission device of an automatic transmission relating to the seventeenth embodiment, Fig. 28 is an operational table of an automatic transmission relating to the seventeenth embodiment, and Fig. 29 is a speed line diagram of an

embodiment. New, Components of the seventeenth embodiment which are the same as those of the fifteenth embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 27 illustrates, the automatic transmission

device 117 of the automatic transmission relating to the differs from the Sifteenth embodiment seventeenth embodiment is a modification of the in use of configuration of the clutch C2, and further, configures a brake B3 instead of a clutch C3, and enables the carrier CR1 second unit can of the planetary gear PR to be fixed by the brake B3, compared to that of the automatic transmission device 116 of the automatic transmission device 116 of the automatic transmission device 150.

Within the automatic transmission newice 1,7, the brake located

B3 is configured on the planetary gear PR, on the epposite opposite (left side on the diagram) from the planetary gear unit PU.

This brake B3 comprises an oil pressure servo 16, friction plate 76, and a hub unit 133. Further, the clutch C2, comprising an oil pressure servo 12, friction plate 72, a drum shaped member 123, and a hub unit 124, is configured on radially inward of the the inner circumference side of above mentioned brake B3/

that is to say, is enclosed within the hub unit 133. The hub unit 133 of this brake B3 is connected to the side plate of one side of the carrier CR1, and the side plate of the

sintermeshed with Societion plates

152 -rotatably

 $side ext{-of-this}$ carrier $ext{CR1}$ is $extstyle^{oldsymbol{\mathsf{V}}}$ supported by the input shaft 2 so as to be capable of rotating. Further, the sun gear S1 is connected to the input shaft 2 via the drum#/ shaped member 123 of the clutch C2. Also, the friction plate 74 of the brake Bl is splined with the outer circumference side of the ring gear R1, and this ring gear R1 is connected to the transmitting member 130 and to connected to the sun gear S3, via this transmitting member 130.

Continuing, based on the above mentioned construction, the operations of an automatic transmission device 117 will now be described with reference to Fig. 27, Fig. 28, and Fig. 29 below. Now, as with the above-mentioned first embodiment, the vertical axis of the speed line diagram illustrated in Fig. 29 indicated the revolutions of each rotation component, and the horizontal axis indicates the corresponding gear ratio of these rotation components. Further, regarding the planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 29) corresponds to ring gear R3, and hereafter moving to the left direction within the diagram, the vertical axxs corresponds to the ring gear R2 and the carrier CR3, the carrier CR2, and the sun gear S2 and the sun gear S3. Further, regarding the planetary gear PR section of this speed line diagram, the vertical axis to the

corresponds to sun gear S1, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R1 and the carrier CR1. Further, the widths between these vertical axes are proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the inverse of the number of teeth of each of the ring gears R1, R3. Also, the dotted line in the horizontal direction in the diagram illustrate that the rotation is transmitted from the transmitting member 130.

As Fig. 27 illustrates, by retaining the brake B3, the above-mentioned carrier CR1 is fixed as to the case 3.

Further, the rotation of the input shaft 2 is input to the sun gear S1, and the above-mentioned ring gear R1 rotates at reduced rotations based on the rotation of input shaft 2 which is input to this sun gear S1, because this carrier CR1 is fixed. In other words, by engaging the brake B3, the reduced rotation of the ring gear R3 is input to the sun gear S3 via the transmitting member 130.

By doing so, as Fig. 28 and Fig. 29 illustrate,

with regard to

regarding the planetary gear PR, at third speed forward,

fifth speed forward, and first speed reverse, the rotation

of the input shaft 2 is input to the sun gear S1 by

regarding the brake B3 the carrier CR1 is fixed, and the

speed

reduced rotation is output to the ring gear R3 by the

rotation of the sun gear S1 wherein the rotation of the speed input shaft 2 is larget, and the reduced rotation is input to the sun gear S3 via the transmitting member 130. In this case, the ring gear R1 and the ring gear R3 are rotating at the reduced speed, therefore the above mentioned transmitting member 130 performs a relatively large torque transmission. On the other hand, at first speed forward, second speed forward, fourth speed forward, and sixth speed forward, the rotation of the ring gear R3 is input to the ring gear R1 via the transmitting member 130, and further, because the brake B3 is released, as Fig. 29 illustrates, the carrier CR1 rotates based on each the rotation within the speed range level of this ring gear R1 and the sun gear S1 of the

Now, The actions of the above-mentioned planetary gear unit PR are similar to those of the above-described fifteenth embodiment (see Fig. 22 and Fig. 23), and accordingly not repeated here description thereof will be smitted.

As described above, according to the automatic of this seventeenth embodiment transmission device 117 relating to the present invention, due to the planetary gear PR and the clutch C2 being located on one side in the axial direction of the planetary gear unit PU, and the clutch C1 being reentiqued on the other side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear

unit PU can be configured closely together, vcompared to the case wherein for example, two clutches C1 and C2 are units configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 130 for made transmitting reduced rotation can be relatively shortexed.

By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia where inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced.

Further, since the oil pressure servos 11 and 12 are mounted on the input shaft 2, one set of the seal rings 81 to the input shaft 2 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 11 and 12 without providing the seal rings between, for example, the input shaft 2 and the order pressure servos 11 and 12.

Therefore, oil can be supplied simply by providing one set of the seal rings 81 and 82 each for the oil pressure servos 11 and 12, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, the clutch C1 $\frac{1}{100}$ and $\frac{1}{100}$ engages at the relatively slow to medium speed $\frac{1}{100}$ evels of first speed forward, second speed forward, third speed forward, and

released at the relatively high speed levels of fifth speed forward, sixth speed forward, or first speed reverse, particularly the hub unit 122 that connects this clutch C1 and the sun gear S2 rotates at a relatively high revolution or revelves in reverse (see Fig. 3). On the other hand, at the fifth speed forward or first speed reverse the transmitting member 130 reduced retation speed, and at a sixth speed forward the transmitting member 130 may be fixed in some cases, and difference in revolutions between the hub unit 122 and the transmitting member 130 can occur. However, because this clutch C1 is located on the eposite side of the first side of th

the planetary gear PR win the planetary gear unit PU, the hub unit 122 and the transmitting member 130 can be spaced a transmiss configured apart from one another. In comparison with the

wherein, for example, these members are in contact due to a multi-axial configuration, decreased efficiency of the automatic transmission resulting from friction and so forth from the relative rotation of those units can be prevented.

Further, since the reduced rotation output to the first second planetary gear unit PU from the planetary gear PR is made to be engaged and disengaged by the brake B3, the number of components parts (for example drum shaped members and so forth) can be reduced as compared to the case wherein, for example, but clutch C3 is provided. Further, the brake B3 can configure

oil wine directly from the case 3, and therefore the configuration of the oil line can be simplified as compared to the case wherein, for example, a clutch C3 is provided.

Further, The automatic transmission device 117 according of this seventeent embodiment is a transmission device that is directly coupled at fourth speed forward. Therefore, at fifth speed forward and sixth speed forward, the gear ratio can be specified to a high ratio, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine revolutions can be reduced to the engine revolutions can be reduced and this contributes to the quiotness of the work speed.

vehicle while running at a high speed.

between the planetary gear PR and the planetary gear unit PU for example, the length of the linking member (particularly the transmitting member) that links the planetary gear PR and the planetary gear unit PU becomes longer in the axial direction, and since this linking member is for transmitting the reduced fotation, the thickness of the member must be increased so as to withstand this, and therefore the weight also increases. Therefore an object of the present invention is to provide an automatic transmission that can shorten the distance between the speed reduction planetary gear and the planetary gear unit, and reduce the increase in weight.

In this seventeenth embeliacet, because

with the present embodiment, in particular, the clutch

of the planetary gear unit PU from the planetary gear PR,

second

and therefore, providing a clutch between the planetary gear unit

PR and the planetary gear unit PU is not necessary, and the length of the linking member, particularly the transmitting member 130 can be made that much shorter. Therefore, an increase in weight of the automatic transmission as a whole can be prevented.

Eighteenth Embodiment

modification of the first through the seventeenth embodiments will be described, with reference to Fig. 30 through Fig. 32. Fig. 30 is a schematic cross sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the eighteenth embodiment, Fig. 31 is an operational table of an automatic transmission relating to the eighteenth embodiment, and Fig. 32 is a speed line diagram of an automatic transmission relating to the eighteenth embodiment. Now components of the eighteenth embodiment which are the same as those of the first embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As illustrated in Fig. 30, an automatic transmission

of the efficienth embodiment
- 159 18 comprises a planet

device 118 comprises a planetary gear unit PU and a planetary
PR on the input shaft 2. This planetary gear unit PU is a
multiple type planetary gear, which comprises a sun gear S2,
a carrier CR2, a ring gear R2, and a sun gear S3, as the
four rotation components; wherein the carrier CR2 has a long
pinion PL that meshes with a sun gear S3 and a ring gear R2,
supported by a side plate, and a short pinion PS that meshes
with a sun gear S3, which are meshed one to another.

Further, the above mentioned planetary gear PR is a double
pinion planetary gear that has a carrier CR1, wherein a
which
pinion Pb is meshed with a ring gear R1, and a pinion Pa is
meshed with a sun gear S2, which are meshed one to another.

on the above mentioned input shaft 2 is configured a multi-disc clutch (second clutch) C2 on the inner a hydraulic circumference side, which comprises an oil pressure servo 12, clutch friction plate 72, a drum shafted member 223 that forms a the clutch drum, and a hub unit 224 linked to a sun gear S2; and localed a multi-disc brake B2 on the outer circumference side, which is hydraulic comprises an oil pressure servo 15, and a friction plate 75 that are that is splined with the above mentioned hub unit 224.

The oil chamber of this off pressure servo 12 is extended from one edge of the case 3, and is connected to an oil line 91 of the boss unit 3a which is provided on the above mentioned input shaft 2 in a sleeve form. Also, this connects oil line 91 is linked to an oil pressure control unit not

illustrated. In other words, because the above mentioned hydraulic oil pressure servo 12 is configured on the boss unit 3a, an oil line from the oil pressure control unit, not illustrated, is connected to the oil chamber of the oil pressure servo 12 hydraulic to the oil chamber of the oil pressure servo 12 hydraulic which provide a constructed, by one set of seal rings 81 to seal between club.

Further, the above-mentioned input shaft 2 is connected

223

to the above mentioned drum shaped member, and on the inner

Furface

eircumference side of the front edge of this drum shaped

member 223 is configured the friction plate 72 of the clutch

operated

C2 which is capable of engaging by the oil pressure servo 12 of the clutch

for the clutch 62, splined. Further, this hub unit 224 is

connected to the above mentioned sun gear S2. Further, the has friction plates 75 intermeshed with friction plates splined to brake B2 is disposed by splining on the outer circumferences of surface side of the above mentioned drum, shaped member 224, eapable operation of hydraulic engaging by an oil pressure servo 15.

diagram) of the input shaft 2 is configured a multi-disc a hydraulic clutch (first clutch) C37 which comprises an oil pressure clutch servo 13, a friction plate 73, a drum shaped member 225 that forms a clutch drum, and a hub unit 226. If friction plate 5 is splined with the inner circumference side of the front clutch can be clutch friction plate 73 is splined with the inner circumference side of the front clutch can be clutch to suffice and the friction plate 73 is splined with the inner circumference side of the front clutch can be compared member 225 of this clutch c3, and are intermeshed that friction plate 73 is splined with the outer configuration of the front edge of the hub unit 226.

and this hub unit 226 is connected to the carrier CR2.

The oil chamber of this off pressure servo 13 is connected to an oil line 2b which is formed on the abovementioned input shaft 2 and this oil line 2b is provided along the edge of the ease 3 that is the opposite side of that of the above mentioned boss in turn, is connected to the oil line 93 of the boss unit 3b which is provided on the input shaft 2 in a sleeve form, and this oil line 93 linked to an oil pressure control unit not illustrated. Therefore, regarding the above mentioned oil pressure servo 136 providing one set of seal rings 81 to seal between the boss mit 3b of the case 3 and the drum/shapedzmember 225, -configures an oil line from the oil pressure control device connected illustrated, to the oil chamber of the oil pressure servo 13.

rather, on the boss unit 3b is configured a multi-disc a hydraul; clutch (third clutch) C1 comprising an old pressure servo 11, a friction plate 71, and a drum shaped member 221. The oil chamber of the above mentioned oil pressure servo 11 is cannected linked to the oil line 94 of the above mentioned boss unit through 3b, and this oil line 94 is linked to an oil pressure control unit, not illustrated. Therefore, regarding the above mentioned oil pressure servo 11, an oil line from the oil pressure control unit, not illustrated, to the oil chamber of the oil pressure servo 11, is constructed by one

18 migrobod

set of seal rings 84 that seal between the boss unit 3b of the case 3 and the drum-shaped member 221.

Further, on the above mentioned boss unit 3b restre -left of the diagram, the drum shaped member, 221 as supported -so as to be capable of rotating, and on the front edge of the inner circumference side of this drum thapped member 221, is splined to the friction plate 71 of the clutch C1 is splined, which can be engaged by the oil pressure servo 11, for the clutch C1. on the outer circumference side of this clutch Cl is configured a hub unit 222 on which is formed the abovementioned ring gear R1 by splining, and this hub unit 222 is rotatably supported by the input shaft 2 so as to be capable of _rotation__Further, the Carrier CR1 comprises a pinion Pa and a pinion Ph, and this pinion Pb s meshed with the above=mentioned ring gear R1 and this pinion Pa meshed with the sun gear S1 which is connected to the input shaft 2. This carrier CR1 is fixed to the boss must 3b of the case 3, via a side plate.

Also, the drum shaped member 221, to which the abovementioned clutch C1 is splined, is supported by the above
is connected to
mentioned boss must 3b so as to retarn, and a transmitting
member 230 is connected for transmitting the rotation of the
ring gear R1, when the clutch C1 is engaged, and further, on
the other side of this transmitting member 230 is connected
the sun gear S3 of the above mentioned planetary gear unit

PU.

the outer circumference side of first the planetary gear unit PU is configured a multi-disc brake B1 that comprises an old pressure servo 14, A friction plate 5 74, and a hub unit 228. To the side plate of the carrier CR2 of the above-mentioned planetary gear unit PU is to which tis splined the friction plates are splined. connected a hub unit 228 that of the above-mentioned brake Bly and further, this hub unit 228 is connected to the inner race of a one-way clutch The short pinion PS of this carrier CR2 meshes with the sun gear S3. Further, the above-mentioned sun gear S2 and ring gear R2 mesh with the long pinion PL of this CR2, a linking member 227 to connected to one edge of this ring gear R2, and this ring gear R3 is linked to the counter gear 5 via this linking As described above, the planetary gear PR and the as Cland located gured on one side in the axial direction of the planetary gear unit PU, and also the clutch C1 is configured on one side in the axial direction, and the clutch C2 is configured on the other are located on the axially direction, and the counter gear 5 is configured in the opposite direction (right side of the diagram) of the 3131 planetary gear unit PU of the planetary gear PR the clutch C3 is disposed on the inner circumferential side of the clutch Cl, and particularly of the transmitting

member 230 that transmits the output thereof. Further, the localed around brake B2 is configured on the outer circumferential side of the clutch C2, and the brake B1 is configured on the outer first circumferential side of the planetary gear unit PU.

Continuing, based on the above mentioned construction. The embasiment the operations of an automatic transmission device 118 will now be described with reference to Fig. 30, Fig. 31, and Fig. 32 below. New, the vertical axis of the speed line diagram illustrated in Fig. 32 indicated the revolutions of each rotation component, and the horizontal axis indicates the corresponding gear ratio of these rotation components. Further, regarding the planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 32) corresponds to sun gear S3, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R2, the carrier CR2, and the sun gear S2. Further, regarding the planetary gear PR section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 32) corresponds to the sun gear S1, and horeafter moving to the left direction within the diagram, the vertical axis correspond to the ring gear R1 and the carrier CR1. Further, the width between these vertical axes are proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the

R3. Also, the dotted line in the horizontal dimestion in the diagram illustrate that the rotation is transmitted from the transmitting member 230.

As illustrated in Fig. 30, the rotation of the input shaft 2 is input to the above-mentioned sun gear by engaging the clutch C2, and the rotation of this sun gear S2 can be fixed by retaining the brake B2. The rotation of the input shaft 2 is input to the above-mentioned carrier CR2, by engaging the clutch C3, and the rotation can be fixed by retaining the brake B2. Further, rotation in one direction is controlled by the one-way clutch F1.

On the other hand, the above-mentioned sun gear S1 is and receives inpol from connected to the input shaft 2, and the rotation of this

connected to the case 3 and its rotation is fixed, and therefore the ring gear R1 rotates at reduced rotations.

Further, by engaging the clutch C1, the reduced rotations of this ring gear R1 are input to the sun gear S3. Also, the rotation of the above mentioned ring gear R2 is output to the

drive wheel with this counter gear 5, a counter shaft unit not illustrated, and a differential unit.

first speed forward within the D (drive) range, as illustrated in Fig. 31, the clutch C1 and the one-way clutch

F1 are engaged. Then, as illustrated in Fig. 32, the speed reduced rotations of the ring gear R1 are input to the sun gear S3 via the clutch C1 and the transmitting member 230. limited to Further, the rotation of the carrier CR2 is controlled in one direction (the forward rotation direction) by the oneway clutch Fla in other words the carrier CR2 is prevented from rotating in the opposite direction and is fixed. Then, the ring gear R2 rotates forward for the first speed forward, from the reduced V rotation input to the sun gear \$2 and the state of this first speed forward fixed carrier CR2, and that totation is output from the state of counter gear 5.

FOR when downshifting (when coasting), the brake B1 is and the carrier CR2 is fixed, and the above--mentioned state of first speed forward is maintained while preventing the forward rotation of this carrier CR2. Further, at this first speed forward, the one-way clutch F1 reverse prevents the carrier CR2 from rotation in the opposite -direction and allows forward rotation, and therefore, switching from a non-driving range to a driving range and first speed forward can be accomplished more smoothly by the automatic engageng of the one-way clutch. In this case, because the sun gear S3 and the ring gear R1 speed rotaling. are at a reduced rotation, the above mentioned transmitting member 230 performs a relatively large torque transmission. At second speed forward within the D (drive) range, as

illustrated in Fig. 31, the clutch C1 is engaged and the brake B2 is relatived. Then, as illustrated in Fig. 32, the reduced rotation of the ring gear R1 are input to the sun gear S3 via the clutch C1 and the transmitting member 230, and the rotation of the sun gear S2 is fixed by the brake B2.

By doing so, the carrier CR2 rotates at reduced rotations alightly, and from the reduced rotations input to the sun gear S3 and this slightly reduced rotation of the carrier CR2, the ring gear R2 rotates forward for the second speed forward, and this rotation is output to the counter gear 5.

Now, also in this case, because the sun gear S3 and the ring gear R1 are at a reduced rotation, the above mentioned transmitting member 230 performs a relatively large torque, transmission.

illustrated in Fig. 31, the clutch C1 and the clutch C2 are engaged. Then, as illustrated in Fig. 32, the reduced speed rotations of the ring gear R1 is input to the sun gear S3 via the clutch C1 and the transmitting member 230, and also the rotation of the input shaft 2 is input to the sun gear S2 by engaging the clutch C2. Further, by the rotation of the input shaft 2 input to the sun gear S2 by engaging the clutch C2. Further, by the rotation of the input shaft 2 input to the sun gear S2 and so the speed reduced rotation of the sun gear S3, the sixed carrier CR2 has slightly greater reduced rotations than the reduced rotations of this sun gear S3. Further, from the input

rotation of the sun gear S2 and the reduced rotations of the sun gear S3, the ring gear R2 rotated forward for third speed forward, and this rotation is output from the counter gear 5. In this case also, because the sun gear S3 and the rotation gear R1 are at a reduced rotation, the above-mentioned transmitting member 230 performs a relatively large torque, transmission.

fourth speed forward within the D (drive) range, as illustrated in Fig. 31, the clutch C1 and the clutch C3 are Then, as illustrated in Fig. 32, the reduced speed rotations of the ring gear R2 is input to the sun gear S3 via the clutch C1 and the transmitting member 230, and also the rotation of the input shaft 2 is input to the carrier Then, by the rotation of input shaft CR2 via the clutch C3. 2 input to the carrier CR2 and by the reduced vrotations the sund gear S3, the ring gear R2 rotates forward for fourth speed forward, and this rotation is output from the counter gear 5. In this case also, because the sun gear S3 and the ring gear R1 are Vat a reduced # mentioned transmitting member 230 perfor 🕏 a relatively large torque transmission.

At fifth speed forward within the D (drive) range, as illustrated in Fig. 31, the clutch C2 and the clutch C3 are engaged. Then, as illustrated in Fig. 32, the rotation of input shaft 2 is input to the carrier CR2 via the clutch C3,

and also the rotation of the input shaft 2 is input to the sun gear S2 via the clutch C2. Then, from the rotation of the input shaft 2 input to the sun gear S2 and the rotation of the input shaft 2 input to the carrier CR2, the ring gear R2 is in a direct-connect rotating state, and rotates forward for the fifth speed forward, which has the same rotation as the input shaft 2, and this rotation is output from the counter gear 5.

illustrated in Fig. 31, the clutch C3 is engaged and the brake B2 is retained. Then, as illustrated in Fig. 32, the rotation of the input shaft 2 is input to the carrier CR2 via the clutch C3, and retation of the sun gear S2 is fixed by retaining the brake B2. Then, from the rotation of the input shaft 2 input to the carrier CR2 and from the fixed sun gear S2, the ring gear R2 rotates at everdrive rotations for sixth speed forward, and this rotation is output from the counter gear 5.

At first speed reverse within the R (reverse) range, as illustrated in Fig. 31, the clutch C2 is engaged and the brake B1 is retained. Then, as illustrated in Fig. 32, the rotation of the input shaft 2 is input to the sun gear S2 by engaging the clutch C2, and also the rotation of the carrier CR2 is fixed by retaining the brake B1. Then from the rotation of the input shaft 2 input to the sun gear S2 and

from the fixed carrier CR2, the ring gear R2 rotates in the opposite direction as the first speed reverse, and this rotation is output to the counter gear 5.

At the P (parking) range and the N (neutral) range,

particularly clutch C1, clutch C2, and clutch C3 are

released, the transmission movement between the input shaft

2 and the counter gear 5 is disconnected, and the automatic

transmission device 1₁₈ as a whole is in an idle state

(neutral state).

As described above, according to the automatic of the eighteeth embodiment transmission device 118 relating to the present invention, second because the planetary gear PR and the clutch C3 is 216 located configured on one side in the axial direction of the Siral planetary gear unit PU, and the clutch C2 is conf. the other oide in the axial direction of the planetary gear units unit PU, the planetary gear PR and the planetary gear , SOF EXAMPLE) PU can be configured closely together, as compared to the an embodiment -case wherein for example two clutches C2 and C3 are configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 230 for anomitting reduced rotation can be relatively shortened. n this morner -doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia inertial can be reduced, the controllability of the automatic transmission can be increased, and the

occurrence of speed change shock can be reduced. Further,

an embodiment

compared to the case wherein three clutches C1, C2, C3 are

located

configured on one side of the planetary gear unit PU, the

oil lines (for example, 2b, 91, 93, 94) that supply the oil

hydraulic

pressure servos 11, 12, and 13 of these clutches C1, C2, C3

more

can be constructed easily, and the manufacturing process can

be simplified and the costs brought down.

Further, since the oil pressure servo 13 is provided on form a setween the input shaft 2, one set of seal rings 82 seal the case 3 and input shaft 2 to throwsh and supply oil to the oil line 2b provided within input shaft 2 and therefore oil can be supplied to the oil chamber of oil pressure servo 13, without providing seal rings between, for example, the input shaft 2 and the oil pressure servo 13. Further, oil pressure servos 11 and 12 of directly can supply oil from the boss units 3a, 3b provided from the components. -case-3, without passing through other units for example, in other words, can supply oil by providing one set of seal Therefore, oil can be supplied simply by rings 81 and 84. providing one set of seal rings 81, 82, and 84/each for Ardraulic oil pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, since the clutch C3 is configured on the inner circumference side of the clutch C1, the clutch C1, which must transmit a relatively large torque in order to transmit

the reduced rotation, can be configured on the outer circumference side, and this clutch C1 and the oil pressure servo 11 thereof can have an increased diameter.

Particularly, the pressure area of the oil chamber of the oil pressure servo 11 can be enlarged, and the capacity capable capacity for the clutch C1 can be increased.

By configuring the clutch C3 which can have a smaller capacity torque transmission compared to the clutch C1, the automatic transmission can be made more compact.

Further, because clutch C2 is a clutch that engages while at first speed reverse, when this clutch 2 is engaged at first speed reverse, the hub unit 224 that connects this clutch C2 and the sun gear S2 rotates at the same rotation as the input shaft 2, by engaging this clutch 62, while the transmitting member 230 rotates in the opposite direction, and accordingly there may be cases wherein the rotation between the rotational speed of that of difference of the transmitting and accordingly there are a second accordingly the transmitting and accordingly there are a second accordingly the accordingly to the accordingly to the accordingly the accordingly the accordingly the accordingly the accordingly to the accordingly the accordingly to the accordingly the accordingly to the according difference of the transmitting member 230 and the hub unit 224 becomes great, but due to this clutch C2 being <u>l</u>ocated on the opposite side of the planetary gear PK, via the second planetary gear unit PG, the transmitting member 230 and the hub hunt 224 can be configured apart from one another. Compared to the case wherein, for example, those parts come $i\vec{n}^{0}$ contact due to a multiple axis construction, the decreased efficiency of the automatic transmission caused by the friction produced by the relative rotation between those

parts can be prevented.

Further, the automatic transmission device 1₁₈ according to the present embodiment is a transmission device that is directly coupled at fifth speed forward. Therefore, at first speed forward and fourth speed forward, the gear ratio more precisely sell can be specified in a detailed manner, and particularly when mounted on a vehicle, in the event that the vehicle is speed reduced running at a high speed, the engine can be atilized with better revolutions, and this contributes to increased fuel economy of the vehicle while running at a low to medium speed.

member for linking member (in particular the transmitting units)

gear unit PU requires rigidity to withstand the reduced speed torque that is input. For example, in the case of configuring a clutch that engages at a slow to medium speed or a clutch that engages and disengages reduced rotations on the inner circumference side of the linking member, the clutches must have a large capacity, therefore and appropriate diameter to correspond with this capacity becomes necessary. Therefore, in the event that the tinking member is the type that passes on the outer circumference side of this type of clutch, even plarger diameter than the necessary diameter measurement of those clutches becomes recessary, and the diameter measurement of the linking

member is enlarged more than necessary, and the automatic must have a transmission as a whole becomes greater in the direction of the diameter. Therefore an object of the present embodiment is to reduce the onlargement of the diameter measurement, thereby and provide a compact automatic transmission.

According to the present embodiment, all clutches can designed to evoid enlarging the diameter measurement of the configured without enlarging the diameter measurement of the linking member, by configuring a clutch C3 with a small capacity on the linking member, particularly on the inner circumference side of the transmitting member 230.

Nineteenth Embodimental

New, the nineteenth embodiment, which is a partial now modification of the eighteenth embodiment will be described, with reference to Fig. 33 through Fig. 36. Fig. 33 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the nineteenth embodiment, Fig. 34 is an operational table of an automatic transmission relating to the nineteenth embodiment, and Fig. 35 is a speed line diagram of an automatic transmission relating to the nineteenth embodiment.

Now, Components of the nineteenth embodiment which are the same as those of the eighteenth embodiment will be denoted with the same reference numerals, and description thereof will not be emitted, except for partial modifications.

As Fig. 33 illustrates, the automatic transmission

device 1₁₉ of the automatic transmission relating to the has nineteenth embodiment is a modification of the configuration modified and of the clutch C2, and further, changes the construction of the oil line of the oil pressure servo 12 of the offutoh C2, compared to that of the automatic transmission device 1₁₈ of the automatic transmission of the eighteenth embodiment (see Fig. 30).

Within the automatic transmission device 1₁₉, the clutch

Within the automatic transmission dovice 119, the clutch unit second C1 is configured on the planetary gear PR, on the opposite (left side on the diagram) from the planetary gear unit PU. front edge of the inner circumference side of the drum -shaped member 221 of this clutch C1 is splined with the friction plate 71, and the inner sincumference side of this friction plate 71 is splined with the hub unit 222. drum shaped member 221 is connected to the input shaft 2, and the hub unit 222 is connected to the sun gear S1 of the Second Unit The side plate of the carrier CR1 of planetary gear ♥ PR. this planetary gear PR is fixed and supported by the case 3. Also, the ring gear R1 is connected to the transmitting member 230 and this transmitting member Further, the clutch C3 comprising an sun gear S3. 13, \$\fraction plate 73, a drum rshaped member 225, and a hub unit 226, is configured so as to be enclosed within this transmitting member 230.

The oil chamber of this oil pressure servo 12 is linked

to an oil line 2a which is formed on the input shaft 2, and
this oil line 2a is provided along one edge of the case, and
is connected to the oil line 91 of the boss unit 3a which is
pround one end of
provided on the input shaft 2 in a sleeve form, and this oil
line 91 is linked to an oil pressure control unit not
illustrated. Therefore, regarding the above-mentioned oil
pressure servo 12, simply by providing one set of seal rings
81 to seal between the input shaft 2 and the boss unit 3a of
communication is established between
the case 3, as oil line is constructed from the oil pressure
control device the input shaft to the oil chamber of the
hydraulic
oil pressure servo 12.

Continuing, based on the above mentioned construction of the nine certific embodiment the operations of the automatic transmission devices 119 will now be described with reference to Fig. 33, Fig. 34, and Fig. 35 below. Now, as with the above mentioned first embodiment, the vertical axis of the speed line diagram illustrated in fig. 35 indicates the revolutions of leach rotation component, and the horizontal axis indicates the corresponding gear ratio of these rotation components. Further, regarding the first planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 35) corresponds to sun gear S3, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R2, the carrier second.

CR2, and the sun gear S2. Further, regarding the planetary

gear PR section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 35) corresponds to sun gear S1, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R1 and the carrier CR1. Further, the width between these vertical axes are proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the inverse of the number of teeth of each dotted line in the horizontal direction in the diagram illustrate that the rotation is transmitted from the transmitting member 230.

As illustrated in Fig. 33, by engaging the clutch C1, the rotation of the input shaft 2 is input to the sun gear S1. Further, the rotation of the above mentioned carrier CR1 is fixed to the case 3, and the above mentioned ring gear R1 rotates at reduced rotations based on the rotation of the input shaft 2 input to this sun gear S1. In other words, by engaging the clutch C1, the reduced rotation of the ring gear R1 is input to the sun gear S2 via the transmitting member 230.

planetary gear PR, at first speed forward, second speed forward, third speed forward, and fourth speed forward, the rotation of the input shaft 2 is input to the sun gear S1 by

engaging the clutch C1, the reduced rotation is output to the ring gear R3 from the fixed carrier CR1, and the reduced speed rotation is input to the sun gear S3 via the transmitting member 230. At this time, the ring gear R1 and the sun gear S3 rotate at a reduced speed, and therefore the above-Transmils a relatively mentioned transmitting member 230 performs large torque transmission. On the other hand, at fifth speed forward, sixth speed forward, and first speed reverse, the rotation of the sun gear S3 is input to the ring gear R1 via the transmitting member 230, and further, because the clutch C1 is released, as illustrated in Fig. 35, the sun がと different speed of this ring gear S1 rotates based on each ation of the gear R1 and the fixed carrier CR1.

Now, the actions of the above-montioned planetary gear are similar to those of the above-described eighteenth embodiment (see Fig. 31 and Fig. 32), and accordingly description thereof will be omitted.

transmission device 119 relating to the automatic relating to the present invention, second unit due to the planetary gear PR and the clutch C3 being located configured on one side in the axial direction of the first planetary gear unit PU, and the clutch C2 being configured on the other side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear unit PU, the planetary gear PR and the planetary gear unit PU can be configured closely together, as compared to

an embodiment the case wherein for example two clutches C2 and C3 are located configured in between the planetary gear PR and planetary -gear-unit PU, and the transmitting member 230 for transmitting reduced rotation can be relatively shortened. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia Inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case wherein three clutches C1, C2, C3 are ared on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 93, 94) that supply the hydraulic ori pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, and the manufacturing process can be reduced can be simplified and the costs brought

Further, since the ell prossure servos 12, 13 are

provided on the input shaft 2, one set of seal rings 81 and

form 3 will
82 seal the case 3 and supply oil to the oil lines 2a and 2b

provided within input shaft 2 and therefore oil can be

supplied to the oil chamber of oil pressure servos 12, 13,

without providing the seal rings between, for example, the

input shaft 2 and the oil pressure servos 12, 13. Further,

the orl pressure servo 11 can supply oil from the boss unit

3b extended from the case 3 without passing through other

component,

parts for example, and therefore can supply oil by providing

Can be connected

one set of seal rings 84. Therefore, oil can be supplied through simply by providing one set of seal rings 81 and 82, 84 cash for the oil pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, since the clutch C2 is a clutch that engages t first speed reverse, when this clutch 2 is engaged first speed reverse, the hub unit 224 that connects this clutch C2 and the sun gear S2 rotates at the same $\frac{7}{100}$ as the input shaft 2, by engaging this clutch 62, while the transmitting member 230 rotates in the opposite direction, speed be rotation difference of and there may be cases wherein the the transmitting member 230 and the hub unit 224 becomes large, However, side of the planetary gear provide the planetary gear unit the transmitting member 230 and the hub burt 224 can be igured apart from one another. Compared to the case wherein, for example, those parts come in contact due to a multiple axis construction, the decreased efficiency of the automatic transmission caused by the friction produced by the relative rotation between those parts can be pre Further, in the event that the clutch C1 Vis placed

between the ring gear R1 and the sun gear S3, for example,

specific the reduced rotation must be engaged and disengaged, and a larger clutch

<1 would be required. However, the dutch Cl becomes relatively large, but by placing between the input shaft 2 and the sun gear S1, the engaging and disengaging of the rotation of the input shaft 2 from this clutch C1 causes the reduced Yrotation output from the ring gear R1 of the second planetary gear, PR to be engaged and disengaged, and the unit clutch C1 can be made more compact, and therefore the automatic transmission can be made more compact. Further, the automatic transmission device 119 according embodiment is a transmission device that is directly coupled at fifth speed forward, Therefore, first speed forward and fourth speed forward, the gear ratio can be specified in a detailed manner, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine can be utilized with increased fuel better revolutions, and this contributes to speed. economy of the vehicle while running at a low to medium member ter linking the planetary gear PR and the planetary -gear unit PU requires rigidity to withstand the reduced speed torque that is input. For example, in the case of -configuring a clutch that engages at a slow to medium, speed speed and is localed and in the case of or a clutch that engages and disengages reduced retations on radially inward transmitting sence side of the linking member, the clutches must have a large capacity therefore and 2756

appropriate diameter to correspond with this capacity. Therefore, in the event that the linking becomes necessary member is the type that passes on the outer circumference such a side of this type of clutch, even a larger diameter than the dor the those clutches becomes even larger necessary diameter measurement of necessary, and the diameter measurement of the linking Transmitting member is enlarged more than necessary, and the automatic has a transmission as a whole becomes greater in the direction of the diameter. Therefore an object of the present embodiment avoid the need for is to reduce the enlargement of the diameter measurement, and provide a compact automatic transmission. In this nineterth all clutches can

According to the present embodiment, all clutches can so as to avoid entitled be configured without enlarging the diameter measurement of the linking member, by configuring a clutch C3 with a small capacity on the linking member, particularly on the inner is provided radially inward eineumference side of the transmitting member 230.

Twentieth Embodiment

Below, the twentieth embodiment, which is a partial modification of the eighteenth embodiment will be described, with reference to Fig. 36 through Fig. 38. Fig. 36 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the twentieth embodiment, Fig. 37 is an operational table of an automatic transmission relating to the twentieth embodiment, and Fig. 38 is a speed line diagram of an

-automatic transmission relating to the twentieth embodiment.

Now, Components of the twentieth embodiment which are the same as those of the eighteenth embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 36 illustrates, the automatic transmission

device 120 of the automatic transmission relating to the

twentieth embodiment comprises a brake B3 instead of a

clutch C1, and enables the carrier CR1 of the planetary gear

PR to be fixed by the brake B3, and further thanges the

PR to be fixed by the brake B3, and further thanges the

V construction of the oil line of the eight pressure servo 12 of

second unit

the planetary gear PR compared to that of the automatic

transmission device 118 of the automatic transmission of the

eighteenth embodiment (see Fig. 30).

Within this automatic transmission device 120, the brake located side of the second unit

B3 is configured on the planetary gear PRA on the opposite first

(left side on the diagram) from the planetary gear unit PU.

This brake B3 comprises an oil pressure servo 16, of friction plate 76, and a hub unit 233.

The hub unit 233 of this brake B3 is connected to the side plate of one side of the carrier CR1, and this carrier CR1 is supported by the input shaft 2 or the boss unit 3a, so as to be capable of rotating. Further, the sun gear S1 is connected to the input shaft 2. Also, this king gear R1 is connected to the transmitting member 230, and is connected

to the sun gear S3 via this transmitting member 230.

The oil chamber of this oil presents servo 12 is linked to an oil line 2a which is formed on the input shaft 2, and his oil line 2a is provided along one edge of the case, and which is connected is connected to the oil line 91 of the boss unit 3a which is provided on the input shaft 2 in a sleeve form, and this oil line 91 is linked to an oil pressure control unit not illustrated. Therefore, regarding the above-mentioned oil pressure servo 11, simply by providing one set of seal rings the case 3, as oil line is constructed from the oil pressure control device not illustrated to the oil chamber of the oil pressure servo 12.

the Operations of the automatic transmission device 120 will

now be described with reference to Fig. 36, Fig. 37, and Fig.

38 below. Now, as with the above mentioned first embodiment, the vertical axis of the speed line diagram illustrated in respective fig. 38 indicates the revolutions of each rotation component, and the horizontal axis indicates the corresponding gear ratio of these rotation components. Further, regarding the first planetary gear unit PU section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 38) corresponds to sun gear S3, and hereafter moving to the left direction within the diagram, the

vertical axis corresponds to the ring gear R2, the carrier second.

CR2, and the sun gear S2. Further, regarding the planetary gear PR section of this speed line diagram, the vertical axis to the farthest horizontal edge (the right side of Fig. 38) corresponds to sun gear S1, and hereafter moving to the left direction within the diagram, the vertical axis corresponds to the ring gear R1 and the carrier CR1.

Further, the width between these vertical axes are inversely proportional to the inverse of the number of teeth of each of the sun gears S1, S2, S3, and to the inverse of the number of teeth of each of the ring gears R1, R3. Also, the dotted line in the horizontal direction in the diagram represents that the rotation is transmitted from the transmitting member 230.

As Fig. 36 illustrates, by retaining the brake B3, the above-mentioned carrier CR1 is fixed as to the case 3.

Further, the rotation of the input shaft 2 is input to the sun gear S1, and the above mentioned ring gear R1 rotates at reduced rotations based on the rotation of input shaft 2 which is input to this sun gear S1, because this carrier CR1 is fixed. In other words, by engaging the brake B3, the reduced rotation of the ring gear R1 is input to the sun gear S3 via the transmitting member 230.

In this manner

By doing so, as Fig. 37 and Fig. 38 illustrate,

in second unit in

regarding the planetary gear PR, at first speed forward,

second speed forward, third speed forward, and fourth speed forward, the rotation of the input shaft 2 is input to the sun gear S1 by retaining the brake B3, the carrier CR1 is fixed, the reduced rotation is output to the ring gear R3 by the rotation of the sun gear S1 wherein the rotation of the input shaft 2 is input, and the reduced rotation is input to the sun gear S3 via the transmitting member 230. In this case, the ring gear R1 and the sun gear S3 are rotating at reduced speed, therefore the above-mentioned transmitting member 230 performs a relatively large torque. transmission. On the other hand, at fifth speed forward, forward speed level, and first speed reverse, the rotation of the sun gear S3 is input to the ring gear R1 via the transmitting member 230, and further, because the brake B3 is released, as Fig. 38 illustrates, the carrier CR1 rotates based on each the rotation within the speed level of this ring gear R1 and the sun gear S1 of the rotation of the input shaft 2.

Now, the operations other than these of the above—

world

mentioned planetary gear are similar to those of the above—

described eighteenth embodiment, and accordingly description thereof will be omitted.

As described above, according to the automatic of the twentieth embodiment, transmission device 120 relating to the present invention, second unit

-configured on one side in the axial direction of the first planetary gear unit PU, and the clutch C2 being configured on the other side in the axial direction of the planetary units gear unit PU, the planetary gear PR and the planetary gear located more 25 muit PU can be configured closely together, compared to the -case wherein, for example, two clutches C2 and C3 are configured in between the planetary gear YPR and planetary -gear unit PU, and the transmitting member 230 for transmitting reduced rotation can be relatively shortened. In this manner doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia force of inertial can be reduced, the controllability of the automatic transmission can be increased, and the

occurrence of speed change shock can be reduced.

Further, since the oil pressure servos 11 and 12 are mounted provided on the input shaft 2, one set of seal rings 81 and serves to room 82 seal the case 3 and supply oil to the oil lines 2a and 2b provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servos 12, 13 without providing seal rings between, for example, the input shaft 2 and the oil pressure servos 12, 13. Therefore, oil can be supplied simply by providing one set of seal rings 81 and 82 each for the oil pressure servos 12, 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can

be improved.

when Further, since the clutch C2 is a clutch that engages while at first speed reverse, when this clutch 2 is engaged at first speed reverse, the hub unit 224 that connects this clutch C2 and the sun gear S2 rotates at the same actation Accordingly, as the input shaft $2_4^{\ \ \ \ }$ by engaging this clutch C2, while the transmitting member 230 rotates in the opposite direction, will cause speeds and there may be cases wherein the retat on difference of the transmitting member 230 and the hub unit 224Vbecome great, but because this clutch C2 is located on the opposite uniTPU opposiTe side of the planetary gear $M_{
m c}$ via the planetary gear unit _PU, the transmitting member 230 and the hub hunt 224 can be 5Faced configured apart from one another. Compared to the case components wherein, for example, those parts come in contact due to a multiple axis construction, the decrease efficiency of the automatic transmission caused by the friction produced by components the relative rotation between those parts can be prevented. the output of SPEEd Further, since the reduced rotation cutput to the

Further, since the reduced rotation output to the scand unit controlled planetary gear unit PU from the planetary gear PR is made to engaged and disengaged by the brake B3, the number of parts (for example drum-shaped members and so forth) can be reduced as compared to the ease wherein, for example, a enclosed clutch C1 is provided. Further, the brake B3 can configure an oil line directly from the case 3, and therefore the

configuration of the oil line can be simplified as compared

to the case wherein, for example, a clutch C1 is provided.

Further, the automatic transmission device 120 according to the present embodiment is a transmission device that is directly coupled at fifth speed forward. Therefore, at first speed forward and fourth speed forward, the gear ratio such as to provide greater efficiency can be specified in a detailed manner, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine can be utilized with efficiently better revolutions, and this contributes to increased fuel economy of the vehicle while running at a low to medium is increased speed.

In this embodiment also,

Now, the linking member (in particular the transmitting units

member) for linking the planetary gear PR and the planetary

speed torque that is input. For example, in the case of

configuring a clutch that engages at a slow to medium speed

to transmit
of a clutch that engages and disengages reduced rotations on

the inner circumference side of the linking member, the

clutches must have a large capacity, therefore an provide the necessary appropriate diameter to correspond with this capacity.

member is the type that passes on the outer circumference such a side of this type of clutch, even a larger diameter, than the necessary diameter measurement of these clutches becomes necessary, and the diameter measurement of the linking

member is enlarged more than necessary, and the automatic has a transmission as a whole becomes greater in the direction of the diameter. Therefore an object of the present embodiment is to reduce the enlargement of the diameter measurement, and provide a compact automatic transmission.

According to the present embodiment, all clutches can be configured without enlarging the diameter measurement of transmilling because the linking member, by configuring a clutch C3 with a small capacity on the linking member, particularly on the inner circumference side of the transmitting member 230.

modification of the eighteenth embodiment will be described, with reference to Fig. 39. Fig. 39 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the twenty first embodiment. Now, Components of the twenty-first embodiment which are the same as those of the eighteenth are embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 39 illustrates, the automatic transmission

device 1₂₁ of the automatic transmission relating to the

differs from the eighteenth embodiment

twenty-first embodiment is a modification of the

second

unit More

configuration of the clutch C1 and the planetary gear PR. in

Hat of

the diagram
- 191 second unit

configured on the right side of the diagram of the planetary gear unit PU, and the counter gear 5 is configured in the between this planetary gear PR and the planetary gear unit PU, compared to that of the automatic transmission device 118 of the automatic transmission of the eighteenth embodiment (see Fig. 30).

Within the automatic transmission device 121 on the inner circumference side of the input shaft 2 is configured a hydraulic a multi-disc clutch C1 comprising an oil prossure servo 11, a friction plate 71, a drum shaped member 221 that forms a clutch drum, a hub unit 222 connecting to a sun gear S3, and on the outer circumference side is comprised a multi-disc hydraulic clutch C2 comprising an oil pressure servo 12, a friction plate 72, a drum shaped member 223 that forms a claute drum, radially outward as .. a hub unit 224. Further, on the hub unit 224 is comprised a multi-disc brake B2 = hydrau/ic # friction plate 75. comprising an oil pressure servo 15 and

The above mentioned input shaft 2 is supported by the entire has above mentioned drum shaped member 221 so as to be capable portion of rotating, and on the front edge of the inner circumference side of this drum shaped member 221 is splined to configured the friction plate 71 of the clutch C1 which as capable of engaging by the oil pressure serve 11 for the

-olutch C, splined, and is connected so that the inner

eircumference side of the friction plate 71 of this clutch

Further, the sun gear S1 is fixed and supported by the above mentioned boss unit 3a, and the carrier CR1 is connected to the input shaft 2 via the side plate. The ring rotatally gear 1 is supported by the boss unit 3a so as to be capable of rotating, and also is connected to the above mentioned of drum shaped member 221. Further, the above mentioned hub unit 222 is connected to the transmitting member 230, and this transmitting member 230 is connected to the above mentioned hub this transmitting member 230 is connected to the above mentioned sun gear S3.

Now, the oil chamber of the oil pressure servo 11 is which is linked to the oil line 2a formed on the above mentioned connected input shaft 2m and this oil line 2a is linked to the oil which, in Turn, is connected in line 91 of the boss amit 3a provided on the imput shaft 2 in a sleeve form, and this oil line 91 is linked to the oil pressure control device not illustrated. This oil pressure servo 11 comprises one set of seal rings 81 that seal between the boss anit 3b of the case 3 and the input shaft 2, and one set of seal rings 85 that seal between the input shaft 2 and the drum shaped member 221, in other words, uses two sets of seal rings and constructs are oil line from the oil pressure control device not illustrated to the oil chamber of the oil pressure servo 11.

On the other hand, on the other side of the input shaft

3 ich

2 (left Vin diagram) is configured a multi-disc clutch C that the hydraulic comprises an oil pressure servo 13, of friction plate 73, a

unit 226. The friction plate 73 is splined with the front portion

surface

edge of the inner circumference side of the drum shaped

-member 225 of this clutch C3, and this friction plate 73 is

of the hub unit 226, and this hub unit 226 is connected to the side plate of the carrier CR2.

The oil chamber of this oil pressure servo 13 is connected to an oil line 2b which is formed on the abovementioned input shaft 2, and this oil line 2b is provided along the edge of the case 3 that is the opposite side of that of the above mentioned boss unit 3a, and is connected

to the oil line 93 of the boss which is provided on

Included the input shaft 2 in a sleeve form. Therefore, an oil line

from the oil pressure control unit, not illustrated, to the

oil chamber of the oil pressure servo 13 is constructed on

the above mentioned oil pressure servo 13; simply by

providing one set of seal rings 82 to seal between the boss

out the service of the seal rings 82 to seal between the boss

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out the seal rings 82 to seal between the boss

out the seal rings 82 to seal between the boss

the other hand, on the outer circumference side of the planetary gear unit PU is configured a multi-disc brake a hydraulic.

B1 comprising an oil pressure servo 14, a friction plate 74, and a hub unit 228. The side plate of the carrier CR2 of

the above mentioned planetary gear unit PU is connected to

To friction plates in termeshed

the hub unit 228 that is splined with the friction plates 74

of the above mentioned brake B1, and further, the hub unit

228 is connected to the inner race of the one-way clutch F1.

The sun gear S3 is meshed with the short pinion PS of this

carrier CR2 Thop, the long pinion PL of this carrier CR2

is meshed with the above mentioned sun gear S2 and the ring

gear 2, and to one edge of this ring gear R2 is connected to

the binking member 227, and this ring gear R2 is linked to

the counter gear 5 via this linking member 227.

The operations of the automatic transmission device 121% from Those of the eighteenth embosiment in that based on the above mentioned construction are as follows. Jecond Unit Within the planetary gear PR, the carrier CR1 and the sun gear S1 have switched positions. In other words, the sun gear S1 is fixed, and the rotation of the input shaft 2 is input to the carrier CR1, but the other parts are the same as those of the eighteenth embodiment (see Fig. 31 and Fig. 32), and according description will be omitted.

As described above, according to the automatic of the Twenty-Size consideral transmission device 121 relating to the present invention, due to the planetary gear PR and the clutch C2 being localed configured on one side in the axial direction of the planetary gear unit PU, and the clutch C3 being configured on the other side in the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear

located more unit PU can be configured closely together, compared to the embodinent se wherein for example, two clutches C2 and C3 are located configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 230 for which transmitting reduced rotation can be relatively shortened. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia Vforce of inertia) can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. compared to the case wherein three clutches C1, C2, C3 are confrigured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 2b, 91, 92, 93) that supply the hydraulic pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be constructed easily, and the manufacturing process can be reduced can be simplified and the costs brought down

Further, since the counter gear 5 is configured in the axial direction between the planetary gear unit PU and the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear direction when the imput side from the drive source is the growing direction) can be prevented because the counter gear 5

is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of an FF vehicle,

the interference toward the front wheels is reduced, and the

mountability on a vehicle can be improved, such as the

steering angle being greatly increased, for example.

Further, the automatic transmission device 121 according
to the present embodiment is a transmission device that is
directly coupled at fifth speed forward. Therefore, at
first speed forward and fourth speed forward, the gear ratio
can be specified in a detailed manner, and particularly when
mounted on a vehicle, in the event that the vehicle is
running at a high speed, the engine can be utilized with
better revolutions, and this contributes to increased fuel
is increased
economy of the vehicle while running at a low to medium
speed.

Twenty-second Embodiment

modification of the twenty-first embodiment, which is a partial modification of the twenty-first embodiment, will be described, with reference to Fig. 40. Fig. 40 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the twenty-second embodiment. Now, Components of the twenty-second embodiment which are the same as those of the twenty-first embodiment will be denoted with the same reference numerals, and description thereof omitted, except

for partial modifications.

As Fig. 40 illustrates, the automatic transmission

device 122 of the automatic transmission relating to the fixed by the brake B3 compared to that of the automatic transmission device 121 of the automatic transmission of the twenty-first embating the twenty first embating the fixed automatic transmission of the twenty first embatic transmission of the twenty first embatic transmission of the twenty first embodiment (see Fig. 39).

Within this automatic transmission device 122, the brake located B3 is configured on the opposite side (the right side of the diagram) of the planetary gear unit po of the planetary gear Unit a hydraulic This brake B3 comprises an oil pressure servo 16, friction plate 76, and a hub unit 233, and this mub unit 233 and is rotatably is connected to the sun gear S1 in the form of being supported by the boss wait 3a, so as to be capable servo 12, a friction plate 72, a drum to ped member 223, and a hub unit 224 is configured on the outer circumference side of the hub unit 233 of this brake B3. The drum #shaped member 223 of this clutch C2 is connected to one side plate of the carrier CR1, and the other side plate of the carrier CR1 is connected to the input shaft 2. Also, the ring gear R1 is connected to the transmitting member 230, and is

connected to the sun gear S3 via transmitting member 230.

Now the oil chamber of the oil pressure servo 12 is linked to the oil line 91 of the boss unit 3a provided on the input shaft 2 in a sleeve form, via an oil hole (not illustrated) formed in the hub unit 233, and this oil line 91 is linked to the oil pressure control device, not had rapic.

illustrated. This oil pressure servo 11 comprises one set of seal rings 80 that seal between the boss unit 3a of the case 3 and the hub unit 233, and one set of seal rings 86 that seal between the hub unit 233 and the drumphoped member 223. In other words, uses two sets of seal rings and constructs an oil line from the oil pressure control device not illustrated to the oil chamber of the oil pressure servo 12.

The operations of the automatic transmission device 122 / Twenty - second embodiment differ from that of the twentieth embodiment based on the above mentioned construction are as follows:

gear S1 have switched positions, in other words, the sun gear S1 is fixed by the brake B3, and the rotation of the input shaft 2 is input to the carrier CR1, but the other components are the same as those of the twentieth embodiment (see Fig. 37 and Fig. 38), and according description will be omitted.

As described above, according to the automatic

transmission device 122 relating to the present invention, second due to the planetary gear PR and the clutch C2 being bested configured on one side in the axial direction of the located planetary gear unit PU, and the clutch C3 being configured axially apposite on the other side in the axial direction of the planetary Units gear unit PU, the planetary gear PR and the planetary gear located more -unit PU can be configured closely together, as compared with In ambadiment the case wherein for example two clutches C2 and C3 are located configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 230 for mode transmitting reduced rotation can be relatively shorted. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia (force of inertia) can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced.

Further, since the counter gear 5 is configured in the exial direction between the planetary gear unit PU and the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear direction when the imput side from the drive source is the front direction) can be prevented because the counter gear 5

is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of and FF vehicle,

the interference toward the front wheels is reduced, and the

mountability on a vehicle can be improved, such as the

steering angle being greatly increased, for example

Further, since the reduced rotation output to the first planetary gear unit PU from the planetary gear PR is made to be engaged and disengaged by the brake B3, the number of parts (for example drum-shaped members and so forth) can be reduced as compared to the case wherein, for example, a clutch C1 is provided. Further, the brake B3 can configure an oil line directly from the case 3, and therefore the configuration of the oil line can be simplified as compared to the case wherein, for example, a clutch C1 is provided.

Further, the automatic transmission device 122 according to the present embodiment is a transmission device that is directly coupled at fifth speed forward. Therefore, at in first speed forward and fourth speed forward, the gear ratio belief and first speed forward and fourth speed forward, the gear ratio can be specified in a detailed manner, and particularly when

running at a high speed, the engine can be utilized with efficiently better revolutions, and this contributes to increased fuel economy of the vehicle while running at a low to medium speed.

Now, in the event that a clutch is configured in

units

for example, the length of the linking member (particularly units)
the transmitting member; that links the planetary gear PR
and the planetary gear unit PU becomes longer in the axially
direction, and since this linking member is for transmitting
the reduced rotation, the thickness of the member must be
increased so as to withstand this, and therefore the weight
also increases. Therefore, an object of the present
invention is to provide an automatic transmission that can
shorten the distance between the speed reduction planetary
unit for a linking member increase in
weight.

In this twenty-second with the present embodiment, in particular, the clutch

of the planetary gear unit PU from the planetary gear VAIIS

PR and the planetary gear unit PU is not necessary, and the length of the linking member, particularly the transmitting member 230 can be made that much shorter. Therefore, and increase in weight of the automatic transmission as a whole avoided can be prevented.

ZTwenty-third Embodiment

Below, the twenty-third embodiment, which is a partial modification of the eighteenth embodiment will be described, with reference to Fig. 41. Fig. 41 is a schematic cross-

device of an automatic transmission relating to the twenty-third embodiment. Now, Components of the twenty-third embodiment which are the same as those of the twenty-third embodiment which are the same as those of the twenty-third embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 41 illustrates, the automatic transmission cdevice 123 of the automatic transmission relating to the differs from the eighteenth embodiment twenty-third embodiment is a modification of second in the configuration of the clutch C1 and the planetary gear PR, (in More specifically, second unit other words, the planetary gear PR and the clutch C1 are located on one side configured to the right side of the diagram of the planetary loca Ted gear unit PU, and the counter gear 5 is configured in between this planetary gear PR and the planetary gear unit The TowerTy-Third embadiment also differs in the The locations of PUE, and further, the clutch C2 and the brake B2 change units are switched as places with the clutch C3, compared to that of the automatic transmission device 118 of the automatic transmission of the eighteenth embodiment (see Fig. 30).

Within the automatic transmission device 123, on the inner circumference side of the input shaft 2 is configured a hydraul; C a multi-disc clutch C3 comprising an oil pressure servo 13, clutch

Application plate 73, a drum shaped member 225 that forms a clutch drum, a hub unit 226 connecting to a sun gear S2, and located on the outer circumference side, is comprised a multi-disc

clutch & comprising an oil pressure servo 11, A friction clutch
plate 71, a drum to happed member 221 that forms a clutch drum,
and a hub unit 224.

Now, the oil chamber of the oil pressure servo 13 is connected to the oil line 2a formed on the above mentioned input shaft 2, and this oil line 2a is extended from one -edge of the case 3, and is -linked to the oil line 91 of the boss unit 3a, provided on the input shaft 2 in a sleeve form, , in Turns connected this oil line 91 is linked to the oil pressure control 77,05 device not illustrated. hydraulic mounted pressure servo 13 is configured on the input shaft 2, simply providing one set of seal rings 81 that seal between the boss unit 3a of the case 3 and the input shaft 2 configures an oil line from the oil pressure control device SETVES TO CORNER! not illustrated to the oil chamber of the oil pressure servo 13.

Further, the oil chamber of the above mentioned oil connected

pressure servo 11 is linked to the oil line 92 of the above mentioned boss unit 3a, and this oil line 92 is linked to the oil pressure control device not illustrated. In other this, for the hydraulic words, regarding the above mentioned oil pressure servo 11, simply providing one set of seal rings 80 that seal between the boss unit 3a of the case 3 and the drum shaped member 221 configures an oil line from the oil pressure controller is connected device, not illustrated, to the oil chamber of the cil

_pressure servo 11.

The above mentioned input shaft 2 is connected to the didd drum shaped member 225 of the clutch C3, and the front edge of the inner directed side of this drum / shaped member 225 is configured splined with the friction plate 73 that is _made_capable of engaging with the oil pressure servo 13 for the clutch C2 The inner circumference side of this are intermeshed with Spiction plates friction plate 73 is splined to the hub unit 226, and this mentioned input shaft 2 is connected hub unit 226 is connected to the sun gear S2. the above mentioned drum shaped member 221, so as to be The and on the inner circumfere -capable of rotating, splined To this adrumt shaped member 221 is sometigured the friction plates 71 of the clutch C1 which is capable of engaging by the oil pressure servo 11 for the clutch C4, splined, and the circumference side of the friction plate 71 of this clutch with friction plates and to the hub unit 222 that is This King gear R1 is rotatably connected to the ring gear R1. supported by the boss unit 3a so as to be capable of rotating, via this hub unit 222. Further, The sun gear S1 is connected to the above mentioned input shaft 2, and the carrier CR1 is fixed vand supported by the boss wanter 3a via the side plate. drum/shaped Also, the above-men to the sun gear \$3 via member 221 is connected the transmitting member 230, and this transmitting member 230 is connected to the above

mentioned sun gear 93.

on the other hand, on the boss unit 3b of the case 3 is in the form of a sleave fitted one end of that is provided on the input shaft 2 in a sleeve form, and is extended from the other side opposite from the above which supports

mentioned boss unit 3a, is comprised a multi-disc clutch C1

a hydraulic

comprising an ail noon comprising an dil pressure servo 12, of friction plate 72, a clutch drum, shaped number 223 that forms a clutch drum; and a hub unit 224. The oil chamber of this oil press connected nked to the oil line 93 of the boss unit 3b, and this oil connected line 93 is rinked to the oil pressure control device not illustrated. In other words, the above-mentioned oil bydaulic connected to pressure servo 12 is constructing an oil line from the oil pressure controledevice not illustrated to the oil pressure -servo 12 by one set of seal rings 84 that seal between the boss that 3b of the case 3 and the drum to hape of the front edge of the inner circumference -side of the drum shaped member 223 of this cluter 12, is splined a friction plates 72 capable of engaging by the oil pressure servo 12 of the elutch C2, and this friction plate the front edge of the outer circumference radially outward _side of the hub unit 224. Further, on the outer -circumference side of the clutch C2 is configured a multidisc brake comprising an oil pressure servo 15 and friction plate 75, and of the outer circumference side of this hub unit 224 is splined a friction plate 75 that can be

operation of

retained by the oil pressure servo 15 for the brake B2, and falso, this hub unit 224 is connected to the sun gear S2.

the planetary gear unit PU is configured a multi-disc brake B1 comprising an off pressure servo 14, a friction plate 74, and a hub unit 228. The side plate of the carrier CR2 of the above mentioned planetary gear unit PU is connected to the hub unit 228 that is splined with the friction plate of the above-mentioned brake B1, and further, the hub unit 228 is connected to the inner race of the one-way clutch F1. The sun gear S3 is meshed with the short pinion PS of this carrier CR2. Then, the long pinion PL of this carrier CR2 meshes with the above mentioned sun gear S2 and the ring gear R2, and to one edge of this ring gear R2 is connected the linking member 227, and this ring gear R2 is linked to the counter gear 5 via this rinking member 227.

The operations of the automatic transmission device 123, of this Twenty-third embodiment based on the above mentioned construction, are similar to that of the eighteenth embodiment (see Fig. 31 and Fig. 32), thereas we repeated here and according description will be omitted.

As described above, according to the automatic

of This embodimen!

transmission device 123 relating to the present invention,

second

unit

due to the planetary gear PR and the clutch C3 being

located

planetary gear unit PU, and the clutch C2 being configured

WOPPOSI ction of the planetary side in the axial/di units gear unit PU, the planetary gear PR and the planetary gear located more unit PU can be configured closely together, vcompared to the case wherein for example, two clutches C2 and C3 are located configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 230 for transmitting reduced rotation can be relatively shortened. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared to the case wherein three clutches C1, C2, C3 are located -configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 91, 92, 93) that supply the oil pressure servos 11, 12, and 13 of these clutches C1, C2, C3 more can be constructed easily, and the manufacturing process can can be reduced be simplified and the costs brought down.

Further, since the six pressure servo 13 is provided on serves to comment the input shaft 2, one set of seal rings 81 seal the case 3 the supply oil to the oil lines 2a provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servo 13 without providing the seal rings between, for example, the input shaft 2 and the oil hydraulic pressure servo 12. Further, the oil pressure servos 11 and

12 can supply oil from the boss writs 3a, 3b extended from components of the case 3, without passing through other parts for example, and therefore can supply oil by providing one set of seal rings 80, 84. Therefore, oil can be supplied simply by providing one set of seal rings 81, 80, 84 each foil the oil hydraulic pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, because the clutch C3 is configured on the

which must transmit a relatively large torque in order to speed transmit the reduced rotation, can be configured on the outer circumference side, and this clutch C1 and the oil pressure servo 11 thereof can have an increased diameter.

Thus Particularly, the pressure area of the oil chamber of the hydraulic oil pressure servo 11 can be enlarged, and the capacity capable of torque transmission of this clutch C1 can be increased. By configuring the clutch C3 which can have a smaller capacity for torque transmission compared to the

Further, because clutch C2 is a clutch that ongages while at first speed reverse, when this clutch 2 is engaged first speed reverse, the transmitting member 230 rotates in the opposite direction while the hub unit 224 that

clutch C1, the automatic transmission can be made more

compact.

connects this clutch C2 and the sun gear S2 rotate at the direction same rotation as the input shaft 2 by engaging lead to eases wherein of the transmitting member 230 and the hub unit 224 becomes great, but har but because this clutch C2 is located on the epposite side of the planetary gear PR, via the planetary gear unit the transmitting member 230 and the hub hunt 224 can be spaced **configured** apart from one another. Compared to the case components wherein, for example, those parts come in contact due multiple axis construction, the decrease# efficiency of the automatic transmission caused by the friction produced by, These components the relative rotation between those parts can be pro-

Further, because the counter gear 5 is configured in localed ection between the planetary gear unit PU and the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the enlargement of For example, when the automatic automatic transmission. Toward the rear of transmission is mounted on the vehicle enlarging towards one direction of the axis (particularly in the rear when the input side $\frac{\xi_{scin}\delta}{\epsilon_{ron}}$ the drive source is the is not necessary front direction) can be prevented because the counter gear 5 adiacen/ is mounted to match the drive wheel transmission device. Because of this, particularly in the case of af FF vehicle, the interference toward the front wheels is reduced, and the mountability on a vehicle can be improved such as the

the steering angle being greatly increased, for example.

Further, the automatic transmission device 123 according to the present embodiment is a transmission device that is directly coupled at fifth speed forward. Therefore, at first speed forward and fourth speed forward, the gear ratio determined for greater efficient, and particularly when can be specified in a detailed manner, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine can be utilized with efficiently better revolutions, and this contributes to increased fuel can be increased when economy of the vehicle while running at a low to medium speed.

tin particular the transmitting Now, the linking member member for linking the planetary gear PR and the planetary - qear unit PU requires rigidity to withstand the reduced speed torque that is input. For example, in the case of configuring a clutch that engages at a slow to medium speed a clutch that engages and disengages reduced rotation radially inward circumference side of the linking member the therefore a clutches must have a large capacity, appropriate diameter to correspond with this capacity Therefore, in the event that the linking radially outward member is the type that passes on Such 2 clutch, veven & larger diameter than the -necessary diameter measuremen necessary, and the diameter measurement of the linking

must be SurTher the diameter or member is enlarged many than necessary, and the automatic transmission as a whole becomes greater in the direction of Therefore an object of the present embodiment the diameter. is to reduce the enlargement of the diameter measurement, and V_{provide} a V_{compact} automatic transmission.

According to the present embodiment, all clutches can designed to avoid be configured without enlarging the diameter measurement of the linking member, by configuring a clutch C3 with a small and to be located inking member, particularly on the inner -side of the transmitting member 230.

ZTwenty-fourth Embodiment

Below, the twenty-fourth embodimenty which is a partial modification of the twenty-third embodiment $^{\vee}$ will be described with reference to Fig. 42. schematic cross-sectional diagram illustrati transmission device of an automatic transmission relating to the forty second embodiments. Now Components of the twentyfourth embodiment which are the same as those of the twentythird embodiment will be denoted with the same reference will not be repeated here numerals, and description thereof omitted, except for partial modifications

As Fig. 42 illustrates, the automatic transmission device 124 of the automatic transmission relating twenty-third embodiment is as modification of the configuration of the clutch C1, vcompared to that of the

automatic transmission when it is a specific 1_{23} of the dynamics of the eighteenth embodiment (see Fig. 41).

Within the automatic transmission devices 124, the clutch 162 Ted 5. de of the second unit C1 is configured on the planetary gear PR portents opposite (right side on the diagram) whom the planetary gear unit PU.

The front edge of the inner circumference side of the drum which shaped member 221, of this clutch of is connected to the input shaft 2, On the front edge of the inner circumference side of the drum-shaped member 221 of this clutch C1 is splined with friction plate 71 pand thereinner circumference side of this friction plate 71 pand thereinner circumference side of this friction plate 71 is splined with the hub unit 222. The hub unit 222 is connected to the sun gear S1 of the planetary gear PR.

planetary gear PR is fixed and supported by the case 3.

planetary gear PR is fixed and supported by the case 3.

Sun gear 53 by the Also, the ring gear R1 is connected to the transmitting member 230 and this transmitting member 230 is connected to the sun gear 53. Now, the clutch C3 comprising an oil pressure servo 13, A friction plate 73, a drum planed member 225, and a hub unit 226 is configured on the inner facility inward circumference side of the above mentioned transmitting member 230, that is to say, May enclosed within that transmitting member 230.

The operations of the automatic transmission $\frac{\text{device}}{\text{device}}$ 1_{24} , based on the above mentioned construction are the same as

that of the nineteenth embodiment (see Fig. 34 and Fig. 35),

Therefore not repeated here,

and according description will be emitted.

As described above, according to the automatic transmission device 1₂₄ relating to the present invention, second unit because the planetary gear PR and the clutch C3 is configured on one side in the axial direction of the firs located planetary gear unit PU, and the clutch C2 is configured on (2xially opposite) the axial direction of the planetary gear the other side in Uni, 18 unit PU, the planetary gear VPR and the planetary gear unit PU can be configured closely together, compared to the case located wherein for example two clutches C2 and C3 are configured in between the planetary gear vPR and planetary gear unit PU, and the transmitting member 230 for transmitting reduced speed rotation can be relatively shortered. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia (force) inertial can be reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced. Further, compared, to the case wherein three clutches C1, C2, C3 are configured on one side of the planetary gear unit PU, the oil lines (for example, 2a, 91, 92, 93) that supply the oil pressure servos 11, 12, and 13 of these clutches C1, C2, C3 can be more and the manufacturing process can be ean be reduced simplified and the costs brought down.

Further, because the off pressure servo 13 is provided on the input shaft 2, one set of seal rings 81 seal the case with 3 and supply oil to the oil lines 2a provided within input be supplicate the oil chamber of oil pressure servo 13 without providing the seal rings between, for example, the input shaft 2 and the hydraulic proseure servos 11 and hydraulic ssure servo 13. Further, the recaive of directly 12 can supply voil from the boss thits 3a, 3b extended from components the case 3, without passing through other parts can be connected and therefore can supply oil by providing one set of seal rings 80, 84. Therefore, oil can be supplied simply by providing one set of seal rings 81, 80, 84 each for the hydraulic pressure servos 11, 12, and 13, and sliding resistance from the seal rings can be minimized, and therefore the efficiency of the automatic transmission can be improved.

Further, since the clutch C2 is a clutch that engages

while at first speed reverse, when this clutch 2 is engaged

if first speed reverse, the transmitting member 230 rotates

in the opposite direction while the hub unit 224 that

connects this clutch C2 and the sun gear S2 rotates at the

same rotation as the input shaft 2 by engaging this clutch

Accordingly,

C2: The case may occur wherein the rotation difference of
the transmitting member 230 and the hub unit 224 becomes

speeds. However,
great, but because this clutch C2 is located on the opposite

side of the planetary gear PR, win the planetary gear unit PR

wherein, for example, those parts come in contact due to a multiple axis construction, the decreased efficiency of the automatic transmission caused by the friction produced by the relative rotation between those parts can be provented.

Further, because the counter gear 5 is configured in The axial direction between the planetary gear unit PU and the planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic transmission is mounted on the vehicle, enlarging towards one direction of the axis (particularly in the rear direction when the input side from the drive source is the front direction) can be prevented because the counter gear 5 is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of a FF vehicle, the interference toward the front wheels is reduced, and the mountability on a vehicle can be improved, such as the steering angle being greatly increased, for example.

Further, If the clutch C1 is placed between the ring gear R1 and the sun gear S3 for example, the reduced specific rotation must be engaged and disengaged, and becomes relatively large, but by placing between the input shaft 2 and the sun gear S1, the engaging and disengaging of the

rotation of the input shaft 2 from this clutch C1 causes the reduced rotation output from the ring gear R1 of the planetary gear PR to be engaged and disengaged, and the clutch C1 can be made more compact, and therefore the automatic transmission can be made more compact.

Further, the automatic transmission device 124 according to the present embodiment is a transmission device that is directly coupled at fifth speed forward. Therefore, at in first speed forward and fourth speed forward, the gear ratio more precisely set to improve efficiency and can be specified in a detailed manner, and particularly when mounted on a vehicle, in the event that the vehicle is aperated more efficiently running at a high speed, the engine can be utilized with better revolutions, and this contributes to increased fuel a low of the vehicle while running at a low to medium

Now, the linking member (in particular the transmitting the linking the planetary gear PR and the planetary gear unit PU requires rigidity to withstand the reduced speed torque that is input. For example, where case of

speed.

configuring a clutch that engages at a slow to medium speed and that is located or a clutch that engages and disengages reduced rotation from transmilling the inner concumposes side of the linking member where

appropriate diameter to correspond with this capacity
becomes necessary. Therefore, in the event that the linking

member is the type that passes on the outer circumforence side of this type of clutch, veven a larger diameter than the necessary diameter measurement of these clutches becomes necessary, which the diameter measurement of the linking member is enlarged more than necessary, and the automatic is increased. transmission as a whole becomes greater in the direction of the diameter. Therefore an object of the present embodiment is to reduce the enlargement of the diameter measurement, and provide a compact automatic transmission.

According to the present embodiment, all clutches can be configured without enlarging the diameter measurement of the linking member, by configuring a clutch C3 with a small capacity on the linking member, particularly on the inner circumference side of the transmitting member 230.

Mow, the twenty-fifth embodiment, which is a partial modification of the twenty-third embodiment will be described with reference to Fig. 43. Fig. 43 is a schematic cross-sectional diagram illustrating the automatic transmission device of an automatic transmission relating to the twenty-fifth embodiment. Now components of the twenty-fifth embodiment which are the same as those of the twenty-third embodiment will be denoted with the same reference numerals, and description thereof omitted, except for partial modifications.

As Fig. 43 illustrates, the automatic transmission

device 1₂₅ of the automatic transmission relating to the

twenty-third embodiment configures a brake B3 instead of the

clutch C3, and makes the carrier CR1 of the planetary gear paid

PR capable of being fixed by the brake B3, as compared to

that of the automatic transmission device 1₂₃ of the

automatic transmission of the twenty-third embodiment (see

Fig. 41).

this automatic transmission device 125, the brake B3 is configured on the opposite side (the right side of the second diagram) of the planetary gear unit be of the planetary gear unit This brake B3 comprises an otherwise servo 16, # friction plate 76, and a hub unit 233. The hub unit 233 of this brake B3 is connected to the carrier CR1, and this carrier CR1 is supported by the input shaft 2 so as to be capable of rotating. Further, the sun gear S1 is connected to the input shaft 2. Also, the ring gear R1 is connected to the transmitting member 230, and is connected to the sun gear S3 via this transmitting member 230. Now, the clutch c3, comprising an oil pressure servo 13, & friction plate 73, a drum shaped member 225, and a hub unit 226, is configured on the inner circumference side of the above mentioned transmitting member 230, that is to say, is enclosed within this transmitting member 230.

The operations of the automatic transmission $\frac{1}{25}$,

that of the twentieth embodiment (see Fig. 37 and Fig. 38),

There of not repetted here a

and according description will be emitted.

As described above, according to the automatic transmission device 125 relating to the present invention, since the planetary gear PR and the clutch C3 are configured on one side in the axial direction of the planetary gear unit PU, and the clutch C2 is configured on the other side the axial direction of the planetary gear unit PU, the planetary gear PR and the planetary gear unit PU can be located more configured closely together, compared to the case wherein for example two clutches C2 and C3 are configured in between the planetary gear PR and planetary gear unit PU, and the transmitting member 230 for transmitting Vreduced Vrotation can be relatively shortened. By doing so, the automatic transmission can be made more compact and more lightweight. Further, because the inertia force inertial reduced, the controllability of the automatic transmission can be increased, and the occurrence of speed change shock can be reduced.

Further, since the oil pressure servo 13 is provided on the input shaft 2, one set of seal rings 81 seal the case 3 and supply oil to the oil lines 2a provided within input shaft 2, and therefore oil can be supplied to the oil chamber of oil pressure servo 13 without providing the seal

rings between, for example, the input shaft 2 and the off

pressure servo 12. Further, the off pressure servo 12 can receive
supply oil from the boss unit 3b extended from the case 3,
without passing through other parts for example, and
therefore can supply oil by providing one set of seal rings

84. Therefore, oil can be supplied simply by providing one
set of seal rings 81, 84 each for the oil pressure servos 12,

13, and sliding resistance from the seal rings can be
minimized, and therefore the efficiency of the automatic
transmission can be improved.

while at first speed reverse, when this clutch C2 is engaged at first speed reverse, the transmitting member 230 rotates in the opposite direction while the hub unit 224 that connects this clutch C2 and the sun gear S2 rotates at the same rotation as the input shaft 2 by engaging this clutch C2, and a max may recur wherein the rotation difference of the transmitting member 230 and the hub unit 224 becomes great, but because this clutch C2 is located on the engaged side of the planetary gear at the planetary gear unit provided apart from one another. Compared to the case wherein, for example, the parts come in contact due to a multiple axis construction, the decreased efficiency of the automatic transmission caused by the friction produced by

Further, since the clutch C2 is a clutch that

the relative rotation between those parts can be prevented.

| located axially intermediate
| Further, since the counter gear 5 is configured in the

planetary gear PR, the counter gear 5 can be configured in approximately the center in the axial direction of the automatic transmission. For example, when the automatic fransmission is mounted on the vehicle, enlarging towards

direction of the axid (particularly in the rear direction) when the input side from the drive source is the front direction) can be prevented because the counter gear 5 is mounted to match the drive wheel transmission device.

Because of this, particularly in the case of aff FF vehicle, with the interference toward the front wheels is reduced, and the mountability on a vehicle can be improved, such as the steering angle being greatly increased, for example.

planetary gear unit PU from the planetary gear PR is made to

be engaged and disengaged by the brake B3, the number of

parts (for example drum-shaped members and so forth) can be

reduced as compared to the case wherein, for example, a

clutch C1 is provided. Further, the brake B3 can configure

connected in

an oil line directly from the case 3, and therefore the

configuration of the oil line can be simplified as compared

to the case wherein, for example, a clutch C1 is provided.

Further, the automatic transmission device 1_{25} according

to the present embodiment is a transmission device that is directly coupled at fifth speed forward. Therefore, at first speed forward and fourth speed forward, the gear ratio better set for efficient and manner, and particularly when mounted on a vehicle, in the event that the vehicle is running at a high speed, the engine can be utilized with efficiently better revolutions, and this contributes to increased fuel economy of the vehicle while running at a low to medium speed.

In this embodiment also, member (in particular the transmitting member for linking the planetary gear PR and the planetary -gear unit PU requires rigidity to withstand the reduced For example, in the case of speed torque that is input. _configuring a clutch that engages at a slow to medium speed and speed and disengages reduced rotation on the inner circumference side of the linking member, the redially clutch must have a large capacity, therefore and large provide the required to roue transmitting appropriate diameter to correspond with this capacity. becomes necessary. Therefore, in the event that the linking radially outward outer circumference member is the type that passes on the outer side of this type of clutch, even a larger diameter than the necessary diameter measurement of these clutches becomes necessary, and the diameter measurement of the linking must be further member as enlarged more than necessary, and the automatic MUST have 2 transmission as a whole becomes greater in the direction of

Therefore an object of the present embodiment May diameter. is to reduce the enlargement of the diameter measurement, more and provide a compact automatic transmission.

In this twenty-sistk According to the present embodiment, all clutches can accommodated without be configured without enlarging the diameter measurement of beczuse the linking member, by configuring a clutch C3 with a small capacity on the linking member, particularly on the inner

circumference-side of the transmitting member 230.

Now, the above first through twenty-fifth embodiments relating to the present invention were described as being applicable to supplying a torque converter an automatic Transmission transmission, but should not be limited to this, and any motion-starting device may be used that would transmit the

torque (rotation) at start of movement. Further, while the bree embodiments have been described as wherein this is mounted on a vehicle with an engine as a the invention is but should not be limited

drive source has been described,

to this, and any drive source may be used as a matter of the present invention may be applied to course, and this may be mounted on a hybrid vehicle. described Further, the above mentioned automatic transmission is favorable for use in a FF vehicle, but should not be limited to this, and can be used in a FR vehicle, a four-wheel drive vehicle, or vehicles with other types of drive systems.

Further, the above first through twenty-fifth embodiments have been described using a double pinion planetary gear fox the planetary gear PR used as a reduced

again the invention is rotation output means, but should not be limited to this, and a single pinion planetary gear may also be used.

Further, the above first through twentieth embodiments and the twenty-third through twenty-fifth embodiments were described as input ting the rotation of the input shaft 2 into the sun gear S1 of this planetary gear PR, and by fixing the rotation of the carrier CR1, whereby the ring gear R1 rotates at reduced rotations, Mowever, the rotation of the sun gear S1 may be fixed, with the rotation of the input shaft 2 input to the carrier CR such that the ring gear R1 rotates at reduced rotations.

Further, the first embodiment and the second embodiment have been described with the input side and the output side of the automatic transmission interchanged but should not be limited to this, and arrangements may be made wherein the input side and the output side are interchanged in an automatic transmission according to the other embodiments as-MOTH

Industrial Applicability

As described above, the automatic transmission according to the present invention is beneficial mounted on vehicles such as automobiles, trucks, busses, and so forth, and is particularly suitable for use with vehicles which require reduction in size and reduction in weight from

in shock of changing speeds.

ABSTRACT

A planetary gear PR and a clutch C3 for outputting special. reduced rotation and a clutch C1 for connecting and disconnecting the rotation of the input shaft 2 input to the sun gear S2 are configured on one side in of the planetary gear unit PU in the axial direction, and a clutch C2 for inputos connecting and disconnecting the rotation of the input shaft located axially apposite (left side of the diagram) of the planetary gear unit PU in the axial direction. By doing so, as compared to a case wherein, for example, a clutch C1 and clutch C2 are both located a pair of units configured together between the planetary gear VPR and the planetary gear unit PU, the planetary gear PR and the located more closely -planetary gear unit PU can be configured close together, and the transmitting member 30 that transmits the reduced speed from the planetery gear unit PR to the planetery gear on T (U can be)
rotations de made shorter. Further, compared to the case, wherein, for example, the clutches C1, C2, C3 are configured on one side is the axial direction, the construction of the 15 the planetory gear units oil line is simplified.